

EXHIBIT SIX

Aprél Phantom Design Requirements SSI/DRB-TP-D0L-031

ITRONIX CORPORATION

Spectrum Sciences Institute RF Dosimetry Research Board

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B

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Phantom Design Requirements SSI/DRB-TP-D01-031



PART of SAR Measurements Requirements SSI/DRB-TP-D01-030

DRAFT

Prepared jointly with:

APREL

Near Field Measurements Laboratory

March 1998

- NOTICE -

This draft was prepared to assist the Dosimetry Research Board of SPECTRUM SCIENCES INSTITUTE and specifically the Working Group on SAR Measurements. It is submitted as a basis for discussion only, and is not binding on APREL Inc. Subsequent study may lead to revisions of the document, both in numerical values and/or form, and after continuing study and analysis, APREL Inc. specifically reserves the right to add to, or amend the content of this contribution.

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1.0 INTRODUCTION

1.1 Purpose and Scope of the Standard

The purpose of this document is to standardize the phantom(s) required for Specific Absorption Rate (SAR) testing associated with SAR measuring systems. This document defines the parts and dimensions of the phantom, in accordance with industry standards and practices.

This Standard defines:

- the methodology and procedures used to define a reproducible representation of the human head, hand and arm
- the dimensions on the canonical shapes used, and the materials required
- the hardware required and the proper setup

This Standard is part of a Certification Program Methodology as described in a separate document entitled "SSI/DBR TP-D01-030, Specific Absorption Rate (SAR) Standard For Portable Telecommunications Devices, March 1998". SSI/DBR TP-D01-031 contains specific criteria that must be met for SAR certification.

1.2 Test Facilities

All calibration work as described in this Standard shall be performed at an ISO/IEC Guide 25 accredited laboratory.

1.3 Test Personnel

Personnel performing the calibration will be experienced in relevant measurements (e.g. physical properties or RF characteristics) and supervised by a person proficient in SAR measurements.

1.4 Standard Environmental Conditions

All measurements and calibration should be performed under normal laboratory conditions for physical properties and electrical characteristics as stipulated by ISO/IEC Guide 25. The nominal temperature for physical property measurements and for electrical characterization are 20°C and 23°C, respectively.

Comments and inquiries should be addressed to:

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Ref: Project U404-7-0016 -1997

2.0 BACKGROUND

Portable communication devices used by consumers typically operate over the range of several watts to a milliwatt, or less, using either analog or digital modulation techniques. Most portable telephones have antennas that radiate within a few centimeters of the user's head. The field strength and field distribution near the antenna are highly dependent on the location, orientation and electromagnetic characteristics of adjacent objects. The head and hand are normally in the reactive near-field region of the antenna where the electromagnetic field is non-propagating. The energy absorbed in the head and hand is mainly due to electric fields induced by the magnetic fields generated by currents flowing through the feedpoint, along the antenna and body of the portable device. The RF energy is scattered and attenuated as it propagates through the tissues of the head, and maximum energy absorption is expected in the more absorptive high water-content tissues near the surface of the head or hand. To account for near-field effects portable devices are evaluated with realistic head models called a phantom.

A phantom is a device that simulates the size, contours, and electrical characteristics of human tissue at normal body temperature. It is composed of a manikin (solid shell) and a tissue-equivalent synthetic material solution (see SSI/DRB-TP-D01-033).

The solid manikin shell is made of a dielectric material, which is transparent to RF energy (i.e. has very low RF absorption), and is as thin as possible while maintaining the strength necessary to hold the mass of simulated tissue.

Current phantoms in use are:

- Universal Head-arm (UniHead) Phantom for ear independent evaluation of the RF exposure in the head of users by telephone-type devices, as well as RF exposure in the head of users of hand held radios positioned in front of the face, and in the hand of users of hand held portable devices
- Flat Phantom for evaluating the RF exposure of other parts of the user body by wireless devices that are not normally used in the vicinity of the head and cannot be accommodated by the UniHead, as well as for experimental investigations. (Such devices would include wireless LAN PCMCIA cards installed in laptop personal computers)
- Insulated Flat Phantom used for the determination of the enhancement factor of synthetic tissue in the calibration of the miniature isotropic electric field (E-field) probes

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3.0 REFERENCES

- Considerations for Human Exposure to EMFs from Mobile Telecommunication Equipment (MTE) in the frequency range 30 MHz – 6GHz, 1997, CENELEC European Committee for Electrotechnical Standardization, Secretariat SC211/B, WGMTE.
- "Numerical and Experimental Near Field Evaluation of a DCS 1800 Mobile Phone", A.Bahr, R.Kastle, S.G.Pan, T.Schmid, T.Becks, and N.Kuster, 1997, part of: "Suggestions Prepared Following the CENELEC Document", N. Kuster et al, Attachment 9, Minutes IEEE Standards Coordinating Committee –34, Subcommittee – 2, May 2, 1997 meeting.
- "Electromagnetic Energy Exposure of Simulated Users of Portable Cellular Telephones", Q. Balzano, O. Garay, T.J. Manning, Jr, 1995, IEEE Transactions on Vehicular Technology, 44:390-403.
- "EM Absorption in the Human Head and Neck for Mobile Telephones at 835 and 1900MHz", O. Gandhi, G. Lazzi, and C. Furse, 1996, IEEE Transactions on Microwave Theory and Techniques, 44:1884-1897.
- "The Dependence of EM Energy Absorption Upon Human Head Modeling at 900 MHz.", V.Hombach, K.Meier, M.Burkhardt, E.Kuhn, and N.Kuster, 1996, IEEE Transactions on Microwave Theory and Techniques, 44:1865 – 1873.
- "Dosimetric Evaluation of Handheld Mobile Communications Equipment with Known Precision", N.Kuster, R.Kastle, and T.Schmid, 1997, IEICE Transactions, E80-A:1 – 8.
- "Soft and Dry Phantom Modeling Material Using Silicone Rubber with Carbon Fiber", Y. Nikawa, M. Chino, and K. Kikuchi, 1996, IEEE Transactions on Microwave Theory and Techniques, 44:1949 – 1953.
- Fields of a Portable Radio Handset Near the Human Head – Phase I, C.W. Trueman, S.J. Kubina, and M. Danesh, 1996, TN-EMC-96-01 Final Report, EMC Laboratory, Department of Electrical and Computer Engineering, Concordia University, Montreal, Quebec, Canada, 70–99.
- Provisional Head and Torso Simulator for Acoustic Measurements of Air Conduction Hearing Aids, International Electrotechnical Commission 60959 TR0 Ed. 1.0 (7 July 1989)

4.0 DEFINITIONS

manikin: an RF transparent shell for the phantom

phantom: a device that simulates the size, contours, and electrical characteristics of human tissue

5.0 PHANTOMS

5.1 Universal Head-Arm (UniHead) Phantom

IEC 60959 (TR0 Ed.1.0, 1989, Provisional Head and Torso Simulator for Acoustic Measurements of Air Conduction Hearing Aids) tabulates standard ergonomic data for the human head and torso. A manikin generated from these measurements represents the 95th percentile of the population.

5.1.1 Head Simulator

The principle dimensions of the head and torso simulator are shown in Figures 5.1 and 5.2 are listed in Table 5.1.

Table 5.1

A	HEAD BREADTH	152 mm
B	HEAD HEIGHT	141 mm
C	BITRAGION DIAMETER	110 mm
D	NECK DIAMETER	103 mm
E	SHOULDER BREADTH	440 mm
F	CHEST BREADTH	279 mm
G	HEAD LENGTH	199 mm
H	TRAGION TO WALL	97 mm
I	CHIN-VERTEX LENGTH	243 mm
J	TRAGION TO SHOULDER	165 mm
K	SHOULDER DEPTH	116 mm
L	CHEST DEPTH	225 mm
M	SHOULDER POSITION	125 mm

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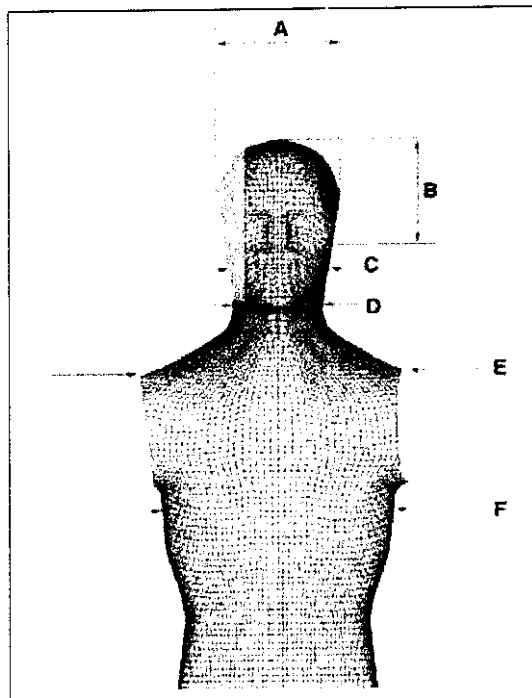


Figure 5.1

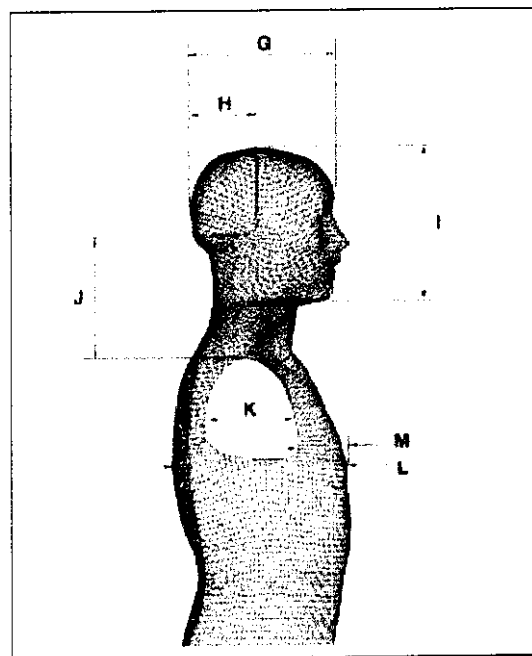


Figure 5.2

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An engineering approximation for a human head simulator can be made from this ergonomic data using basic canonical shapes. If we define one cylinder with the diameter of the head's breadth (A) and a second with the diameter of the chin's diameter (C) and join the two cylinder with a plane tangent to both cylinders and with a contact separation of $(I - (A+C)/2)$ we have the basic shape of the head simulator shown in Figure 5.3. This plane defines the "cheek" of the head simulator. The width of the head simulator can be defined by the length of the head (G).

The head simulator is therefore defined by two quarter cylinders, the plane joining these two sections, for an overall length of 243 mm, and limited to a width of 199 mm.

Figure 5.4 shows an alignment aid for positioning a portable communication device. This applique is defined by the positions of the ears and the eyes within the head. By recognizing that both ears are in the center of their respective sides of the head and that the tip of the pinna of the compressed ear coincides with the beginning of the roll-off of the skull cylinder section, we can define a symmetric, ear independent, reference point at (0,0). This is the tip of the composite pinna. Furthermore, the two shaded spots at (0,-7 cm) and (0,+7 cm) correspond to the positions of the humans eyes relative to the ears.

