





TEST REPORT

Test Report No.: 1-2536/16-02-02





Testing Laboratory

CTC advanced GmbH

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Accredited Test Laboratory:

The testing laboratory (area of testing) is accredited according to DIN EN ISO/IEC 17025 (2005) by the Deutsche Akkreditierungsstelle GmbH (DAkkS)

The accreditation is valid for the scope of testing procedures as stated in the accreditation certificate with

the registration number: D-PL-12076-01-01

Applicant

Intel Corporation

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Phone: +1 408 765 8080

Manufacturer

Intel Deutschland GmbH

Konrad-Zuse-Bogen 4, 82152 Krailling, GERMANY

Radio Communications & EMC

Test Standard/s

Recommended Practice for Determining the Peak Spatial-Average Specific Absorption Rate

(SAR)in the Human Head from Wireless Communications Devices: Measurement Techniques

RSS-102 Issue 5 Radio Frequency Exposure Compliance of Radiocommunication Apparatus (All Frequency

Bands)

For further applied test standards please refer to section 3 of this test report.

Test Item

Kind of test item: Professional Drone Remote Control

Device type: portable device

Model name: INTEL COCKPIT GROUND CONTROL STATION V0.96

S/N serial number: 600

FCC-ID / IC: COCKPIT will be certified as host device containing FCC IDs & ICs.

See chapter 2.4 EUT description details.

Hardware status: 0.95 Software status: 0.793

Radio Communications & EMC

Frequency: 2.45 and 5 GHz proprietary control signal

Battery option: Fully Charged Internal Power Packs

(INTEL POWERPACK PP4000|14.8 V DC-4000mAh-59.2Wh)

Test sample status: identical prototype

Exposure category: general population / uncontrolled environment

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l est Report authorised:	l est performed:
p.o.	
Alexander Hnatovskiy Lab Manager	Marco Scigliano Testing Manager

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2 General information

2.1 Notes and disclaimer

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2.2 Application details

Date of receipt of order: 2017-03-15
Date of receipt of test item: 2017-03-16
Start of test: 2017-03-16
End of test: 2017-03-16

Person(s) present during the test:

2.3 Statement of compliance

The SAR values found for the INTEL COCKPIT GROUND CONTROL STATION V0.96 Professional Drone Remote Control are below the maximum recommended levels of 1.6 W/Kg as averaged over any 1 g tissue according to the FCC rule §2.1093, the ANSI/IEEE C 95.1:1992, the NCRP Report Number 86 for uncontrolled environment, according to the Health Canada's Safety Code 6 and the Industry Canada Radio Standards Specification RSS-102 for General Population/Uncontrolled exposure.



2.4 EUT description details I

EUT Information : COCKPIT					
Manufacturer:	Intel				
Model:	INTEL COCKPIT GROUND CONTROL STATION				
EUT Type:	Professional Drone Remote Control				
Model:	INTEL COCKPIT GROUND CONTROL V0.96				
HW version:	0.95				
SW version:	0.793				
Serial number:	600				
Test Mode Settings:	EMC0.3 Software				
Power Supply: Battery Option:	Fully Charged Internal Power Packs (INTEL POWERPACK PP4000 14.8 V DC-4000mAh-59.2Wh)				
Comment:	Power Packs changed at regular time intervals (every 60 Min)				
Inte	grated Antenna Details				
Antenna Location:	Integrated				
Antenna Name:	Intel FA5 Antenna				
Antenna Hardware Version:	Antenna-002				
Antenna Details (For 5 GHz)	Intel FA5 Antenna ports 2 3 4 connected to VLMRX58G Modules RX TX RX connector respectively				
Antenna Type (For 5 GHz):	Circularly Polarized Patch Antenna				
Antenna Gain (For 5 GHz): (Port 3 TX Port)	8.02 dBi				
Antenna Details (For 2.4 GHz)	Intel FA5 Antenna's Port 1(Lower 2.4 GHz Port)				
Antenna Gain (For 2.4 GHz): (Port 1 Lower 2.4 GHz Port)	3.19 dBi				
Antenna Gain (For 2.4 GHz): (Port 5 Upper 2.4 GHz Port)	4.49 dBi				

Above mentioned EUT: COCKPIT will be certified as host device containing following FCC IDs & IC.

Parameter	2.4 GHz Modular Certification	5 GHz Modular Certification
Module Type:	RCM24G(Radio Control Module 2.4GHz)	VLMRX58G (Video Link Module Rx5.8GHz)
FCC ID	2AJ2A-RCM24G	2AJ2A-VLMR X58G
IC	1000B-RCM24G	1000B-VLMRX58G
ISED	1000B	1000B
PMN	RCM24G	VLMRX58G
UPN	RCM24G	VMRX58G
HVIN	D	AMN-PCB_183 REV 2.0
FVIN	RCM24G_12017USCN	4.2.2



HOST CERTIFICATION							
HMN (For Host device) Intel Cockpit Ground Control Station							
	Applicant Details						
	Applicant Name: Intel Corporation						
Address: 2200 Mission (College Boulevard						
Santa Clara, C	CA 95054, USA						
Contact: +1 408-765-808)						
	Manufacturer Details						
Manufacturer : Intel Deutschl	and GmbH						
Address: Konrad-Zuse-E							
82152 Krailling							
	Canada Representative Details						
HMN (For Host device)	Intel Cockpit Ground Control Station						
Applicant	Intel Canada Ltd.						
	ISED Company Number: 1000T						
	200 Ronson Drive, Ste 401, Toronto,						
	Ontario, Canada, M9W 5Z9						
Contact Name:	Flaine Mah						
Email:	Elaine.mah@intel.com						
Telephone No:	647-259-0114						
FAX:	647-259-0195						