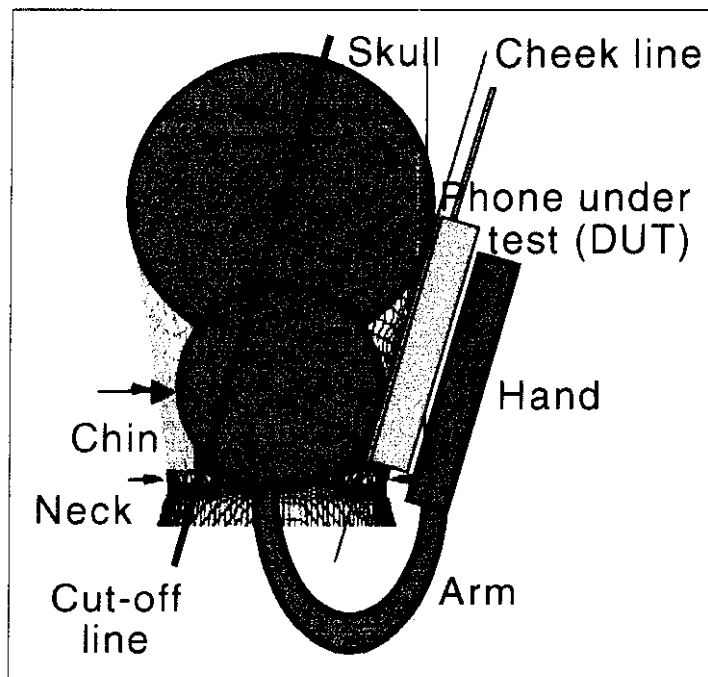


Figure 5.3

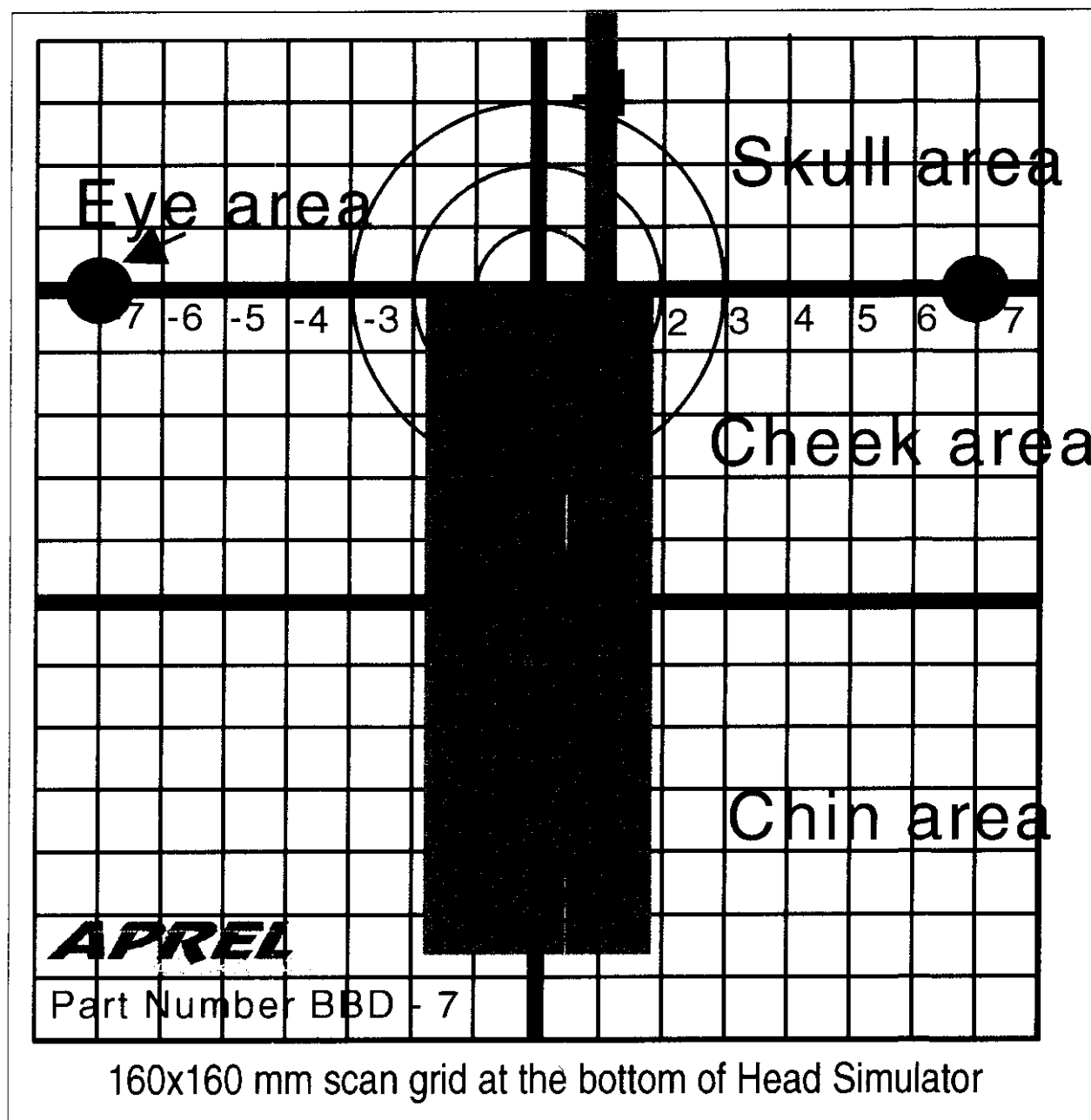


Figure 5.4

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5.1.2 Arm and Hand Simulator

The principal dimensions of the arm and hand are listed in Table 5.2. The hand is represented with a parallelepipedic volume having the dimensions 36x90x110mm. The hand simulator is attached to the head simulator by means of a flexible arm that is attached to a valved nipple. This can provide a continuous conducting link between the liquid in the head where the measurements are taking place and the hand where the handset is being held. Alternatively, with the valve shut, muscle simulating synthetic tissue can be placed in the hand and arm simulator, at the expense of the continuous conducting link.

Table 5.2

	SHOULDER –ELBOW LENGTH	365 mm
	FOREARM-HAND LENGTH	440 mm
	HAND THICKNESS	36 mm
	HAND LENGTH	200 mm
	HAND BREADTH AT THUMB	112 mm
	HAND BREADTH AT METACARPAL	90 mm

Figure 5.5 shows an alignment aid for positioning a portable communication device. This applique is symmetric with respect to the center of the hand simulator. The upper surface of the hand simulator is longer than the defined parallelepipedic volume in order for a dielectric alignment pin to be screwed in to act as a stop for positioning the phone on the hand. In addition, the upper surface is also wider to allow notches to be placed on either side to which an elastic restraint can be attached to hold the portable device in place.

5.1.3 Materials

The materials used for the fabrication of the Universal Head-arm (UH-a) are non-metallic. The support platform and base are constructed of laminated wood for easy cleaning (see Figure 5.6 and Table 5.3). The vertical guides are constructed of hard wood giving precision of vertical movement to the measuring gauge and the hand guide. The head- and hand-simulating volumes are made of Plexiglas. The head simulation has the top edge raised above the platform for easy wrapping and removal for storage when containing tissue-simulating liquid. This allows a substitution of phantoms representing different frequencies. Tissue-simulating liquid contained in the hand volume is connected to tissue simulating liquid contained in the head volume by a flexible arm that can be detached for cleaning and storage. The Plexiglas volume of head is formed and terminally stabilized to its exact characteristics. Plexiglas does not include additives for reinforcement. The manufacturing process for the Universal Head-arm allows precise duplication of

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geometrical and dielectric properties of the setup. Bonding with adhesives and solvents is used. Nylon screws are used to secure some elements. Clear gloss materials and appropriate grids allow verification of proper location and function of the phone under test.

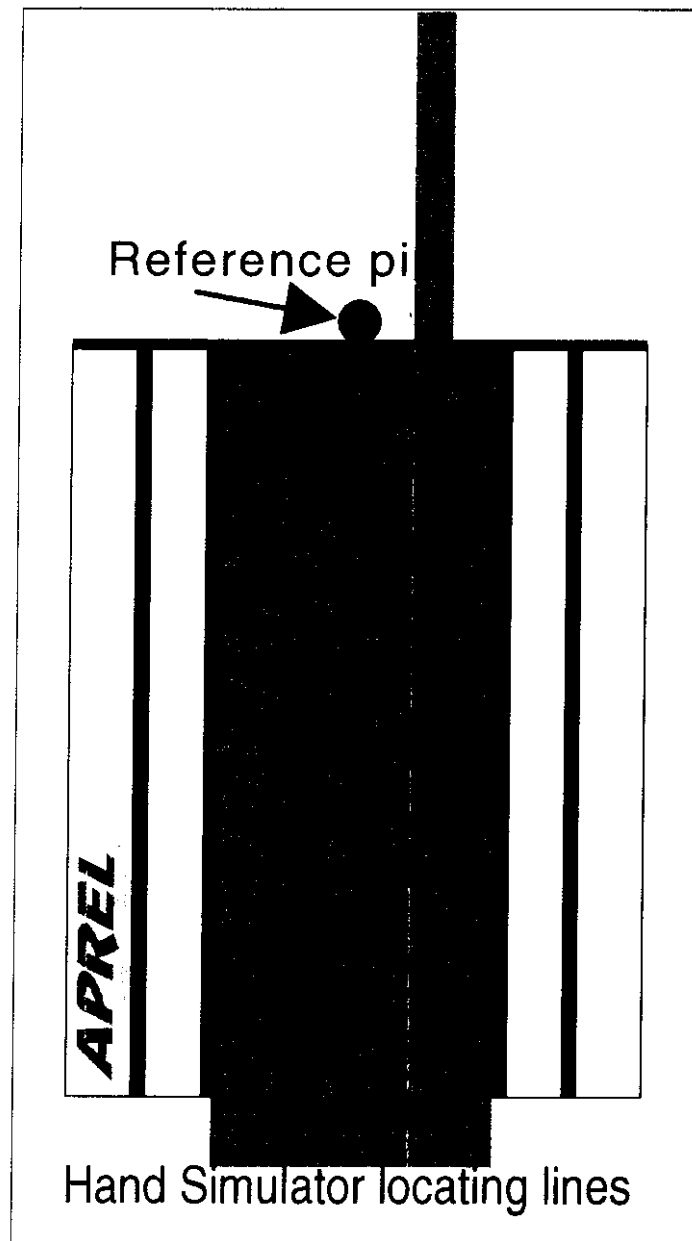


Figure 5.5

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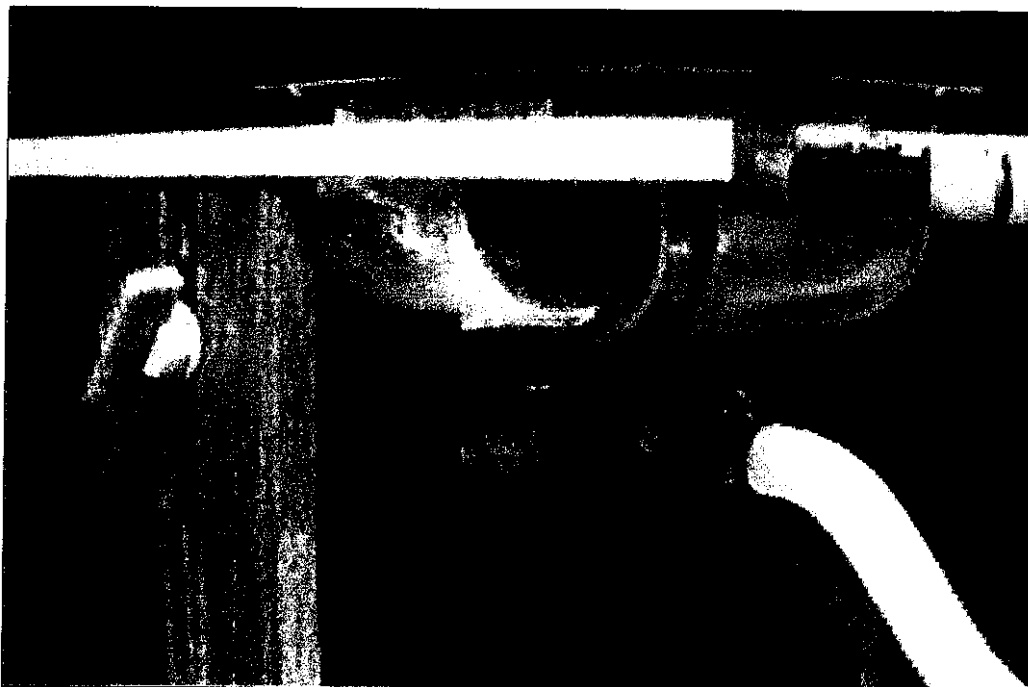


Figure 5.6

Table 5.3

Specifications	
Model	UH-1
Frequency	tissue dependant
Head cut-off section	190 mm x 240 mm
Hand surface	95 mm x 115 mm
Basic scan area	160 mm x 160 mm
Hand position	self-locking
Head-arm-hand connections	fast release type
Dimensions	
-height	410 mm
-length	580 mm
-width	500 mm
Weight	approx. 12 kg

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5.2 Flat Phantom

An acrylic flat phantom with a parallelepipedic volume of 47mm x 14mm x 7mm is used for evaluating the RF exposure of other parts of the user body by wireless devices that are not normally used in the vicinity of the head and cannot be accommodated by the UniHead. (Such devices would include wireless LAN PCMCIA cards installed in laptop personal computers). It can also be suitable for experiment where a larger flat surface is desired that is provided by the UniHead phantom.

Insulated Flat Phantom

A styrofoam flat phantom with a parallelepipedic volume of 32mm x 21mm x 18 mm is used for the determination of the enhancement factor of synthetic tissue in the calibration of the miniature isotropic electric field (E-field) probes.

6.0 SAR LABORATORY SETUP

The phantom is typically setup in relation to the other SAR measurement system equipment as shown in Figure 6.1. The major pieces of equipment for this setup are shown in the Table 6.1.

The articulated robot arm is usually located at one edge or corner of the laboratory space, situated in an RF anechoically damped area. The miniature isotropic E-field probe is attached to the end of the robot arm by means of a dielectric holder which serves the purpose of displacing the probe from the metal of the robot arm that could perturb the RF fields from the portable communication device under test. The phantom is placed in front of the robot arm, on the phantom support fixture, at a distance as far as possible from the robot, but close enough that the E-field probe can explore the entire interior region of the phantom. Again, this is to minimize the perturbations of the RF fields from the portable communication device under test in the vicinity of the robot arm.

The E-field probe is connected to a data acquisition card inside a computer by means of shielded cables. The computer controls the SAR measurement system by controlling the movement of the robot by communicating with its controller, and recording data from the data acquisition card.

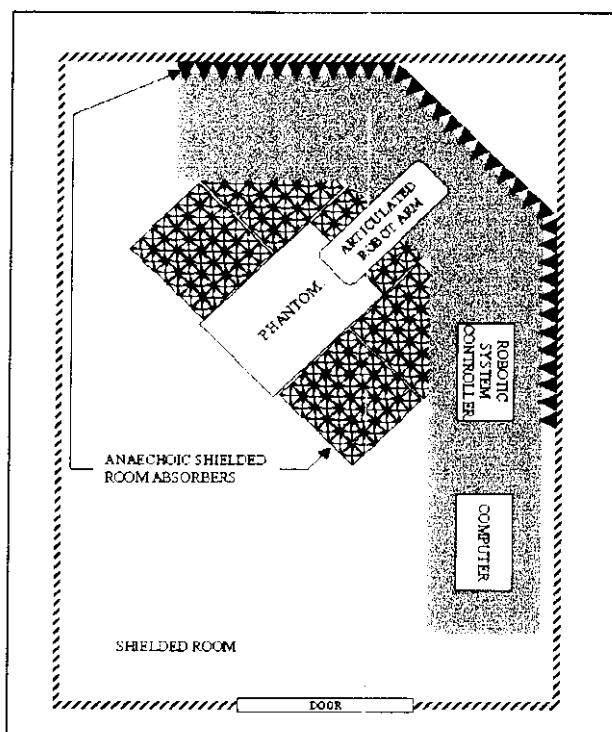


Figure 6.1

Table 6.1

Description	Manufacturer	Model
Articulated Robot Arm	CRS Robotics	A255
Robotic System Controller	CRS Robotics	C500
Phantom	APREL	various
Phantom support fixture	APREL	various
Synthetic Tissue Mixture	APREL	SSI/DRB-TP-D01-033
Miniature E-field probe	Narda	8021B
Probe support fixture	APREL	N/A
Computer	Northern Micro	Pentium 75
Software	Microsoft	Office 97 Pro
Software	APREL	SAR Measurement
Data acquisition card	ComputerBoards	CIO-DAS08-PGH
Miscellaneous Cables	N/A	N/A

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7.0 TEST CONFIGURATIONS USING THE UNI-HEAD

The Universal Head (Uni-Head) had been originally designed by APREL Laboratories for studies of antenna structures and for optimization of radiating characteristics of handsets. In addition of being a design tool, the Uni-Head may be used for most of measurements required in dosimetry. The figure 7.1 below illustrates some typical scenarios using the Uni-head for various devices under test (DUT).

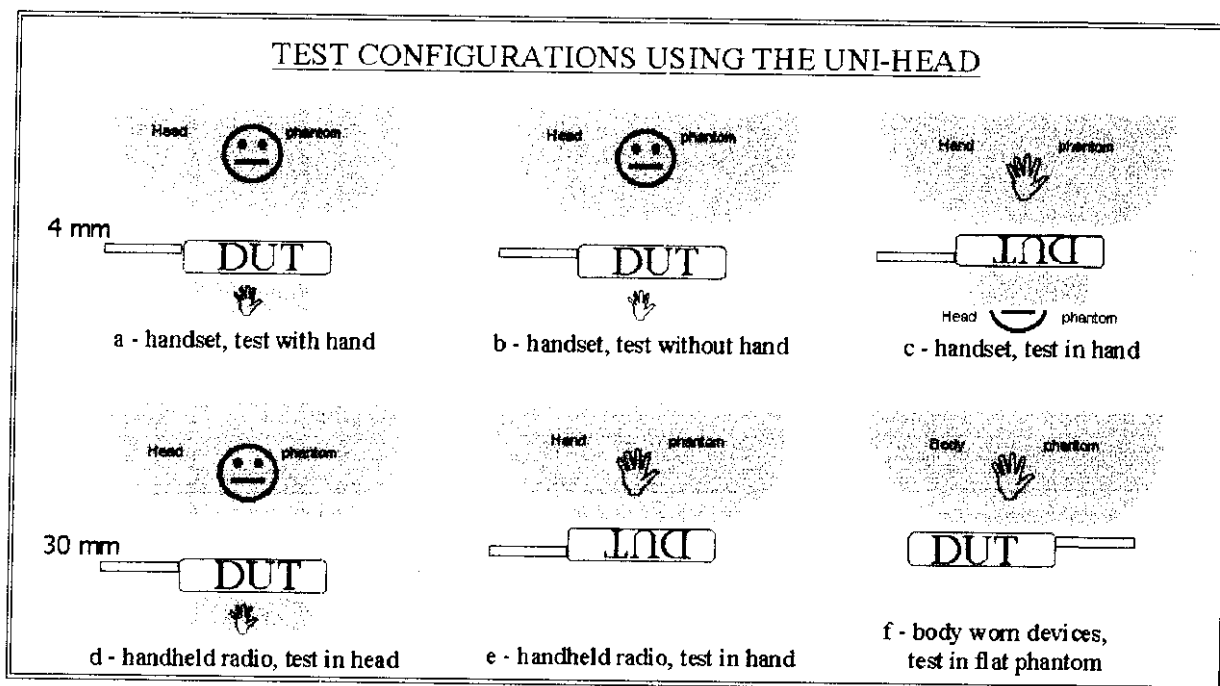


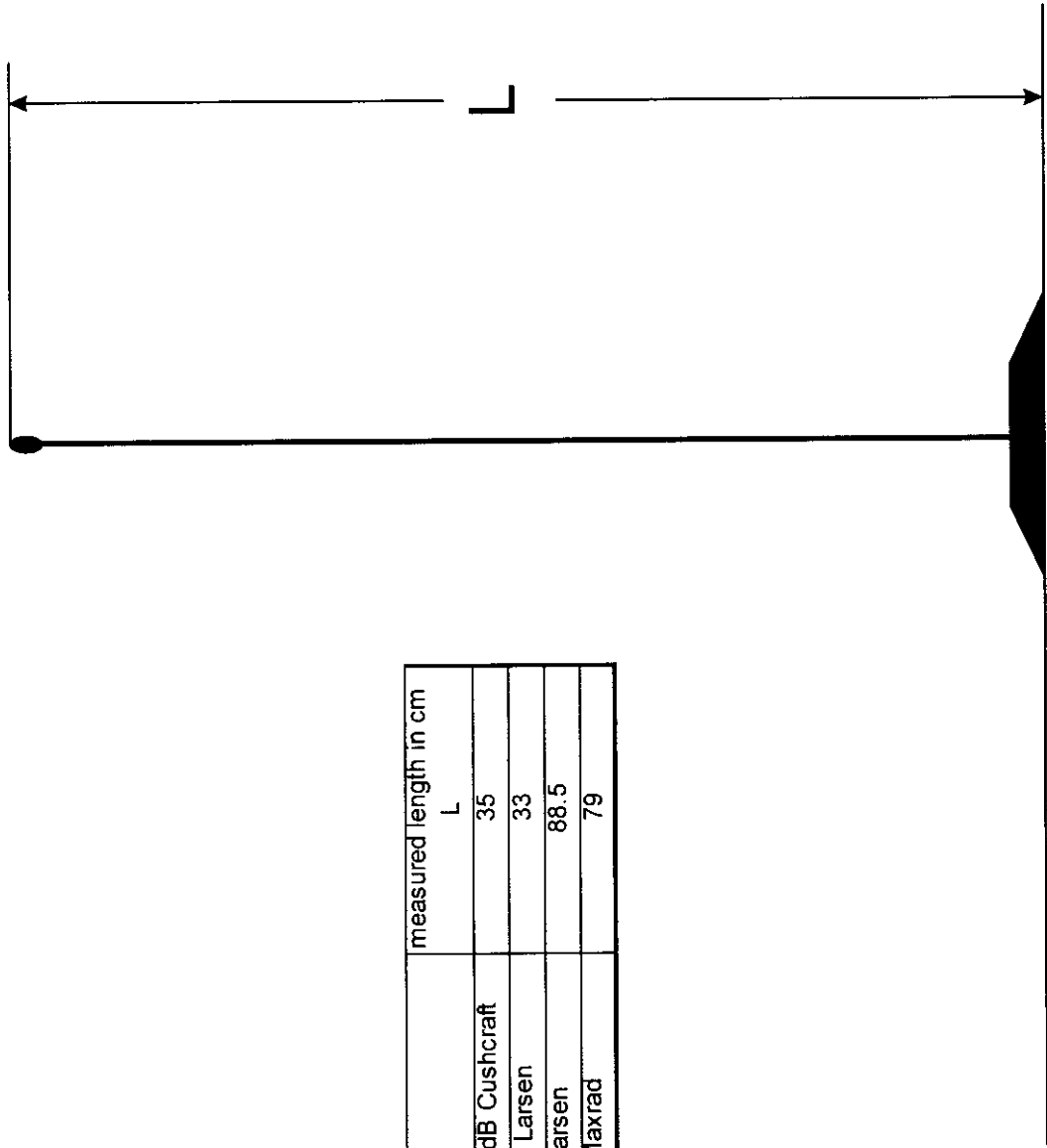
Figure 7.1 (not to scale)

Comments and inquiries should be addressed to:

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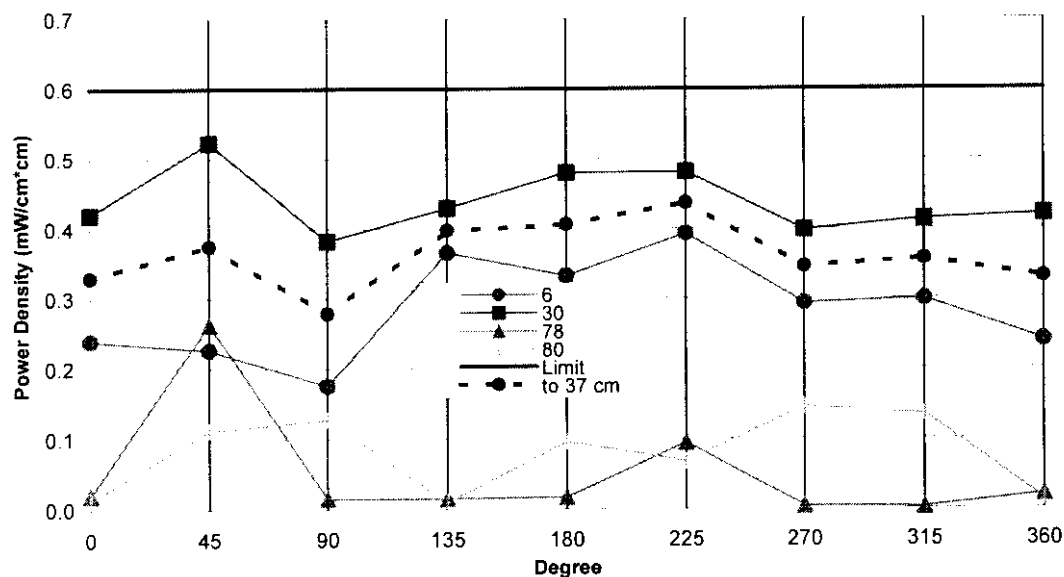
Antenna		measured length in cm L
3103	RIM/Itronix w/3 dB Cushcraft	35
3106	Itronix w/4.5 dB Larsen	33
3107	Itronix w/5 dB Larsen	88.5
3108	Itronix w/5 dB Maxrad	79



Power Density Measurement Result (mW/cm²) for Itronix Maxrad-3108
(Antenna height: 79 cm. Test Distance: 20 cm. Four Heights above Antenna Base)

Angular Position	Adjusted Total Power Density				Average Values up to 37 cm	MPE Limit
	H1 [cm]	H2 [cm]	H3 [cm]	H4 [cm]		
[°]	[mW/cm ²]	[mW/cm ²]	[mW/cm ²]	[mW/cm ²]	[mW/cm ²]	[mW/cm ²]
0	0.2404	0.4202	0.0205	0.0137	0.3303	0.6
45	0.2268	0.5231	0.2640	0.1125	0.3750	0.6
90	0.1754	0.3822	0.0154	0.1280	0.2788	0.6
135	0.3651	0.4296	0.0149	0.0095	0.3973	0.6
180	0.3323	0.4796	0.0173	0.0961	0.4059	0.6
225	0.3926	0.4809	0.0945	0.0683	0.4367	0.6
270	0.2928	0.3978	0.0041	0.1457	0.3453	0.6
315	0.2986	0.4133	0.0022	0.1357	0.3559	0.6
360	0.2404	0.4202	0.0205	0.0137	0.3303	0.6

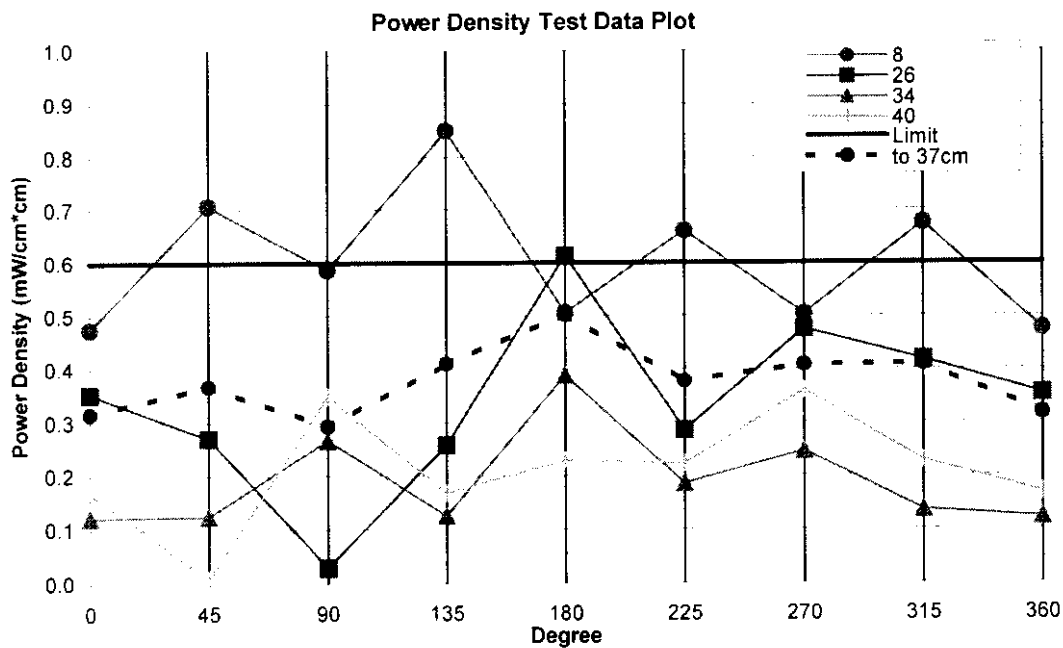
Power Density Test Data Plot



Power Density Measurement Result (mW/cm²) for Itronix-3106

(Antenna height: 33 cm. Test Distance: 20 cm. Four Heights above Antenna Base)