2.5 EUT description details II (Area specific)

5 GHz Technical data of main EUT as declared by applicant (USA only)

Model	INTEL COCKPIT GROUND CONTROL STATION						
Model Type	INTEL COCKPIT GROUND CONTROL STATION V0.96						
FCC Filing Type:	Host Approval						
FCC ID	Contains 5 GHz Transmitter Module FCC-ID: 2AJ2A-VLMRX58G						
Main Function	Professional	Drone Wi	reless	Remote	Control		
Hardware Version	0.95						
Software Version	0.793						
	U-NII 1: (5150	D-5250MH	Hz)	5190 l	/IHz & 523	30 MHz	
Frequency Band Channels	U-NII2A: (525	50-5350M	IHz)	5270 N	/IHz & 5310) MHz	
(USA bands only)	U-NII 2C (547	70-5725M	Hz)	5510 N	/lHz, 5550	MHz, 5590 MHz, 5670 MHz	
	U-NII-3 (5725	5 -5850 M	Hz)	5755 N	1Hz & 5795	5 MHz	
Nominal Channel Bandwidth	40MHz						
Type of Modulations	BPSK, OFDM	1					
Antenna Connections	Integrated						
Antenna Details	Intel FA5 An						
Antenna Type	Monopole An GHz)	`		Circularly	Polarized	Patch Antenna(5GHz)	
Antenna Ports Number Type	5 Port 1 & GHz	5 Port 1 & Port 5: 2.4 Port 2 Port 3 Port 4: 5 GHz					
			Acc	ording to	Applicant'	s declaration	
	Frequency		Por	2 : RX	Port 3 :	Port 4 : RX	
5 GHz Antenna Ports	U-NII 1: (5 5250M		7.9	98 dBi	6.15 dBi	9.37 dBi	
Antenna Gain (Peak)	U-NII2A: (5350M		7.9	98 dBi	6.15 dBi	9.37 dBi	
	U-NII 2C (5725M		11.	08 dBi	8.02 dBi	11.18 dBi	
	U-NII-3 (572 MHz)		11.	08 dBi	8.02 dBi	11.18 dBi	
Total Number of Antennas	1 (Intel FA5	Antenna)					
Total Number of Modules	1 (5 GHz Tra	nsmitter	Modu	le FCC-	ID: 2AJ2A	-VLMRX58G)	
Max. Power Settings	+11 dBm (Using 11 dBm Power Scripts + EMC0.3 Software)						
Power Supply	DC power only: Total: 1 INTEL POWERPACK INTEL POWERPACK Type PP4000 Ratings: 14.8 V DC-4000mAh-59.2Wh						
Special EMI Components							
EUT Sample Type	Production	Pre-Production Engineering					
Firmware	for normal use Special version for test execution : EMC0.3 Software						
FCC label attached	Yes	No					



5 GHz Technical data of main EUT as declared by applicant (CANADA only)

Model	INTEL COCKPIT GROUND CONTROL STATION						
Model Type	INTEL COCK	INTEL COCKPIT GROUND CONTROL STATION V0.96					
ISED Filing Type:	Host Approv						
IC						DB-VLMRX58G	
Main Function	Professional I	Drone W	irele	ess Remote	Control		
Hardware Version	0.95						
Software Version	0.793						
	U-NII 1: 5150	-5250 MH	l z			nd Software Disabled*	
Frequency Band	U-NII2A: 5250	0-5350 N	1Hz	5310	MHz ***		
Channels	U-NII 2C: 547	'0-5600 N	ЛHz	<u>'</u>	MHz & 55	50 MHz**	
(Canada bands only)	U-NII 2C: 565	0-5725 N	ЛHz	5670	MHz**		
	U-NII 3: 5725	-5850 M	Hz	5755	MHz & 57	95 MHz	
Nominal Channel Bandwidth	40MHz						
Type of Modulations	BPSK, OFDM	1					
Antenna Connections	Integrated						
Antenna Details	Intel FA5 Ant	-					
Antenna Type	Monopole An GHz)	tenna (2.	4	Circularly	Polarized	Patch Antenna(5GHz)	
Antenna Ports Number Type	5 Port 1 & GHz	Port 5: 2	2.4	Port 2 P	ort 3 Port	4: 5 GHz	
	According to Applicant's declaration						
	Frequency Band		Port 2 : RX		Port 3 :	Port 4 : RX	
5 GHz Antenna Ports	U-NII 1: (5 5250MH	łz)) 7.98 081		6.15 dBi	9.37 dBi	
Antenna Gain (Peak)	U-NII2A: (5 5350MH	łz)	7	7.98 dBi	6.15 dBi	9.37 dBi	
(U-NII 2C (∜ 5725M⊦	łz)	1	1.08 dBi	8.02 dBi	11.18 dBi	
	U-NII-3 (572) MHz)	5 -5850	1	1.08 dBi	8.02 dBi	11.18 dBi	
Total Number of Antennas	1 (Intel FA5 A	Antenna)					
Total Number of Modules	1 (5 GHz Transmitter Module IC: 1000B-VLMRX58G)						
Max. Power Settings	+11 dBm (Using 11 dBm Power Scripts + EMC0.3 Software)						
Power Supply	DC power only: Total: 1 INTEL POWERPACK INTEL POWERPACK Type PP4000 Ratings: 14.8 V DC-4000mAh-59.2Wh						
EUT Sample Type	Production Pre-Production Engineering						
Firmware	for normal use	Special version for test execution : EMC0.3 Software					
ISED label attached	Yes	No					
					ation O Du		

^{*}For further details refer Applicants declaration & Product user manual.

This restriction is for the protection of Environment Canada's weather radars operating in this band.

^{**} Until further notice, devices subject to RSS-247, Issue 2,February 2017 section 6.2.3

Operating in Frequency bands 5470-5600 MHz and 5650-5725 MHz

shall not transmit in the band 5600-5650 MHz.

^{***} U-NII2A: Channel 5270 MHz Software Disabled refer Applicants declaration & Product user manual.