Angular Position	Adjusted Total Power Density				Average of Values up to 37cm	MPE Limit
	H1 [cm]	H2 [cm]	H3 [cm]	H4 [cm]		
	8	26	34	40		
[°]	[mW/cm ²]	[mW/cm ²]	[mW/cm ²]	[mW/cm ²]	[mW/cm ²]	[mW/cm ²]
0	0.4747	0.3531	0.1216	0.1686	0.3165	0.6
45	0.7064	0.2711	0.1246	0.0073	0.3674	0.6
90	0.5866	0.0286	0.2664	0.3486	0.2939	0.6
135	0.8492	0.2577	0.1252	0.1676	0.4107	0.6
180	0.5059	0.6131	0.3878	0.2285	0.5023	0.6
225	0.6602	0.2850	0.1852	0.2221	0.3768	0.6
270	0.5035	0.4747	0.2455	0.3598	0.4079	0.6
315	0.6738	0.4177	0.1362	0.2280	0.4093	0.6
360	0.4747	0.3531	0.1216	0.1686	0.3165	0.6



Antenna Lengths For Vehicle Mounted Antennas.		
Exhibit	Antenna	measured length in cm. (L)
Two	3 dB Cushcraft Model SN8962A *	35
	3 dB Cushcraft Model SX908LN	35.6
	3 dB Maxrad Model MUF-9103 (S)	35.6
	3 dB Larsen Model NM03E900BTNC	34.5
Three		
	5 dB Maxrad Model MUF-9105SP *	79
	5 dB Maxrad Model MUF-9025 NGP(S)	70
Four		
	4.5 dB Larsen Model NMO 900 *	33
Five		
	5dB Larsen Model EF5T900SNMO *	88.5
	5dB Maxrad Model MUF-9025(S)	63.5

* indicates antenna tested for FCC compliance

X-C 6250 Computer

RF Antenna Placement

FCC regulations require that radio operators comply with the following.

RF Modems

WARNING While the radio is operating, its antenna must be at least 5 cm from all persons in order to comply with the FCC RF exposure limit. Operators must ensure that while the radio is operating its antenna is at least 5cm from nearby persons in order to comply with the FCC RF exposure limit.

RF Modems and Vehicle Mounted Antennas

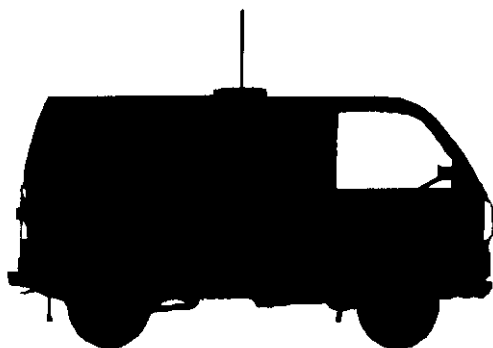
FCC regulations require that users of vehicle-mounted antennas must use only antennas authorized for use with the X-C 6250 computer in order to meet FCC RF exposure limits. Please contact Itronix for a list of approved vehicle-mounted antennas. For mounting installation and/or mounting instructions for these types of antennas, see the instructions that accompany each antenna.

WARNING Improper installation and/or operating configurations of permanent and magnetic vehicle mount antennas may cause FCC RF exposure limits to be exceeded. Vehicle mount antennas must be placed at least 20cm from operators and bystanders.

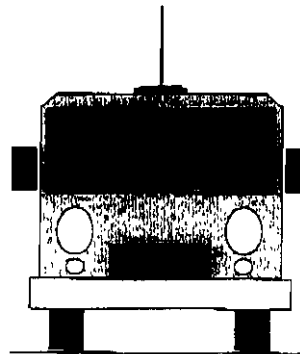
Placement of the vehicle mount antenna

1. Measure and identify an area 20 cm (8 inches) in from the edges of the vehicle roof.
2. Place the vehicle mount antenna within that area.

To maximize RF performance, position the antenna in the center of the vehicle roof.



Side View



Front View

EXHIBIT SEVEN

Aprél Probe Design and Calibration Requirements SSI/DRB-TP-D0L-032

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Comments and inquiries should be addressed to:

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Ref: Project U404-7-0016 -1997

1.0 INTRODUCTION

1.1 Purpose and Scope

The purpose of this document is to standardize the test procedures to be followed in calibrating miniature isotropic electric-field (E-Field) probes. This Standard includes the methodology and procedures to be followed in calibrating E-field probes to be used for Specific Absorption Rate (SAR) measurements, in accordance with industry standards and practices.

This Standard defines:

- the methodology and procedures to be followed in the laboratory calibration of the miniature isotropic E-field probes.
- the hardware and software required, the test procedures, and, where applicable, the required limits for calibration of the miniature isotropic E-field probes.

This Standard includes tests to determine the following parameters:

1. Sensor Sensitivity
2. Simulated Tissue Enhancement Factor

This Standard is part of a Certification Program Methodology as described in a separate document entitled "SSI/DBR TP-D01-030, Specific Absorption Rate (SAR) Standard For Portable Telecommunications Devices, March 1998". SSI/DBR TP-D01-032 contains specific criteria that must be met for SAR certification.

1.2 Test Facilities

All calibration work as described in this Standard shall be performed at an ISO/IEC Guide 25 accredited laboratory.

1.3 Test Personnel

Personnel performing the calibration will be experienced in relevant measurements (eg physical properties or RF characteristics) and supervised by a person proficient in SAR measurements.

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1.4 Test Equipment

The required test equipment, hardware and software, is identified in each individual procedure. Equipment may be substituted or updated from time to time. Should this occur, such change shall be noted in the test report. Equipment shall be calibrated to standards traceable to International Standards.

1.5 Standard Environmental Conditions

All measurements and calibration should be performed under normal laboratory conditions for physical properties and electrical characteristics as stipulated by ISO/IEC Guide 25. The nominal temperature for physical property measurements and for electrical characterization are 20°C and 23°C, respectively.

2.0 BACKGROUND

The miniature isotropic electric-field (E-field) probe (Fig. 2.1) is a three-channel device used to measure RF electric fields. The sensors are three mutually-orthogonal dipoles, each 2.5 mm, or less, in length. For each channel of the probe, the dipole and two high-impedance lines are deposited on a planar substrate. Located at the center of the dipole is a Schottky diode (shown in Fig. 2.1). The three substrates are assembled to form a beam. Along the substrate are three pairs of high impedance conductors that connect the dipoles to a single output connector. The probe is enclosed in a protective sleeve to avoid contact with the corrosive elements of the simulated tissue. The total length of the probe is approximately 25 cm. The probe does not perturb significantly the field being measured. It is isotropic so that no matter how the probe is positioned relative to the electric field, the sum of the outputs of the three channels always gives the same value. The probe is very fragile, can be damaged by mechanical shock, and should be safely stored when not in use.

In the case of the triangular probe, because of the geometry of the probe elements, if the probe axis is aligned perpendicular to the E-field, and the probe is rotated so that the output of Channel x is maximized, then Channel x's dipole will form a 35.3° angle with the E-field. The relationship between the sensitivity of each channel with the probe axis perpendicular to the electric field (e) to the sensitivity for the E-field tangential to the dipole (η) is then:

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$$\eta = e/\cos^2(35.3^\circ) = 1.50e$$

Free space calibration of E-field probes can be performed using a TEM cell with operating frequency at or below 1 GHz. Free space calibration of E-field probes can be performed in an open area test site (OATS) or in a RF shielded enclosure for operating frequency at or above 1 GHz.

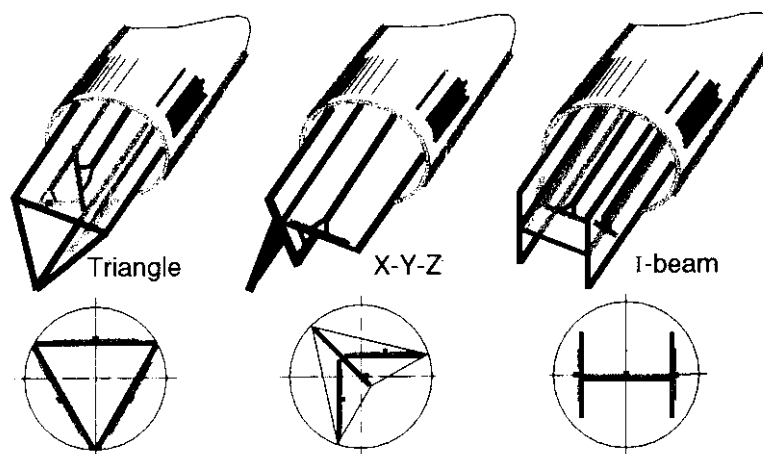


Figure 2.1

The following plots show the output of an E-field probe versus angular position for rotation in a vertical plane in a TEM cell.

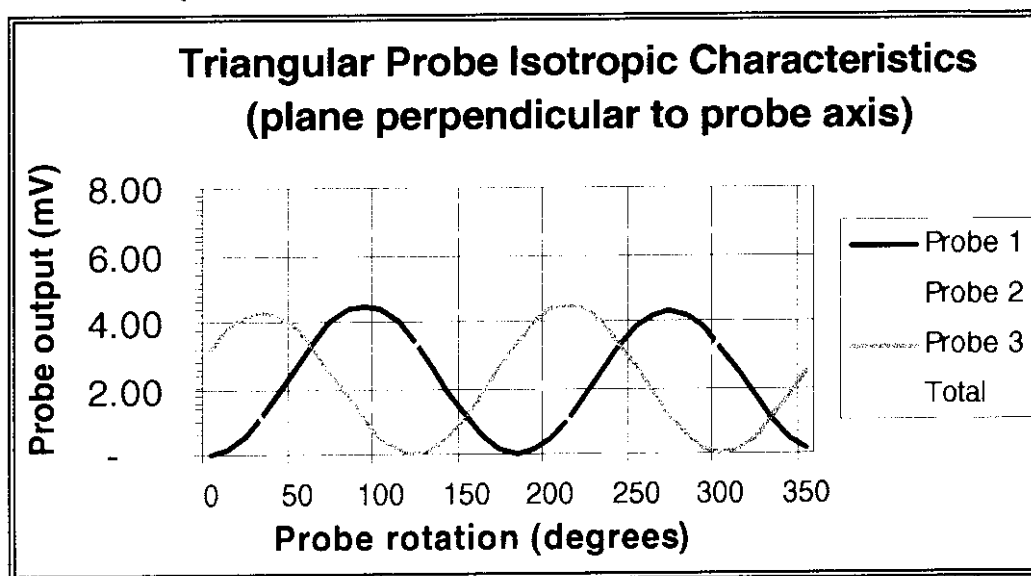


Figure 2.2

Comments and inquiries should be addressed to:

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3.0 ELECTRIC-FIELD PROBE MEASUREMENT SYSTEM CALIBRATION

This section describes the tasks necessary to characterize the electrical performance of the E-field probe. Note that two types of calibration are specified. Section 3.1 describes calibration below or at 1 GHz. Section 3.2 describes calibration at frequencies above 1 GHz.

The E-field probe measurement system has two main components: a) the probe, which is connected to the inputs of b) the data acquisition card that is installed in a computer. The probe is connected to the data acquisition card by means of shielded cables. The system is calibrated as one unit, not as individual components. If any component is modified or replaced, the system must be re-calibrated.

The system calibration is performed by determination of the free space E-field from the probe outputs in a test RF field.

3.1 Determining E-Field Probe Sensitivities at Frequencies up to 1 GHz

3.1.1 References

- SAR Measurement Operational Guide, O.M. Garay and Q. Balzano, 1995, Motorola, Florida Corporate Electromagnetics Research Laboratory, Fort Lauderdale, Florida.
- "Calibration of Low Frequency Electric and Magnetic Field Probes", W. Köhler, EMC '96, International Symposium on Electromagnetic Compatibility, Rome, Italy, September 1996
- "Calibration of Electromagnetic Field Probes in Different Measurement Sites: Comparison of Results", G. Agnello, P. Bertotto, M. Borsero, G. Pierucci, V. Squizzato, EMC '96, International Symposium on Electromagnetic Compatibility, Rome, Italy, September 1996
- "Electric Field Probes for Cellular Phone Dosimetry", H.I. Bassen, Center for Devices and Radiological Health, FDA, Attachment 6a, Minutes IEEE Standards Coordinating Committee - 34, Subcommittee - 2 (Certification of Wireless Handsets), Qualcomm, La Jolla, California, 3&4 December, 1997.
- "New Perspective in Broad Band Sensors Calibration", Licitra, Francia, Giusti, Pocai, EMC '96, International Symposium on Electromagnetic Compatibility, Rome, Italy, September 1996

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3.1.2 Definition

The sensitivity of each of the three probe channels is a DC voltage produced at the outputs with the probes exposed to a specified free space electrical field.