2.4 GHz Technical data of main EUT as declared by applicant (USA & CANADA)

Model	INTEL COCKPIT GROUND CONTROL STATION							
Model Type	INTEL COCKPIT GROUND CONTROL STATION V0.96							
FCC Filing Type:	Host Approval							
FCC ID	Contains 2.4 RCM24G	Contains 2.4 GHz Transmitter Module FCC-ID: 2AJ2A-RCM24G / IC: 1000B-RCM24G						
Main Function	Professional	Drone Wireles	s Remote Con	trol				
Hardware Version	0.95							
Software Version	0.793							
Frequency Band	2.4 GHz ISM	Band (2400-2	483.5 MHz)					
Frequency Channels (Range)	Channel 0: 2	402.5 MHz to	Channel 69: 2	2471.5 MHz				
Number of Channels	70 Frequenc	y Hopping Cl	nannels					
Nominal Channel Bandwidth	1 MHz							
	According to Applicant's declaration (Max. Typical Power Values)							
	Channel Range	Channel Power	Channel Range	Channel Power				
	Channel 0- 3	12 dBm	Channel 40-43	20 dBm				
	Channel 4- 7	13 dBm	Channel 44-48	19 dBm				
Channels Power	Channel 8- 10	14 dBm	Channel 49-52	18 dBm				
Settings	Channel 11-14	16 dBm	Channel 53-57	16 dBm				
	Channel 15-17	18 dBm	Channel 58-61	14 dBm				
	Channel 18-21	19 dBm	Channel 62-66	13 dBm				
	Channel 22-24	20 dBm	Channel 67-69	12 dBm				
	Channel 25-39	21 dBm						



Torres of Mandada Carre	MOLC (NATional	MOV (AT 1 OUT)					
Type of Modulations	MSK (Minir	MSK (Minimum Shift Keying)					
Supported Data Rates	50 Kbps 1	00 Kbps 250) Kb	ps 500 Kbps			
Antenna Connections	Integrated						
Antenna Details	Intel FA5 A	ntenna					
Antenna Type	Monopole A GHz)	Antenna (2.4	Cir	cularly Polarized Patch Antenna(5GHz)			
Antenna Ports Number Type	5 Port 1 5: 2.4	& Port GHz	Ро	rt 2 Port 3 Port 4: 5 GHz			
2.4 GHz Antenna Ports Antenna Gain (Peak)	Port 1: 3.19 dBi Port 5: 4.86 dBi (According to Applicant's declaration)						
Total Number of Antennas	1 (Intel FA	1 (Intel FA5 Antenna)					
Total Number of Modules	2 (2.4 GHz RCM24G)	2 (2.4 GHz Transmitter Module FCC-ID: 2AJ2A-RCM24G / IC: 1000B-RCM24G)					
Test Mode. Settings	EMC0.3 Sc	ftware					
Power Supply				TEL POWERPACK PP4000 Ratings: 14.8 V DC-4000mAh-59.2Wh			
Special EMI Components							
EUT Sample Type	Production Pre- Production			Engineering			
Firmware	for normal use	Special ver	Special version for test execution : EMC0.3 Software				
FCC /IC label attached	Yes	No	No				



3 Test standards/ procedures references

Test Standard	Version	Test Standard Description	
IEEE 1528-2013	2013-06	Recommended Practice for Determining the Peak Spatial- Average Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques	
RSS-102 Issue 5	2015-03	Radio Frequency Exposure Compliance of Radiocommuni- cation Apparatus (All Frequency Bands)	
Canada's Safety Code No. 6	2015-06	Limits of Human Exposure to Radiofrequency Electromagnetic Fields in the Frequency Range from 3 kHz to 300 GHz	
IEEE Std. C95-3	2002	IEEE Recommended Practice for the Measurement of Potentially Hazardous Electromagnetic Fields – RF and Microwave	
IEEE Std. C95-1	2005	IEEE Standard for Safety Levels with Respect to Human Exposure to Radio Frequency Electromagnetic Fields, 3 kHz to 300 GHz.	
IEC 62209-2	2010	Human exposure to radio frequency fields from hand-held and bodymounted wireless communication devices. Human models, instrumentation, and procedures. Procedure to determine the specific absorption rate (SAR) for wireless communication devices used in close proximity to the human body (frequency range of 30 MHz to 6 GHz)	
FCC KDBs:			
KDB 865664D01v01	August 7, 2015	FCC OET SAR measurement requirements 100 MHz to 6 GHz	
KDB 865664D02v01	October 23, 2015	RF Exposure Compliance Reporting and Documentation Considerations	
KDB 447498D01v06	October 23, 2015	Mobile and Portable Devices RF Exposure Procedures and Equipment Authorization Policies	
KDB 648474D04v01	October 23, 2015	SAR Evaluation Considerations for Wireless Handsets	



3.1 RF exposure limits

Human Exposure	Uncontrolled Environment General Population	Controlled Environment Occupational
Spatial Peak SAR* (Brain and Trunk)	1.60 mW/g	8.00 mW/g
Spatial Average SAR** (Whole Body)	0.08 mW/g	0.40 mW/g
Spatial Peak SAR*** (Hands/Feet/Ankle/Wrist)	4.00 mW/g	20.00 mW/g

Table 1: RF exposure limits

The limit applied in this test report is shown in bold letters

Notes:

- The Spatial Peak value of the SAR averaged over any 1 gram of tissue (defined as a tissue volume in the shape of a cube) and over the appropriate averaging time
- ** The Spatial Average value of the SAR averaged over the whole body.
- The Spatial Peak value of the SAR averaged over any 10 grams of tissue (defined as a tissue volume in the shape of a cube) and over the appropriate averaging time.

Uncontrolled Environments are defined as locations where there is the exposure of individuals who have no knowledge or control of their exposure.

Controlled Environments are defined as locations where there is exposure that may be incurred by persons who are aware of the potential for exposure, (i.e. as a result of employment or occupation).



4 Summary of Measurement Results

\boxtimes	No deviations from the technical specifications ascertained						
	Deviations from the technical specifications ascertained						
	Maximum SAR value reported for 1g (W/kg)						
		DTS	UNII				
body worr	n 0 mm distance	0.082 0.036					
collocated situations	ΣSAR evaluation		0.183				

5 Test Environment

Ambient temperature: $20 - 24 \, ^{\circ}\text{C}$ Tissue Simulating liquid: $20 - 24 \, ^{\circ}\text{C}$

Relative humidity content: 40 - 50 %

Air pressure: not relevant for this kind of testing

Power supply: 230 V / 50 Hz

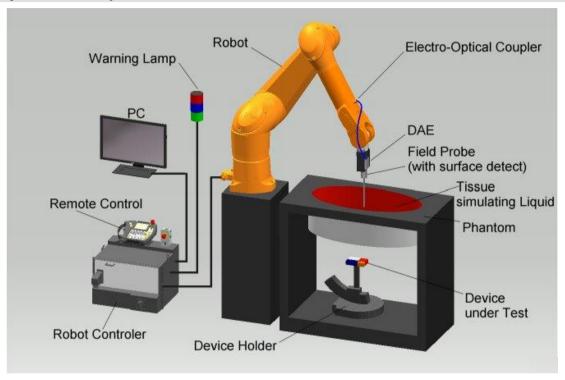
Exact temperature values for each test are shown in the table(s) under 7.1 and/or on the measurement plots.



6 Test Set-up

6.1 Measurement system

6.1.1 System Description



- The DASY system for performing compliance tests consists of the following items:
- A standard high precision 6-axis robot (Stäubli RX/TX family) with controller and software. An arm extension for accommodating the data acquisition electronics (DAE).
- A dosimetric probe, i.e. an isotropic E-field probe optimized and calibrated for usage in tissue simulating liquid.
- A data acquisition electronic (DAE) which performs the signal amplification, signal multiplexing, AD-conversion, offset measurements, mechanical surface detection, collision detection, etc. The unit is battery powered with standard or rechargeable batteries. The signal is optically transmitted to the EOC.
- The <u>Electro-Optical Coupler</u> (EOC) performs the conversion from the optical into a digital electric signal of the DAE. The EOC is connected to the DASY measurement server.
- The DASY measurement server, which performs all real-time data evaluation for field measurements and surface detection, controls robot movements and handles safety operation. A computer operating Windows 7.
- DASY software and SEMCAD data evaluation software.
- Remote control with teach panel and additional circuitry for robot safety such as warning lamps, etc.
- The generic twin phantom enabling the testing of left-hand and right-hand usage.
- The triple flat and eli phantom for the testing of handheld and body-mounted wireless devices.
- The device holder for handheld mobile phones and mounting device adaptor for laptops
- Tissue simulating liquid mixed according to the given recipes.
- System check dipoles allowing to validate the proper functioning of the system.



6.1.2 Test environment

The DASY measurement system is placed in a laboratory room within an environment which avoids influence on SAR measurements by ambient electromagnetic fields and any reflection from the environment. The pictures at the beginning of the photo documentation show a complete view of the test environment. The system allows the measurement of SAR values larger than 0.005 mW/g.

6.1.3 Probe description

Isotropic E-Fi	Isotropic E-Field Probe EX3DV4 for Dosimetric Measurements								
Tec	hnical data according to manufacturer information								
Construction	Symmetrical design with triangular core								
	Interleaved sensors								
	Built-in shielding against static charges								
	PEEK enclosure material (resistant to organic solvents, e.g.,								
	DGBE)								
Calibration	ISO/IEC 17025 calibration service available.								
Frequency	10 MHz to >6 GHz (dosimetry); Linearity: ± 0.2 dB (30 MHz to								
	6 GHz)								
Directivity	± 0.3 dB in HSL (rotation around probe axis)								
	± 0.5 dB in tissue material (rotation normal to probe axis)								
Dynamic range	10 μW/g to > 100 mW/g; Linearity: ± 0.2 dB (noise: typically<1								
	μW/g)								
Dimensions	Overall length: 337 mm (Tip: 20mm)								
	Tip length: 2.5 mm (Body: 12mm)								
	Typical distance from probe tip to dipole centers: 1mm								
Application	High precision dosimetric measurements in any exposure								
	scenario (e.g., very strong gradient fields). Only probe which								
	enables compliance testing for frequencies up to 6 GHz with								
	precision of better 30%.								



6.1.1 Phantom description

The used ELI4 Phantom meets the requirements specified in KDB865664 D01 for Specific Absorption Rate (SAR) measurements. The phantom consists of a fibreglass shell integrated in a wooden table.



The ELI4 phantom is intended for compliance testing of handheld and body-mounted wireless devices in the frequency range of 30MHz to 6 GHz. ELI4 is fully compatible with the standard IEC 62209-2 and all known tissue simulating liquids.

6.1.2 Device holder description

The DASY device holder has two scales for device rotation (with respect to the body axis) and the device inclination (with respect to the line between the ear openings). The plane between the ear openings and the mouth tip has a rotation angle of 65°. The bottom plate contains three pair of bolts for locking the device holder. The device holder positions are adjusted to the standard measurement positions in the three sections. This device holder is used for standard mobile phones or PDA's only. If necessary an additional support of polystyrene material is used.



Larger DUT's (e.g. notebooks) cannot be tested using this device holder. Instead a support of bigger polystyrene cubes and thin polystyrene plates is used to position the DUT in all relevant positions to find and measure spots with maximum SAR values.

Therefore those devices are normally only tested at the flat part of the SAM.



6.1.3 Scanning procedure

- The DASY installation includes predefined files with recommended procedures for measurements and system check. They are read-only document files and destined as fully defined but unmeasured masks. All test positions (head or body-worn) are tested with the same configuration of test steps differing only in the grid definition for the different test positions.
- The "reference" and "drift" measurements are located at the beginning and end of the batch process. They measure the field drift at one single point in the liquid over the complete procedure. The indicated drift is mainly the variation of the DUT's output power and should vary max. +/- 5 %.
- The highest integrated SAR value is the main concern in compliance test applications. These values can mostly be found at the inner surface of the phantom and cannot be measured directly due to the sensor offset in the probe. To extrapolate the surface values, the measurement distances to the surface must be known accurately. A distance error of 0.5mm could produce SAR errors of 6% at 1800 MHz. Using predefined locations for measurements is not accurate enough. Any shift of the phantom (e.g., slight deformations after filling it with liquid) would produce high uncertainties. For an automatic and accurate detection of the phantom surface, the DASY5 system uses the mechanical surface detection. The detection is always at touch, but the probe will move backward from the surface the indicated distance before starting the measurement.
- The "area scan" measures the SAR above the DUT or verification dipole on a parallel plane to the surface. It is used to locate the approximate location of the peak SAR with 2D spline interpolation. The robot performs a stepped movement along one grid axis while the local electrical field strength is measured by the probe. The probe is touching the surface of the SAM during acquisition of measurement values. The scan uses different grid spacings for different frequency measurements. Standard grid spacing for head measurements in frequency ranges ≤ 2GHz is 15 mm in x- and y- dimension. For higher frequencies a finer resolution is needed, thus for the grid spacing is reduced according the following table:

Area scan grid spacing	for different frequency ranges
Frequency range	Grid spacing
≤ 2 GHz	≤ 15 mm
2 – 4 GHz	≤ 12 mm
4 – 6 GHz	≤ 10 mm

Grid spacing and orientation have no influence on the SAR result. For special applications where the standard scan method does not find the peak SAR within the grid, e.g. mobile phones with flip cover, the grid can be adapted in orientation. Results of this coarse scan are shown in annex B.

• A "zoom scan" measures the field in a volume around the 2D peak SAR value acquired in the previous "coarse" scan. It uses a fine meshed grid where the robot moves the probe in steps along all the 3 axis (x, y and z-axis) starting at the bottom of the Phantom. The grid spacing for the cube measurement is varied according to the measured frequency range, the dimensions are given in the following table:

Zooi	m scan grid spacing and	volume for different fre	quency ranges
Frequency range	Grid spacing for x, y axis	Grid spacing for z axis	Minimum zoom scan volume
≤ 2 GHz	≤ 8 mm	≤ 5 mm	≥ 30 mm
2 – 3 GHz	≤ 5 mm*	≤ 5 mm	≥ 28 mm
3 – 4 GHz	≤ 5 mm*	≤ 4 mm	≥ 28 mm
4 – 5 GHz	≤ 4 mm*	≤ 3 mm	≥ 25 mm
5 – 6 GHz	≤ 4 mm*	≤ 2 mm	≥ 22 mm

^{*} When zoom scan is required and the reported SAR from the area scan based 1-g SAR estimation procedures of KDB Publication 447498 is \leq 1.4 W/kg, \leq 8 mm, \leq 7 mm and \leq 5 mm zoom scan resolution may be applied, respectively, for 2 GHz to 3 GHz, 3 GHz to 4 GHz and 4 GHz to 6 GHz.

DASY is also able to perform repeated zoom scans if more than 1 peak is found during area scan. In this document, the evaluated peak 1g and 10g averaged SAR values are shown in the 2D-graphics in annex B. Test results relevant for the specified standard (see section 3) are shown in table form in section 7.



6.1.4 Spatial Peak SAR Evaluation

The spatial peak SAR - value for 1 and 10 g is evaluated after the Cube measurements have been done. The basis of the evaluation are the SAR values measured at the points of the fine cube grid consisting of all points in the three directions x, y and z. The algorithm that finds the maximal averaged volume is separated into three different stages.

- The data between the dipole center of the probe and the surface of the phantom are extrapolated. This data cannot be measured since the center of the dipole is 1 to 2.7 mm away from the tip of the probe and the distance between the surface and the lowest measuring point is about 1 mm (see probe calibration sheet). The extrapolated data from a cube measurement can be visualized by selecting 'Graph Evaluated'.
- The maximum interpolated value is searched with a straight-forward algorithm. Around this maximum the SAR - values averaged over the spatial volumes (1g or 10 g) are computed using the 3d-spline interpolation algorithm. If the volume cannot be evaluated (i.e., if a part of the grid was cut off by the boundary of the measurement area) the evaluation will be started on the corners of the bottom plane of the cube.
- All neighbouring volumes are evaluated until no neighbouring volume with a higher average value is found.

Extrapolation

The extrapolation is based on a least square algorithm [W. Gander, Computermathematik, p.168-180]. Through the points in the first 3 cm along the z-axis, polynomials of order four are calculated. These polynomials are then used to evaluate the points between the surface and the probe tip. The points, calculated from the surface, have a distance of 1 mm from each other.

Interpolation

The interpolation of the points is done with a 3d-Spline. The 3d-Spline is composed of three one-dimensional splines with the "Not a knot"-condition [W. Gander, Computermathematik, p.141-150] (x, y and z -direction) [Numerical Recipes in C, Second Edition, p.123ff].

Volume Averaging

At First the size of the cube is calculated. Then the volume is integrated with the trapezoidal algorithm. 8000 points (20x20x20) are interpolated to calculate the average.

Advanced Extrapolation

DASY uses the advanced extrapolation option which is able to compensate boundary effects on E-field probes.



6.1.5 Data Storage and Evaluation

Data Storage

The DASY software stores the acquired data from the data acquisition electronics as raw data (in microvolt readings from the probe sensors), together with all necessary software parameters for the data evaluation (probe calibration data, liquid parameters and device frequency and modulation data) in measurement files with the extension ".DA4", ".DA5x". The software evaluates the desired unit and format for output each time the data is visualized or exported. This allows verification of the complete software setup even after the measurement and allows correction of incorrect parameter settings. For example, if a measurement has been performed with a wrong crest factor parameter in the device setup, the parameter can be corrected afterwards and the data can be re-evaluated.

The measured data can be visualized or exported in different units or formats, depending on the selected probe type ([V/m], [A/m], [°C], [mW/g], [mW/cm²], [dBrel], etc.). Some of these units are not available in certain situations or show meaningless results, e.g., a SAR output in a lossless media will always be zero. Raw data can also be exported to perform the evaluation with other software packages.