3.1.3 Minimum Standard

The sensitivity of the probes depends on the manufacturer of the probes and individual components used to manufacture the probes. As such, there is no minimum requirement for sensitivity of the probes.

3.1.4 Test Equipment

Description	Manufacturer	Model
RF Signal Generator	Hewlett Packard	8662A
RF Amplifier 0.5 – 1 GHz	APREL	RFPA-1000
TEM Test Cell	Fischer Custom Communications	FCC-TEM-JM1
RF Power Meter	Rohde & Schwarz	NRVS
Miniature E-field probe	Narda	8021B
Probe support fixture	APREL	N/A
Computer	Northern Micro	Pentium 75
Software	Microsoft	Office 97 Pro
Software	APREL	SAR Measurement
Data acquisition card	ComputerBoards	CIO-DAS08-PGH
Miscellaneous Cables	N/A	N/A

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3.1.5 Test Configuration

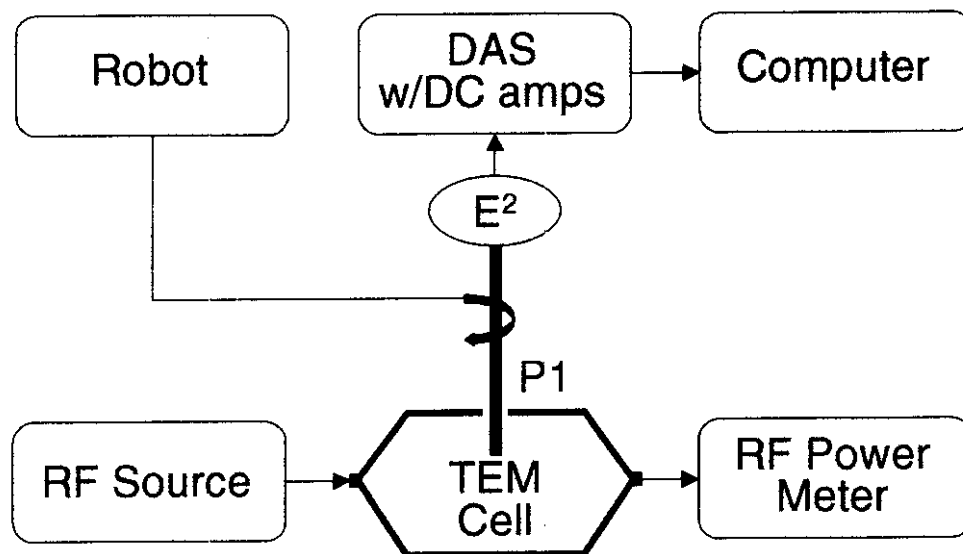


Figure 3.1

3.1.6 Test Procedure

1. Connect the equipment as shown in the test configuration.
2. Set the RF generator frequency to 1GHz.
3. Adjust the RF generator output so that the power density inside the TEM Cell is 1mW/cm². (For the FCC Model FCC-TEM-JM1 Cell, the correct power level is 153 mW.)
4. Mount the probe of the system to be calibrated in the support fixture.
5. Insert the probe through the side aperture of the TEM Cell. The probe handle should be at the geometric center of the aperture, i.e. midway between the septum and the upper surface, and orthogonal to the side of the Cell. The sensing portion of the probe should be located at a point halfway across the depth of the cell (volumetric center).
6. Once the prescribed position is obtained, it must be maintained during the rest of the measurement. The only movement of the probe allowed is rotation on its axis to position the dipoles in the plane of E-field.
7. Verify that the RF power level remains constant throughout the measurement. While the probe is being rotated through 360 degrees, record the maximum measured on each channel.

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8. Set the RF generator to a desired calibration frequency and repeat steps 4 through 7.

3.1.7 Test Data Table

The sensitivities in mV/ (mW/cm²) for each channel can be recorded in the following table:

Frequency (MHz)	Channel 0 (Pins 6 & 1)		Channel 1 (Pins 2 & 3)		Channel 2 (Pins 4 & 5)	
	e	η	e	η	e	η
835						
1000						

3.2 Determining E-Field Probe Sensitivities at Frequencies above 1 GHz

3.2.1 References

- "Calibration of Low Frequency Electric and Magnetic Field Probes", W. Köhler, EMC '96, International Symposium on Electromagnetic Compatibility, Rome, Italy, September 1996
- "Calibration of Electromagnetic Field Probes in Different Measurement Sites: Comparison of Results", G. Agnello, P. Bertotto, M. Borsero, G. Pierucci, V. Squizzato, EMC '96, International Symposium on Electromagnetic Compatibility, Rome, Italy, September 1996
- "Electric Field Probes for Cellular Phone Dosimetry", H.I. Bassen, Center for Devices and Radiological Health, FDA
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3.2.2 Definition

The sensitivity of each of the three probe channels is a DC voltage produced at the outputs with the probes exposed to a free space electrical field at frequencies greater than or equal to 1 GHz.

3.2.3 Minimum Standard

The sensitivity of the probes depends on the manufacturer of the probes and individual components used to manufacture the probes. As such, there is no minimum requirement for sensitivity of the probes.

3.2.4 Test Equipment

Description	Manufacturer	Model
RF Signal Generator	Hewlett Packard	8340B
TWT Amplifier (1.4 – 2.4 GHz)	Hughes	1177H-10F000
Anechoic Shielded Room	APREL	N/A
Horn Antenna (1 – 18 GHz)	APREL	AA-118
RF Power Meter	Rohde & Schwarz	NRVS
Miniature E-field probe	Narda	8021B
Probe support fixture	APREL	N/A
Computer	Northern Micro	Pentium 75
Software	Microsoft	Office 97 Pro
Software	APREL	SAR Measurement
Data acquisition card	ComputerBoards	CIO-DAS08-PGH
Miscellaneous Cables	N/A	N/A

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3.2.5 Test Configuration

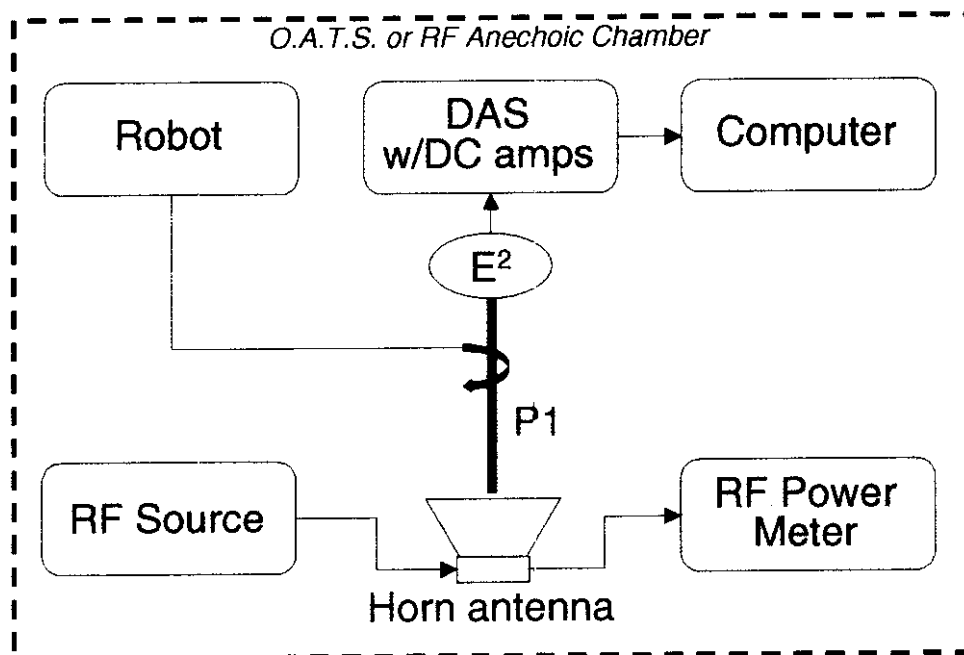


Figure 3.2

3.2.6 Test Procedure

1. Mount the miniature RF probe of the system to be calibrated in a support fixture.
2. Setup the equipment so that the horn antenna is coaxial with, and separated from the probe by 1 m.
3. Set the RF generator output at 1GHz.
4. Adjust the RF generator output so that the power density at the miniature RF probe is $1\text{mW}/\text{cm}^2$
5. Once the prescribed position is obtained, it must be maintained during the rest of the measurement. The only movement of the probe allowed is rotation on its axis to position the dipoles in the plane of E-field.
6. While the probe is being rotated through 360 degrees, record the maximum measured on each channel.
7. Verify the 1 GHz results against those obtained with the TEM cell at the same frequency before proceeding
8. Set the RF generator to a desired calibration frequency and repeat steps 4 through 6.

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3.2.7 Test Data Table

The sensitivities in mV/ (mW/cm²) for each channel can be recorded in the following table:

Frequency (GHz)	Channel 1 (Pins 6 & 1)		Channel 2 (Pins 2 & 3)		Channel 3 (Pins 4 & 5)	
	e	η	e	η	e	η
1.0						

4.0 DETERMINING THE ENHANCEMENT FACTOR OF SIMULATED TISSUE

4.1 Background

The enhancement factor describes the ratio of the sensitivity of the probe sensors in different media to their sensitivity in air. The calibration factor needs only be calculated once for each probe type

4.2 References

- SAR Measurement Operational Guide, O.M. Garay and Q. Balzano, 1995, Motorola, Florida Corporate Electromagnetics Research Laboratory, Fort Lauderdale, Florida.
- "Broadband Calibration of E-Field Probes in Lossy Media", K. Meier, M. Burkhardt, T. Schmid, and N. Kuster, 1996, IEEE Transactions on Microwave Theory and Techniques. 44:1954-1962.

4.3 Definition

enhancement factor: the ratio of the sensitivity of the probe sensors in different media to their sensitivity in air.

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4.4 Minimum Standard

The enhancement factor of the probes depends on the simulated tissue formulation. As such, there is no minimum requirement for the enhancement factor of the probes.

4.5 Test Equipment

Description	Manufacturer	Model
Precision Thermistor	Omega	ON-901-44004
Precision Dual-Channel Thermometer	Guildline	5150
Insulated Flat Phantom	APREL	
Synthetic Tissue Mixture	APREL	SSI/DRB-TP-D01-033
Reference Half-Wave Dipole	APREL	various
RF Signal Generator	Hewlett Packard	8340B
Amplifier	various	various
RF Power Meter	Rohde & Schwarz	NRVS
Miniature E-field probe	Narda	8021B
Probe support fixture	APREL	N/A
Computer	Northern Micro	Pentium 75
Software	Microsoft	Office 97 Pro
Software	APREL	SAR Measurement
Data acquisition card	ComputerBoards	CIO-DAS08-PGH
Miscellaneous Cables	N/A	N/A

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4.6 Test Configuration

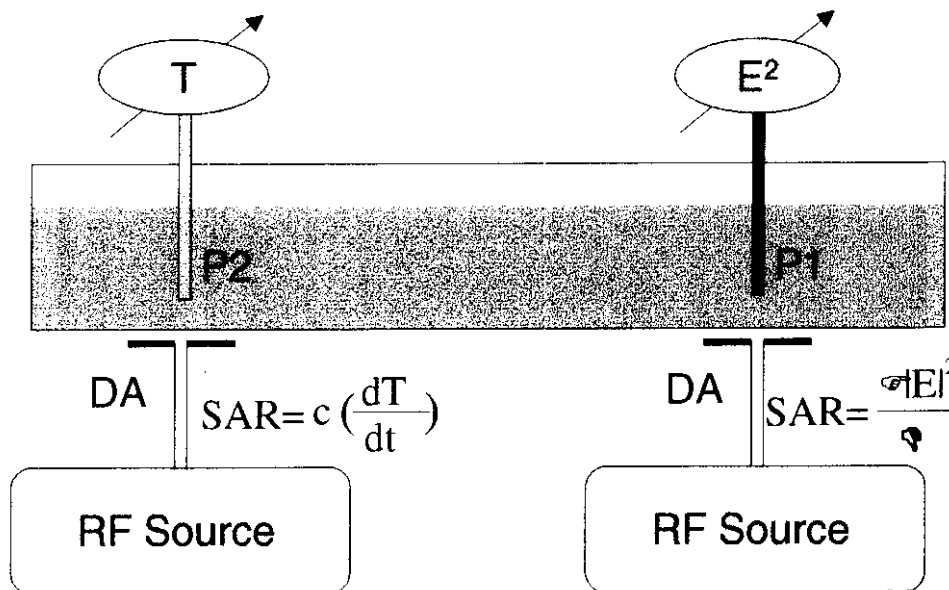


Figure 4.1

4.7 Test Procedure

1. A RF-transparent thermistor-based temperature probe (used with the Guildline 5150 Precision Dual-Channel Thermometer) and an isotropic E-field probe are placed side-by-side in a planar phantom while both are exposed to RF energy from a half wave dipole antenna located below the phantom (See Fig. 4.1). The E-field probe and data acquisition system was previously calibrated (see Section 3.0).
2. First, the location of the maximum E-field close to the phantom's bottom is determined as a function of power into the dipole.
3. Then, the E-field probe is moved sideways so that the temperature probe, while affixed to the E-field probe, is placed at the previous location of the E-field probe.
4. Finally, temperature changes for 30-second exposures at the same RF power levels used for the E-field measurement are recorded.
5. Care is taken to allow cooling to the original temperature and temperature stabilization between tests. (The heated region of the mixture is briefly stirred to accelerate the process).