Data Evaluation by SEMCAD

The SEMCAD software automatically executes the following procedures to calculate the field units from the microvolt readings at the probe connector. The parameters used in the evaluation are stored in the configuration modules of the software:

Probe parameters: - Sensitivity Normi, aio, ai1, ai2

Conversion factor
 Diode compression point
 ConvF_i
 Dcpi

Device parameters: - Frequency f

 $\begin{array}{ccc} & - \operatorname{Crest} \ \operatorname{factor} & \operatorname{cf} \\ \operatorname{Media} \ \operatorname{parameters:} & - \operatorname{Conductivity} & \sigma \end{array}$

- Density ho

These parameters must be set correctly in the software. They can be found in the component documents or they can be imported into the software from the configuration files issued for the DASY components. In the direct measuring mode of the multimeter option, the parameters of the actual system setup are used. In the scan visualization and export modes, the parameters stored in the corresponding document files are used.

The first step of the evaluation is a linearization of the filtered input signal to account for the compression characteristics of the detector diode. The compensation depends on the input signal, the diode type and the DC-transmission factor from the diode to the evaluation electronics.

If the exciting field is pulsed, the crest factor of the signal must be known to correctly compensate for peak power. The formula for each channel can be given as:

$$V_i = U_i + U_i^2 \cdot cf/dcp_i$$

with V_i = compensated signal of channel i (i = x, y, z)

 U_i = input signal of channel i (i = x, y, z)

cf = crest factor of exciting field (DASY parameter) dcp_i = diode compression point (DASY parameter)

From the compensated input signals the primary field data for each channel can be evaluated:

E-field probes: $E_i = (V_i / Norm_i \cdot ConvF)^{1/2}$

H-field probes: $H_i = (V_i)^{1/2} \cdot (a_{i0} + a_{i1}f + a_{i2}f^2)/f$

with V_i = compensated signal of channel i (i = x, y, z)

Norm_i = sensor sensitivity of channel i (i = x, y, z)

 $[mV/(V/m)^2]$ for E-field Probes ConvF = sensitivity enhancement in solution

a_{ij} = sensor sensitivity factors for H-field probes

f = carrier frequency [GHz]

E_i = electric field strength of channel i in V/m H_i = magnetic field strength of channel i in A/m

The RSS value of the field components gives the total field strength (Hermitian magnitude):

$$E_{tot} = (E_x^2 + E_y^2 + E_z^2)^{1/2}$$

The primary field data are used to calculate the derived field units.

$$SAR = (E_{tot}^2 \cdot \sigma) / (\rho \cdot 1000)$$

with SAR = local specific absorption rate in mW/g

 E_{tot} = total field strength in V/m

 σ = conductivity in [mho/m] or [Siemens/m] ρ = equivalent tissue density in g/cm³

Note that the density is normally set to 1 (or 1.06), to account for actual brain density rather than the density of the simulation liquid. The power flow density is calculated assuming the excitation field to be a free space field.

$$P_{pwe} = E_{tot}^2 / 3770$$
 or $P_{pwe} = H_{tot}^2 \cdot 37.7$

with P_{pwe} = equivalent power density of a plane wave in mW/cm²

E_{tot} = total electric field strength in V/m
H_{tot} = total magnetic field strength in A/m



6.1.6 Tissue simulating liquids: dielectric properties

The following materials are used for producing the tissue-equivalent materials.

(Liquids used for tests described in section 7. are marked with \boxtimes):

Ingredients (% of weight)		Frequency (MHz)												
frequency band	☐ 4 50	☐ 7 50	□ 835	900	<u> </u>	<u> </u>	<u> </u>	⊠ 2450	⊠ 5000					
Water	51.16	51.7	52.4	56.0	71.40	71.45	71.56	71.65	64 - 78					
Salt (NaCl)	1.49	0.9	1.40	0.76	0.55	0.5	0.39	0.3	2 - 3					
Sugar	46.78	47.2	45.0	41.76	0.0	0.0	0.0	0.0	0.0					
HEC	0.52	0.0	1.0	1.21	0.0	0.0	0.0	0.0	0.0					
Bactericide	0.05	0.1	0.1	0.27	0.1	0.1	0.1	0.1	0.0					
Tween 20	0.0	0.0	0.0	0.0	27.95	27.95	27.95	27.95	0.0					
Emulsifiers	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	9 - 15					
Mineral Oil	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	11 - 18					

Table 2: Body tissue dielectric properties

Salt: 99+% Pure Sodium Chloride Water: De-ionized, $16M\Omega$ + resistivity

Sugar: 98+% Pure Sucrose HEC: Hydroxyethyl Cellulose

Tween 20: Polyoxyethylene (20) sorbitan monolaurate

6.1.7 Tissue simulating liquids: parameters

Liquid	Frag	Target b	ody tissue	N	/leasurem	ent body	tissue		Magaurament
Liquid MSL	Freq. (MHz)	Permittivity	Conductivity	Permittivity	Dev.	Condu	ıctivity	Dev.	Measurement date
IVIOL	(1011 12)	Ferritaivity	(S/m)	Ferrilliuvity	Dev.	٤"	(S/m)	Dev.	uale
2450	2402	52.76	1.90	51.8	-1.8%	14.51	1.94	1.8%	2017-03-16
	2437	52.72	1.94	51.6	-2.0%	14.62	1.98	2.3%	
	2450	52.70	1.95	51.7	-2.0%	14.68	2.00	2.6%	
	2472	52.67	1.98	51.6	-2.1%	14.74	2.03	2.3%	
5GHz	5200	49.01	5.30	48.0	-2.0%	18.71	5.41	2.1%	2017-03-16
	5230	48.97	5.33	47.8	-2.4%	18.65	5.43	1.7%	
	5310	48.87	5.43	47.8	-2.2%	18.90	5.58	2.8%	
	5500	48.61	5.65	47.2	-2.9%	18.98	5.81	2.8%	
	5670	48.38	5.85	47.1	-2.6%	19.13	6.03	3.2%	
	5795	48.21	5.99	46.9	-2.8%	19.01	6.13	2.2%	
	5800	48.20	6.00	46.9	-2.8%	18.93	6.11	1.8%	

Table 3: Parameter of the body tissue simulating liquid

Note: The dielectric properties have been measured using the contact probe method at 22°C.



6.1.8 Measurement uncertainty evaluation for SAR test

DASY5 Uncertainty Budget										
According to IEEE		_	_		MHz - 3	B GHz rang	e			
Source of	certainty Valu	Probability	Divisor	Ci	Ci	Standar	d Uncertainty	v _i ² or		
uncertainty	± %	Distribution		(1g)	(10g)	± %, (1g)	± %, (10g)	V _{eff}		
Measurement System										
Probe calibration	± 6.0 %	Normal	1	1	1	± 6.0 %	± 6.0 %	∞		
Axial isotropy	± 4.7 %	Rectangular	√ 3	0.7	0.7	± 1.9 %	± 1.9 %	∞		
Hemispherical isotropy	± 9.6 %	Rectangular	√ 3	0.7	0.7	± 3.9 %	± 3.9 %	∞		
Boundary effects	± 1.0 %	Rectangular	√ 3	1	1	± 0.6 %	± 0.6 %	∞		
Probe linearity	± 4.7 %	Rectangular	√3	1	1	± 2.7 %	± 2.7 %	8		
System detection limits	± 1.0 %	Rectangular	√3	1	1	± 0.6 %	± 0.6 %	8		
Readout electronics	± 0.3 %	Normal	1	1	1	± 0.3 %	± 0.3 %	8		
Response time	± 0.8 %	Rectangular	√ 3	1	1	± 0.5 %	± 0.5 %	8		
Integration time	± 2.6 %	Rectangular	√ 3	1	1	± 1.5 %	± 1.5 %	8		
RF ambient noise	± 3.0 %	Rectangular	√ 3	1	1	± 1.7 %	± 1.7 %	∞		
RF ambient reflections	± 3.0 %	Rectangular	√3	1	1	± 1.7 %	± 1.7 %	8		
Probe positioner	± 0.4 %	Rectangular	√3	1	1	± 0.2 %	± 0.2 %	8		
Probe positioning	± 2.9 %	Rectangular	√ 3	1	1	± 1.7 %	± 1.7 %	8		
Max.SAR evaluation	± 1.0 %	Rectangular	√ 3	1	1	± 0.6 %	± 0.6 %	8		
Test Sample Related										
Device positioning	± 2.9 %	Normal	1	1	1	± 2.9 %		145		
Device holder uncertainty	± 3.6 %	Normal	1	1	1	± 3.6 %	± 3.6 %	5		
Power drift	± 5.0 %	Rectangular	√ 3	1	1	± 2.9 %	± 2.9 %	∞		
Phantom and Set-up										
Phantom uncertainty	± 4.0 %	Rectangular	√ 3	1	1	± 2.3 %	± 2.3 %	∞		
Liquid conductivity (target)	± 5.0 %	Rectangular	√ 3	0.64	0.43	± 1.8 %		∞		
Liquid conductivity (meas.)	± 5.0 %	Rectangular	√ 3	0.64	0.43	± 1.8 %	± 1.2 %	8		
Liquid permittivity (target)	± 5.0 %	Rectangular	√3	0.6	0.49	± 1.7 %		∞		
Liquid permittivity (meas.)	± 5.0 %	Rectangular	√3	0.6	0.49	± 1.7 %	± 1.4 %	8		
Combined Std.						± 11.1 %	± 10.8 %	387		
Expanded Std.						± 22.1 %	± 21.6 %			

Table 4: Measurement uncertainties

Worst-Case uncertainty budget for DASY5 assessed according to IEEE 1528/2003.

The budget is valid for 2G and 3G communication signals and frequency range 300MHz - 3 GHz.

For these conditions it represents a worst-case analysis. For specific tests and configurations, the uncertainty could be considerable smaller.



Relative DASY5 Uncertainty Budget for SAR Tests According to IEEE 1528/2013 and IEC62209/2011 for the 0.3 - 3GHz range certainty Valu Standard Uncertainty Divisor Ci v² or Probability **Error Description** Distribution ± % (1g)(10q)± %, (1g) ± %, (10g) V_{eff} Measurement System Probe calibration ± 6.0 % Normal 1 6.0 % 6.0 % 1 1 ± ± Axial isotropy ± 4.7 % Rectangular √3 0.7 0.7 1.9 % 1.9 % 00 ± Hemispherical isotropy √3 0.7 ± 9.6 % Rectangular 0.7 3.9 % 3.9 % ± ± 0.6 % Boundary effects Rectangular √ 3 0.6 % ± 1.0 % 1 1 ∞ ± Probe linearity 2.7 % ± 4.7 % Rectangular √|3 1 1 ± 2.7 % ± ∞ System detection limits ± 1.0 % Rectangular √ 3 1 1 0.6 % 0.6 % ∞ ± ± ± 2.4 √|3 1 1 1.4 % 1.4 % Modulation Response % Rectangular ∞ ± ± 0.3 % Readout electronics ± 0.3 % Normal 1 1 1 0.3 % ± ± √3 0.5 % 0.5 % Response time ± 0.8 % Rectangular 1 1 ∞ ± ± Integration time ± 2.6 % Rectangular √3 1 1.5 % 1.5 % 1 ± ± ∞ RF ambient noise ± 3.0 % Rectangular √ 3 1 1 1.7 % 1.7 % ∞ ± ± 1 √3 1 1.7 % RF ambient reflections ± 3.0 % Rectangular 1.7 % ∞ ± ± Probe positioner ± 0.4 % Rectangular √ 3 1 1 0.2 % 0.2 % ∞ ± ± Probe positioning ± 2.9 % Rectangular √ 3 1 1 1.7 % 1.7 % ∞ ± ± Max. SAR evaluation ± 2.0 % Rectangular √ 3 1 1 1.2 % 1.2 % ∞ ± **Test Sample Related** Device positioning ± 2.9 % Normal 1 1 1 2.9 % 2.9 % 145 ± ± ± 3.6 % Device holder uncertainty Normal 1 3.6 % 3.6 % 1 1 5 ± ± Rectangular √3 Power drift ± 5.0 % 1 1 2.9 % 2.9 % ± ± ∞ **Phantom and Set-up** Phantom uncertainty % Rectangular √3 1 3.5 % 3.5 % ± 6.1 ± ± SAR correction ± 1.9 % Rectangular √|3 1 0.84 1.1 % 0.9 % ± ± Liquid conductivity (meas.) ± 5.0 % Rectangular √ 3 0.78 0.71 2.3 % 2.0 % ∞ ± ± Liquid permittivity (meas.) Rectangular √ 3 0.8 % ± 5.0 % 0.26 0.26 0.8 % ± ± √ 3 Temp. Unc. - Conductivity ± 3.4 % 1.5 % 1.4 % Rectangular 0.78 0.71 ∞ ± ± 0.26 0.1 % Temp. Unc. - Permittivity ± 0.4 % Rectangular √ 3 0.23 0.1 % ± ± **Combined Uncertainty** ± 11.3 % ± 11.3 % 330 Expanded Std. ± 22.7 % ± 22.5 % **Uncertainty**