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Ref: Project U404-7-0016 -1997

4.8 Test Data Table

Frequency: (MHz)				Date:
RF Power	E-Field Measurement μ V Sensor			Temperature change Measurement ($^{\circ}$ C)
Watts	1	2	3	30 Seconds

4.9 Test Data Analysis

The data from the insulated flat phantom measurements are used to determine the enhancement factor (γ) of the simulated tissue from the following relationships:

$$SAR = C \frac{\Delta T}{\Delta t} \quad (1)$$

$$SAR = \frac{\sigma |E|^2}{\rho} \quad (2)$$

or

$$SAR = 3.77 \times 10^{-4} \frac{\sigma}{\rho \gamma} \sum_{i=1}^3 \frac{V_i}{\eta_i} \quad (3)$$

where C is the heat capacity of the simulated tissue (see SSI/DRB-TP-D01-033)
 ΔT is the temperature rise in $^{\circ}$ C measured for an elapsed time of Δt seconds
 (30s)

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- $|E|^2$ is the total RMS E-field level (V/m) induced within the exposed tissue
 σ is the conductivity of the simulated tissue (see SSI/DRB-TP-D01-033)
 ρ is the density of the simulated tissue (see SSI/DRB-TP-D01-033)
 V_i are the rectified signal voltages measured on each of the three sensors in the probe
 η_i are the sensor sensitivities relating the signal from a single sensor and the field component in the direction of the sensor
 γ is the tissue enhancement factor which related the sensitivity of the probe in different media to their sensitivity in air.

Taking the derivative of equations (1) and (3) with respect to the RF power (P) delivered to the dipole:

$$\frac{d(SAR)}{dP} = \frac{C}{\Delta t} \frac{d\Delta T}{dP} \quad (4)$$

$$\frac{d(SAR)}{dP} = 3.77 \times 10^{-4} \frac{\sigma}{\rho \gamma} \frac{d}{dP} \left(\sum_{i=1}^3 \frac{V_i}{\eta_i} \right) \quad (5)$$

Let $m_T = \frac{d\Delta T}{dP}$ which is the slope of a temperature change (ΔT) versus power (P) graph;

and $m_V = \frac{d}{dP} \left(\sum_{i=1}^3 \frac{V_i}{\eta_i} \right)$ which is the slope of the total compensated measured voltage $\left(\sum_{i=1}^3 \frac{V_i}{\eta_i} \right)$ versus power (P) graph.

Setting equations 4 and 5 equal to each other and solving for γ we get:

$$\gamma = 3.77 \times 10^{-4} \frac{\sigma}{\rho} \frac{\Delta t}{C} \frac{m_V}{m_T}$$

EXHIBIT NINE

Aprél Positioning and Scanning Requirements SSI/DRB-TP-D0L-034

ITRONIX CORPORATION

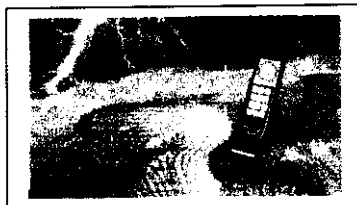
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Positioning and Scanning Requirements

SSI/DRB-TP-D01-034



PART of SAR Measurements Requirements

SSI/DRB-TP-D01-030

DRAFT

Prepared jointly with:

APREL

Near Field Measurements Laboratory

March 1998

- NOTICE -

This draft was prepared to assist the Dosimetry Research Board of SPECTRUM SCIENCES INSTITUTE and specifically the Working Group on SAR Measurements. It is submitted as a basis for discussion only, and is not binding on APREL Inc. Subsequent study may lead to revisions of the document, both in numerical values and/or form, and after continuing study and analysis, APREL inc. specifically reserves the right to add to, or amend the content of this contribution.

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1.0 INTRODUCTION

1.1 Purpose and Scope of the Standard

The purpose of this document is to standardize the portable transmitter positioning and E-field scanning inside the phantom that simulates parts of the human body for Specific Absorption Rate (SAR) measurements.

This Standard defines:

- the methodology and procedures to be followed in the laboratory to setup the portable handset
- the procedure to define the E-field area scanning
- the procedure to determine zoom scan to derive the 1 or 10 gram average SAR.

This Standard is part of a Certification Program Methodology as described in a separate document entitled "SSI/DBR TP-D01-030, Specific Absorption Rate (SAR) Standard For Portable Telecommunications Devices, March 1998". SSI/DBR TP-D01-034 contains specific criteria that must be met for SAR certification.

1.2 Test Facilities

All calibration work as described in this Standard shall be performed at an ISO/IEC Guide 25 accredited laboratory.

1.3 Test Personnel

Personnel performing the calibration will be experienced in relevant measurements (eg physical properties or RF characteristics) and supervised by a person proficient in SAR measurements.

1.4 Test Equipment

The required test equipment, hardware and software, is identified in each individual procedure. Equipment may be substituted or updated from time to time. Should this

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1.5 Standard Environmental Conditions

All measurements and calibration should be performed under normal laboratory conditions for physical properties and electrical characteristics as stipulated by ISO/IEC Guide 25. The nominal temperature for physical property measurements and for electrical characterization are 20°C and 23°C, respectively.

2.0 BACKGROUND

2.1 Positioning of the Device Under Test (DUT)

In positioning a portable communication device with respect to the simulated human body, we are interested in obtaining the worst coupling between the device and the head while ensuring that such a position is a reasonable approximation of a common usage position.

SAR inside the head is predominantly attributable to the H-fields produced by the currents inside the handset or along its antenna. These H-fields cause currents in the boundary of the phantom, which in turn induce E-fields within the simulated tissue. These E-fields give rise to the measured SAR within the portion of the simulated human body being exposed.

The exact sources of the highest H-fields within the phone are not usually known. However, the antenna feedpoint area is normally the prime suspect. The coupling of a high current producing area with the simulated tissue causes deposition of energy into the simulated tissue as well as modifications to characteristics of the transmitting source itself.

If a large plastic case, with various internal components, is coupled to simulated tissue, and the coupled area does not carry current, or the current carrying area is remote (in relative terms), there will be no significant SAR deposited in the tissue, nor will there be any significant change of the source.

The purpose of various standards (e.g. CENELEC), or industry practices, is to position the handset with respect to an arbitrary shape of the head in such a way that the coupling between the tissue and the current source is the strongest.

The Universal Head-arm (UniHead) is engineered in such a way that the maximum coupling can be found without maneuvering the handset through various positions. This is

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achieved by placing the handset at a constant position and a constant displacement relative to the phantom. Thus the SAR generating area, wherever it is in the handset, will always couple to the simulated tissue. This makes maneuvering of the handset (3 angles, left-right ear, 3 point contact, etc.) redundant.

The commonly accepted distance between the tissue boundary and the handset is 6 mm (2 mm shell + 4 mm for the compressed human ear).

In the practice of measuring SAR a plastic layer forms part of the space between the tissue boundary and the phone. The dielectric and conductive characteristics of this layer of plastic are relatively close to those of air in comparison to those of the simulated tissue. It is believed in today's practice that this layer does not have any other role than creating a distance between the device surface and the tissue boundary. However, an investigation of the measuring uncertainty produced by the presence of plastic are not very complete. In the UniHead, for the sake of precision and repeatability, the only layer which is introduced is the one that is needed to contain the tissue simulation and no additional arbitrarily shaped space is introduced.

In the research carried out by APREL Laboratories for Spectrum Sciences Institute, much of which was witnessed by industry, it was demonstrated that when the current was flowing in the parts of the phone closer to the head than the hand simulation, there was essentially no impact on the SAR distribution or the peak SAR value (< 10% difference). However, in instances when the current carrying components are closer to the hand than to the head, the impact on the handset performance and peak SAR value is significant, and should not be neglected.

In the instances where there is a requirement for measurement without the hand, the Universal Head is engineered in such a way that the simulated tissue can be easily removed from the hand simulation and thus becomes a positioning bracket with marginal quantities of plastic with a marginal impact on the radiated fields.

2.2 Area Scanning

A head model is usually placed on its side, which allows a handset to be placed underneath the head to facilitate field measurements. The field probe is inserted into the liquid from above and measurements can then be made on the inside surface of the head next to the phone. SAR measurements usually start with a coarse measurement at 1-2 cm resolution where the electric field probe is scanned throughout the entire region of tissues next to the handset and its antenna. This provides a SAR distribution near the surface of the phantom, closest to the phone, where the approximate location of the peak SAR can be identified.

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2.3 Zoom Scanning and 1g or 10g Averaging

A smaller region centered on the peak SAR location is then scanned with a 1-5 mm finer resolution to determine the one-gram average SAR. The measurements obtained from this fine resolution scan are averaged over a 1-cm³ volume in the shape of a cube to determine the one-gram average SAR. A 10-cm³ volume for a ten-gram average SAR is appropriate for the extremities in North America, or for all requirements in Europe or Japan. The average density of most high water-content tissues is about 1020-1040 kg/m³, which requires the tissue volume to be about 1 cm long on each side. For a 10-gram average SAR a tissue volume of 2 cm long on each side can be used produce a conservative overestimate of the SAR value (the actual side length should be 2.125 cm). The number of measurement points required in the fine scan to provide accurate one-gram average SAR is dependent on the field gradients at the peak SAR location. In smooth gradients, the one-gram average SAR can be correctly predicted with only a few measurement points. When steep field gradients exist, many measurement points evenly distributed within a cubic centimeter of the tissue material may be required to correctly predict the one-gram average SAR. To overcome this problem, a curve-fitting process may be applied to the measured data to allow more points to be used in the average.

The measurements provided by electric field probe normally do not correspond to the location at the tip of a probe because the detectors are located behind the tip. For homogeneous phantoms, the peak field values are at the surface of the phantom, but the detectors of the probe are generally 2.5-7.0 mm behind the tip of the probe. Therefore the field measurements must be extrapolated to the surface of the phantom to compensate for field attenuation introduced by this offset distance. This can be done by taking a number of measurement points in a straight line perpendicular to the phantom surface at the peak SAR location and applying a curve-fitting process for the extrapolation.

If measurements in the immediate vicinity of the phantom surface are included in the extrapolation routine, the boundary effect of the probe must be considered. The boundary effect results in an increased sensitivity of the probe and is caused by the interaction of the field disturbance around the probe with the boundary. The strength of the overestimation depends on the probe dimensions, the probe distance from the surface, the boundary curvature, the probe angle to the surface and the field decay in the solution. If the boundary effect is not completely compensated for in the software, a positive error offset (overestimation) of the spatial peak SAR will occur. An alternative approach is to dismiss all measurements near the surface and extrapolate over a longer distance. This will eliminate the offset error, but largely increase the error due to extrapolation uncertainty.

The actually assessed cube is a surface adapted "cube" as opposed to a geometrical cube. This is partially due to the missing definition of the cube placement and partially due to the mechanics of the data acquisition systems which operate in a Cartesian coordinate system.

3.0 REFERENCES

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- CENELEC, prES 59005, "Considerations for human exposure to electromagnetic fields from mobile telecommunication equipment (MTE) in the frequency range 30MHz - 6 GHz", December 1997

4.0 DEVICE UNDER TEST (DUT) POSITIONING PROCEDURES

4.1 DUTs Held Against the Ear

1. Select the simulated tissue appropriate for the type of tissue being tested, and the operating frequency of the DUT, and fill the Universal Head-arm (UniHead) with it.
2. Allow sufficient time for all air bubbles to escape before performing a scan.
3. Lift up the measurement slide (see Figure 4.1) and place the DUT face-up under it. Lower the measurement slide so that it rests on the DUT and record the height on the scale to the left of the slide using the lower edge of the slide as reference.
4. Add 4 mm to this height to account for the spacing provided by a compressed human ear and record the value.

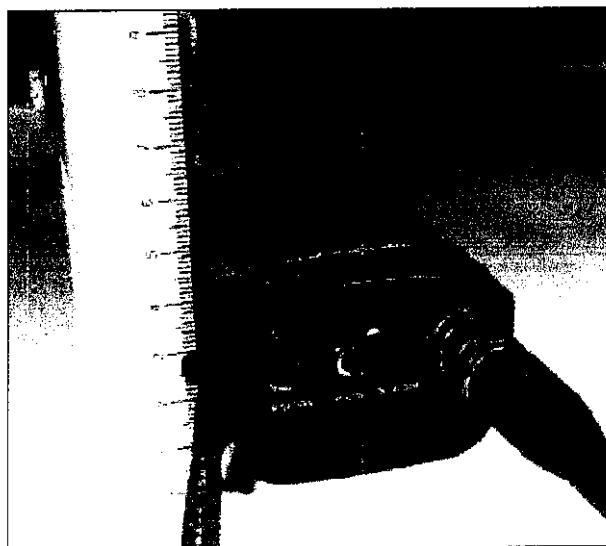


Figure 4.1

5. Put the DUT into test mode at the highest rated power, and operating on either the maximum performance frequency or one of the low, middle and high channels.
6. Loosen the bolt (on the right side of the UniHead stand) holding the hand simulator support, using the orange finger tab, and lower whole structure. Pull out the sliding support, using its orange finger tab (Figure 4.2), so that the DUT simulator is easily accessible.
7. Position the DUT on top of the hand simulator, butting the top of it up against the reference pin, and centered within the locating lines (see Figure 4.3).

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8. Use a rubber band (elastic) to hold the DUT in place making use of the two notches on either side of the hand simulator (see Figure 4.2).

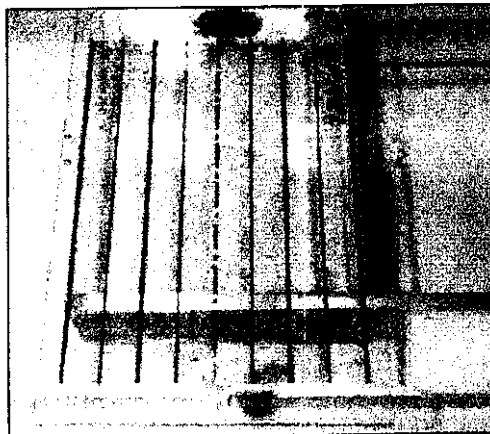
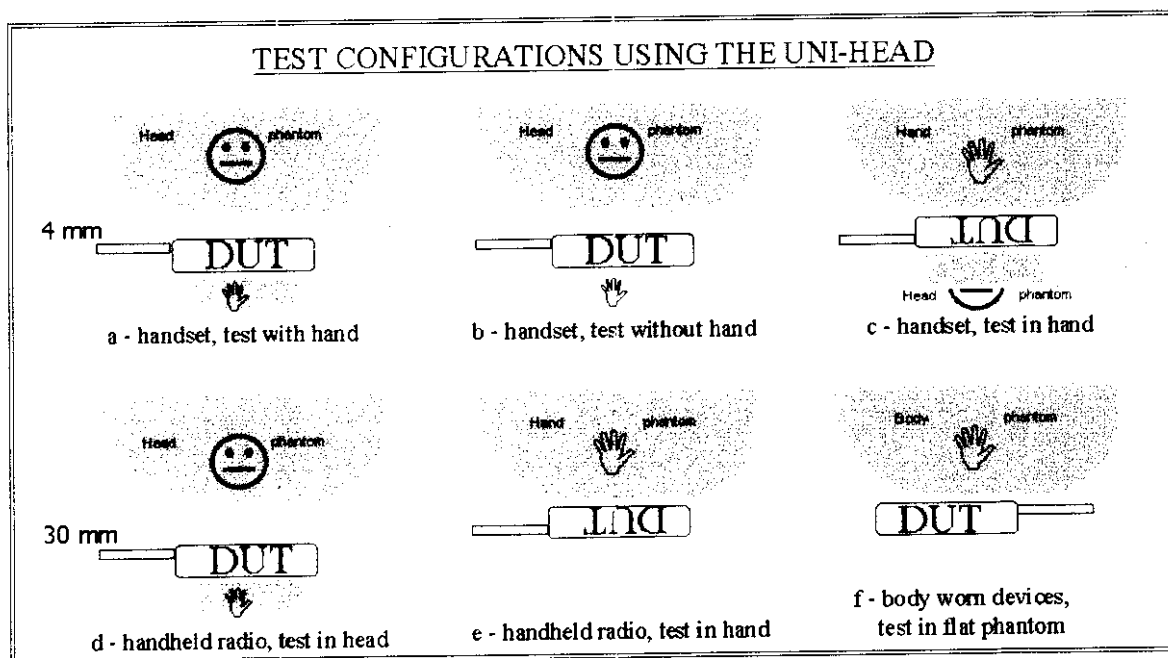


Figure 4.2

9. Slide the hand simulator back under the UniHead until it stops against the mechanical stop. This will locate the device properly in a horizontal plane in relation to the head simulator.
10. Slide the hand simulator support up until the top of the support lines up with the height determined in step 4 above.
11. Looking from above the device should be lined up as shown in Figure 4.4



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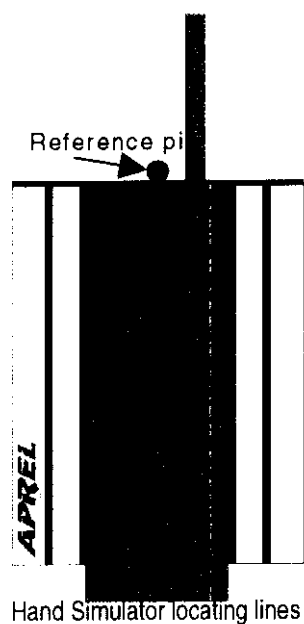


Figure 4.3

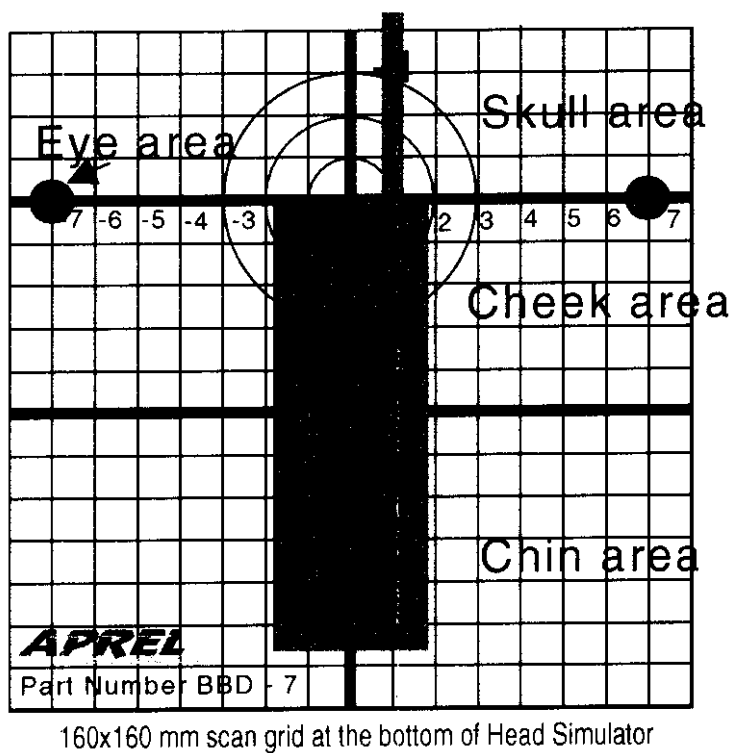


Figure 4.4

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4.2 DUTs Held In Front of the Mouth (e.g. PPT radio like handset)

1. Perform steps 1 through 9 as in Section 4.1.
2. Lower the device by 30 mm to account for the spacing provided by a human nose.
3. Looking from above the device should be lined up as shown in Figure 4.4

4.3 DUTs Used in the Hand Away from the Body (e.g. point of sale device)

The head simulator can be used as a substitute for the hand when performing a SAR evaluation for a device that is normally held in the hand but is not used in the vicinity of the head or the body. In this case the hand simulator should be empty (i.e. it will not contain simulated tissue) and will act strictly as a support to hold the DUT. The hand substitute (i.e. the head simulator) should be filled with simulated muscle tissue.

1. Close the valve between the head simulator and the hand simulator. This will ensure that the hand simulator remains empty and will serve only as a support for the DUT (if the hand is full of simulated tissue from a previous procedure, disconnect and empty it).
2. Select the simulated tissue appropriate for the type of tissue being tested, and the operating frequency of the DUT, and fill the head simulator portion of the UniHead with it.
3. Allow sufficient time for all air bubbles to escape before performing a scan.
4. Lift up the measurement slide (see Figure 4.1) and place the DUT face-up under it. Lower the measurement slide so that it rests on the DUT and record the height on the scale to the left of the slide using the lower edge of the slide as reference.
5. Add 30 mm to this height to account for the spacing provided by a human nose and record the value.
6. Put the DUT into test mode at the highest rated power, and operating on either the maximum performance frequency or one of the low, middle and high channels.
7. Loosen the bolt (on the right side of the UniHead stand) holding the hand simulator support, using the orange finger tab, and lower whole structure. Pull out the sliding support, using its orange finger tab (Figure 4.2), so that the DUT simulator is easily accessible.
8. Position the DUT upside-down on top of the hand simulator, butting the top of it up against the reference pin, and centered within the locating lines (see Figure 4.3).
9. Use a rubber band (elastic) to hold the DUT in place making use of the two notches on either side of the hand simulator (see Figure 4.2).
10. Slide the hand simulator back under the UniHead until it stops against the mechanical stop. This will locate the device properly in a horizontal plane in relation to the head simulator.

11. Slide the hand simulator support up until the top of the support lines up with the height determined in step 5 above.
12. Looking from above the device should be lined up as shown in Figure 4.4

4.4 DUTs Carried Next to the Body

The head simulator can be used as a substitute for the body, or thighs, when performing a SAR evaluation for a device that is normally positioned against the body. These devices include backpack, shoulder strap or belt mounted portable communication gear as well as those installed into laptop computers. In this case the hand simulator should be empty (i.e. it will not contain simulated tissue) and will act strictly as a support to hold the DUT. The body or thigh substitute (i.e. the head simulator) should be filled with simulated muscle tissue.

- 1 Close the valve between the head simulator and the hand simulator. This will ensure that the hand simulator remains empty and will serve only as a support for the DUT (if the hand is full of simulated tissue from a previous procedure, disconnect and empty it).
- 2 Select the simulated tissue appropriate for the type of tissue being tested, and the operating frequency of the DUT, and fill the head simulator portion of the UniHead with it.
- 3 Allow sufficient time for all air bubbles to escape before performing a scan.
- 4 Lift up the measurement slide (see Figure 4.1) and place the DUT face-up under it. Lower the measurement slide so that it rests on the DUT and record the height on the scale to the left of the slide using the lower edge of the slide as reference.
- 5 Add 30 mm to this height to account for the spacing provided by a human nose and record the value.
- 6 Put the DUT into test mode at the highest rated power, and operating on either the maximum performance frequency or one of the low, middle and high channels.
- 7 Loosen the bolt (on the right side of the UniHead stand) holding the hand simulator support, using the orange finger tab, and lower whole structure. Pull out the sliding support, using its orange finger tab (Figure 4.2), so that the DUT simulator is easily accessible.
- 8 Position the DUT upside-down on top of the hand simulator, butting the top of it up against the reference pin, and centered within the locating lines (see Figure 4.3).
- 9 Use a rubber band (elastic) to hold the DUT in place making use of the two notches on either side of the hand simulator (see Figure 4.2).
- 10 Slide the hand simulator back under the UniHead until it stops against the mechanical stop. This will locate the device properly in a horizontal plane in relation to the head simulator.

- 11 Slide the hand simulator support up until the top of the support lines up with the height determined in step 5 above.
- 12 Looking from above the device should be lined up as shown in Figure 4.4

5.0 AREA SCANNING PROCEDURE

Once the DUT is properly positioned with respect to the UniHead, a coarse scan of the electric field generated by the DUT can be made using a miniature isotropic E-field probe, throughout the entire region of tissues next to the handset and its antenna. This provides a SAR distribution near the surface of the phantom, closest to the phone, where the approximate location of the peak SAR can be identified.

5.1 Definition

area scan: measurement of the electric field inside the simulated tissue, over an array of positions following the inside surface of the phantom, and covering the entire region. The resolution of the scan is usually 1-3 cm.

5.2 Test Equipment

Table 5.1

Description	Manufacturer	Model
Articulated Robot Arm	CRS Robotics	A255
Robotic System Controller	CRS Robotics	C500
Phantom	APREL	UniHead
Phantom support fixture	APREL	various
Synthetic Tissue Mixture	APREL	SSI/DRB-TP-D01-033
Miniature E-field probe	Narda	8021B
Probe support fixture	APREL	N/A
Computer	Northern Micro	Pentium 75
Software	CRS Robotics	RobComm
Software	Microsoft	Office 97 Pro
Software	APREL	SAR Measurement
Data acquisition card	ComputerBoards	CIO-DAS08-PGH
Miscellaneous Cables	N/A	N/A

5.3 Test Procedure

1. Ensure that the UniHead is level.
2. Start RobComm, open FLATSAR.TXT, and start Dashboard. Use the mouse to push RESET button and then the GO button. This will place the miniature E-field probe above the UniHead in its start position.
3. Close Dashboard and put RobComm in Terminal mode.
4. Type STATUS and check that the tool transform in effect is REF25.
5. Move the probe to (x,y) coordinates (12,8) on the grid (see Figure 5.1).
6. Adjust the probe height so that it is 2.5 mm above the phantom surface.
7. Set the position BEGIN to this probe location.
8. Move the probe 12 cm along the x-axis. If the probe does not follow the grid line, move the probe back 12 cm, and then readjust the UniHeads position and try again by moving the probe 16 cm along the y-axis. If the probe still does not follow a

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grid line, move the probe back 16 cm along the y-axis, and readjust the UniHead position again.

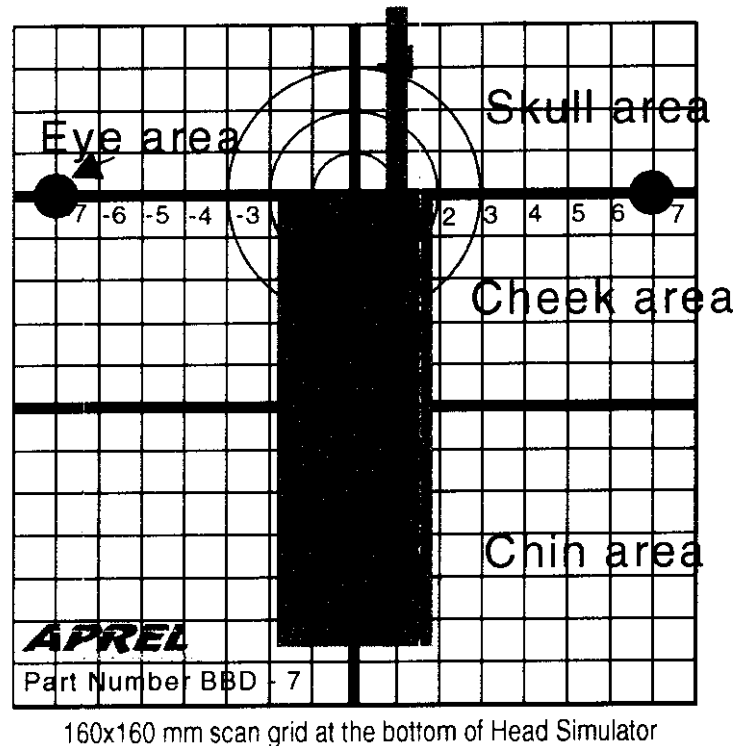


Figure 5.1

9. Repeat step 7 until the robot's x- and y-axes coincide with the UniHead's.
10. Exit Terminal Mode and restart Dashboard. Use the mouse to push RESET button and then the GO button. This will place the miniature E-field probe above the UniHead in its start position.
11. From the Application Menu select FLATSAR.XLS. Microsoft Excel will open this file automatically.
12. Enter a name for the spreadsheet that will be created with the measurement data. The file name should include the DUT model number, measurement height, "area" and date.
13. Select the scan resolution of 10 mm. The default scan resolutions available are 10 mm and 5 mm. The default x and y spans are 16 cm and 8 cm, for 10 and 5 mm resolutions, respectively. (The x-axis is along the DUT and y-axis is across the DUT). If other scan resolutions or spans are desired, then the Visual Basic code will have to be edited.
14. Start the scan by pushing the ACQUIRE DATA button with the mouse pointer. The application will now run automatically and acquire the data.

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15. Once the application has stopped, quit the application. Reenter Terminal mode and change the tool transform to REF125. Type STATUS and verify that the tool transform in effect is REF125.
16. Repeat steps 10-14. This creates a spreadsheet with a second scan data set 1 cm further away from the surface of the phantom.
17. Once the application has stopped, quit the application. Print out the surface and contour plots for each of the 2 spreadsheets.

6.0 ZOOM SCANNING AND 1 OR 10 GRAM AVERAGING PROCEDURES

A smaller region centered on the peak SAR location identified with the area scan is then scanned with a 5 mm finer resolution to determine the one-gram, or ten-gram, average SAR. The measurements obtained from this fine resolution scan are averaged over a 1-cm³ volume in the shape of a cube to determine the one-gram average SAR, or an 8-cm³ volume for a ten-gram average SAR.

The spatial peak SAR is calculated from a large number of values (27); measured in a volume of 80 x 80 x 10 mm around the maximum local SAR (867 values in total). A numerical procedure then searches for the 1-cm³ or 8-cm³ cube with the highest average SAR within this data array.

An exponential extrapolation to the surface is then applied based on measurements made on 4 or 5 grid locations, at 2.5 mm intervals between 2.5 and 17.5 mm from the inside surface of the phantom.

An exponential extrapolated to the surface of the phantom is then applied to compensate for the field attenuation introduced by the 7 mm offset distance between the E-field detectors to the tip of the probe and the 2.5 mm distance from the lowest measurements to the surface. The extrapolation is calculated from 5 sets of data taken in a straight line perpendicular to the phantom surface at the peak SAR location and applying an exponential curve-fitting routine for the extrapolation. The location of these sets is at the center of the peak SAR cube and the 4 next nearest (x,y) coordinates.

6.1 Definitions

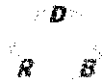
zoom scan: measurement of the electric field inside the simulated tissue, over an array of positions following the inside surface of the phantom, and covering a region in the vicinity of the peak(s) identified with an area scan. The resolution of the scan is usually 1-5 mm.

1-g average: the peak energy absorption rate averaged over the 1 g of tissue in the shape of a cube. Since the average density of simulated muscle or brain tissue is 1020-1040 kg/m³ this ideally corresponds to a side length of 0.987 – 0.993 cm. In practice, 1 cm sides are normally used.

10-g average: the peak energy absorption rate averaged over the 10 g of tissue in the shape of a cube. Since the average density of simulated muscle or brain tissue is 1020-1040 kg/m³ this ideally corresponds to a side length of 2.126 - 2.140 cm. In practice, 2 cm sides are normally used.

6.2 Zoom Scanning Procedure

1. Review the plots obtained from the area scan and determine one set of grid coordinates (x_m , y_m) that is closest to the maximum SAR value measured on each of the two sets of area scans. The maximums on the two levels are usually at the same coordinates, or with a cm or so of each other.
2. Close Dashboard, put RobComm in Terminal mode and change the tool transform to REF25. Type STATUS and verify that the tool transform in effect is REF25.
3. Move the probe to (x,y) coordinates ($x_m+4\text{cm}$, $y_m+4\text{cm}$) on the grid (see Figure 5.1).
4. Set the position BEGIN to this probe location.
5. Exit Terminal Mode and restart Dashboard. Use the mouse to push RESET button and then the GO button. This will place the miniature E-field probe above the UniHead in its start position.
6. From the Application Menu select FLATSAR.XLS. Microsoft Excel will open this file automatically.
7. Enter a name for the spreadsheet that will be created with the measurement data. The file name should include the DUT model number, measurement height, "zoom" and date.
8. Select the scan resolution of 5 mm. The default x and y spans are 8 cm. If other scan resolutions or spans are desired, then the Visual Basic code will have to be edited.
9. Start the scan by pushing the ACQUIRE DATA button with the mouse pointer. The application will now run automatically and acquire the data.



10. Once the application has stopped, quit the application. Reenter Terminal mode and change the tool transform to REF75. Type STATUS and verify that the tool transform in effect is REF75.
11. Repeat steps 5-9. This create a spreadsheet with a second scan data set 0.5 cm further away from the surface of the phantom.
12. Once the application has stopped, quit the application. Reenter Terminal mode and change the tool transform to REF125. Type STATUS and verify that the tool transform in effect is REF125.
13. Repeat steps 5-9. This creates another spreadsheet with a third scan data set an additional 0.5 cm further away from the surface of the phantom. Once the application has stopped, quit the application.
14. Print out the surface and contour plots for each of the 3 spreadsheets.

6.3 1g and 10 g averaging

1. Open the PEAK SAR.XLS template and resave it with a new name that should include the DUT model number, "peak SAR" and date
2. Modify the formulas in the 1g and 10 g averaging sheets to gather data from the 3 zoom scan spreadsheets. A numerical procedure will then search for the 1-cm³ or 8-cm³ cube with the highest average SAR within this data array.
3. Note the location of the peak 1g or 10 g SAR and the (x,y) coordinates of the center and the 4 edges.
4. Use the mouse pointer to push RESET button on Dashboard and then the GO button. This will place the miniature E-field probe above the UniHead in its start position.
5. From the Application Menu select FLATSAR.XLS. Microsoft Excel will open this file automatically. Enter the name "TEMP" for the spreadsheet that will be created.
6. Use <ALT>-<TAB> to switch to back to RobComm.
7. Close Dashboard, put RobComm in Terminal mode and change the tool transform to REF25. Type STATUS and verify that the tool transform in effect is REF25.
8. Move the probe to the (x,y) coordinates corresponding to the center of the peak SAR cube.
9. Use <ALT>-<TAB> to switch to back to TEMP.XLS
10. Use the mouse pointer to push the "Single Point" button. Record the values displayed in the last 3 columns for the 3 probe sensors.
11. Use <ALT>-<TAB> to switch to back to RobComm.
12. Move the probe to the next (x,y) coordinates corresponding to the east edge of the peak SAR cube.
13. Repeat steps 9-11.
14. Move the probe to the next (x,y) coordinates corresponding to the south edge of the peak SAR cube.

15. Repeat steps 9-11.
16. Move the probe to the next (x,y) coordinates corresponding to the west edge of the peak SAR cube.
17. Repeat steps 9-11.
18. Move the probe to the next (x,y) coordinates corresponding to the north edge of the peak SAR cube.
19. Repeat steps 9-11.
20. Use <ALT>-<TAB> to switch back to RobComm.
21. Change the tool transform to REF50. Type STATUS and verify that the tool transform in effect is REF50.
22. Repeat steps 8 through 20.
23. Change the tool transform to REF50. Type STATUS and verify that the tool transform in effect is REF50.
24. Repeat steps 8 through 20.
25. Change the tool transform to REF75. Type STATUS and verify that the tool transform in effect is REF75.
26. Repeat steps 8 through 20.
27. Change the tool transform to REF100. Type STATUS and verify that the tool transform in effect is REF100.
28. Repeat steps 8 through 20.
29. Change the tool transform to REF125. Type STATUS and verify that the tool transform in effect is REF125.
30. Repeat steps 8 through 20.
31. Change the tool transform to REF150. Type STATUS and verify that the tool transform in effect is REF150.
32. Repeat steps 8 through 20.
33. Change the tool transform to REF175. Type STATUS and verify that the tool transform in effect is REF175.
34. Repeat steps 8 through 20.
35. Quit TEMP.XLS.
36. Enter the data obtained above into sheets Sensor1, 2 and 3 of the spreadsheet created in step 1.
37. A numerical procedure will process the data create a chart of the 5 exponential curve such as shown in Figure 6.1. The average of the exponential coefficients is then used to extrapolate the 1 g or 10 g peak SAR to the surface.

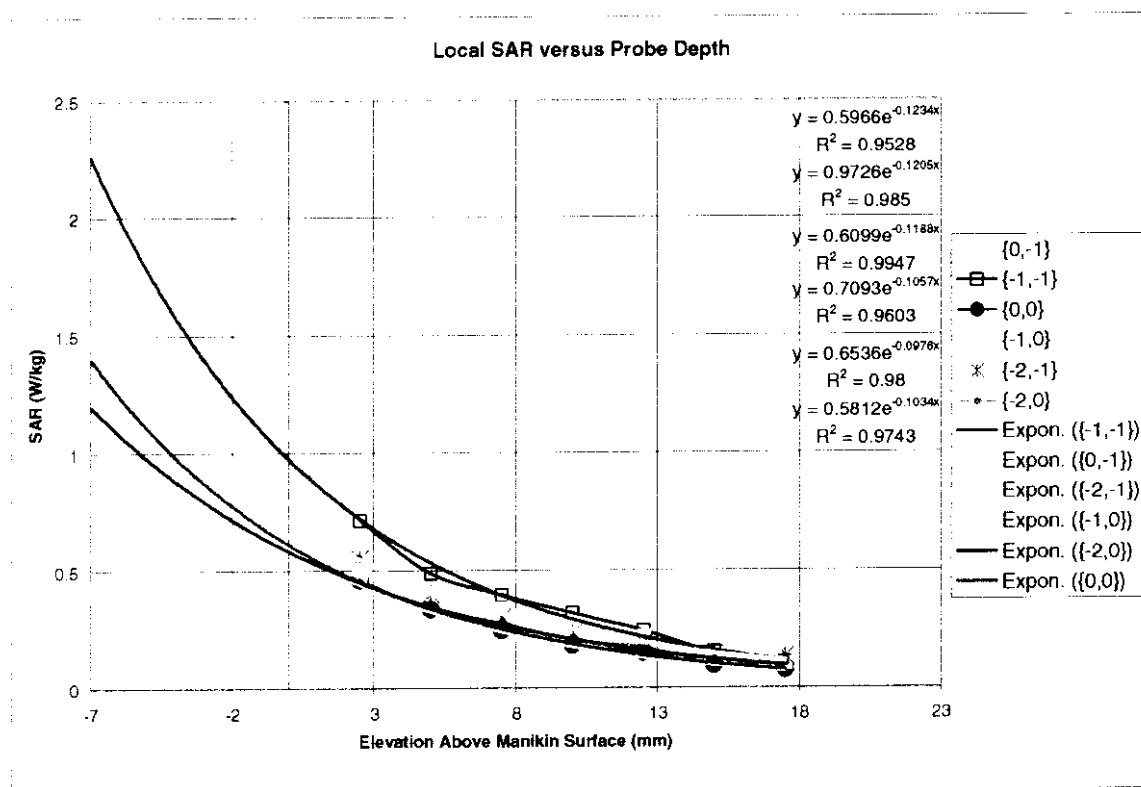


Figure 6.1

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