Table 5: Measurement uncertainties

Worst-Case uncertainty budget for DASY5 assessed according to IEEE 1528/2013

and IEC 62209-1/2011 standards. The budget is valid for the frequency range 300MHz -3 GHz and represents a worst-case analysis. For specific tests and configurations, the uncertainty could be considerable smaller.



		DVG	VE I	Uncertainty	, Buda	of						
According				2/2010 for the	_		CU= #		•			
According	LOIE	C 62	209-		Divisor					l I In	certainty	, _
Source of	Un	certa	inty	Probability	DIVISOI	Ci	Ci	,	Stariuarc		certairity	v _i ² or
uncertainty		Value		Distribution		(1g)	(10g)	± 9	%, (1g)	± %	%, (10g)	V _{eff}
Measurement System												
Probe calibration	±	6.6	%	Normal	1	1	1	±	6.6 %	±	6.6 %	
Axial isotropy	±	4.7	%	Rectangular	√ 3	0.7	0.7	±	1.9 %	±	1.9 %	∞
Hemispherical isotropy	±	9.6	%	Rectangular	√3	0.7	0.7	H	3.9 %	±	3.9 %	∞
Boundary effects	±	2.0	%	Rectangular	√3	1	1	H	1.2 %	±	1.2 %	∞
Probe linearity	±	4.7	%	Rectangular	√ 3	1	1	±	2.7 %	±	2.7 %	∞
System detection limits	±	1.0	%	Rectangular	√ 3	1	1	H	0.6 %	±	0.6 %	∞
Modulation Response	±	2.4	%	Rectangular	√ 3	1	1	H	1.4 %	±	1.4 %	∞
Readout electronics	±	0.3	%	Normal	1	1	1	H	0.3 %	±	0.3 %	8
Response time	±	8.0	%	Rectangular	√ 3	1	1	±	0.5 %	±	0.5 %	∞
Integration time	±	2.6	%	Rectangular	√3	1	1	H	1.5 %	±	1.5 %	∞
RF ambient noise	±	3.0	%	Rectangular	√3	1	1	±	1.7 %	±	1.7 %	∞
RF ambient reflections	±	3.0	%	Rectangular	√3	1	1	H	1.7 %	±	1.7 %	∞
Probe positioner	±	8.0	%	Rectangular	√ 3	1	1	H	0.5 %	±	0.5 %	∞
Probe positioning	±	6.7	%	Rectangular	√ 3	1	1	±	3.9 %	±	3.9 %	8
Post-processing	±	4.0	%	Rectangular	√ 3	1	1	H	2.3 %	±	2.3 %	8
Test Sample Related												
Device positioning	±	2.9	%	Normal	1	1	1	±	2.9 %	±	2.9 %	145
Device holder uncertainty	±	3.6	%	Normal	1	1	1	±	3.6 %	±	3.6 %	5
Power drift	±	5.0	%	Rectangular	√3	1	1	±	2.9 %	±	2.9 %	∞
Phantom and Set-up												
Phantom uncertainty	±	7.9	%	Rectangular	√ 3	1	1	±	4.6 %	±	4.6 %	∞
SAR correction	±	1.9	%	Rectangular	√ 3	1	0.84	±	1.1 %	±	0.9 %	∞
Liquid conductivity (meas.)	±	5.0	%	Rectangular	√ 3	0.78	0.71	Ħ	2.3 %	±	2.0 %	∞
Liquid permittivity (meas.)	±	5.0	%	Rectangular	√3	0.26	0.26	H	0.8 %	±	0.8 %	∞
Temp. Unc Conductivity	±	3.4	%	Rectangular	√3	0.78	0.71	±	1.5 %	±	1.4 %	∞
Temp. Unc Permittivity	±	0.4	%	Rectangular	√ 3	0.23	0.26	±	0.1 %	±	0.1 %	
Combined Uncertainty								±	12.7 %	±	12.6 %	330
Expanded Std.									25 4 9/		25 2 9/	
Uncertainty								±	25.4 %	±	25.3 %	
Table 6: Measurement uncert	ainti	00										

Table 6: Measurement uncertainties.

Worst-Case uncertainty budget for DASY5 assessed according to according to IEC 62209-2/2010 standard. The budget is valid for the frequency range 300MHz - 6 GHz and represents a worst-case analysis. For specific tests and configurations, the uncertainty could be considerable smaller.



Probe calibration	Polat	ivo DASV5	Uncortaint	, Rude	not fo	r SAD	Toete		
Probability Value								_	
Measurement System	According	to IEEE 1528	72003 and IEC		-1 tor t				
Measurement System		Uncertainty	Probability	Divisor	Ci	Ci	Standard	Uncertainty	v _i ² or
Probe calibration	Error Description	1	•		(1g)	(10g)	± %, (1g)	± %, (10g)	•
Axial isotropy	Measurement System								
Hemispherical isotropy	Probe calibration	± 6.6 %	Normal	1	1	1	± 6.6 %	± 6.6 %	8
Boundary effects	Axial isotropy	± 4.7 %	Rectangular	√ 3	0.7	0.7	± 1.9 %	± 1.9 %	8
Probe linearity	Hemispherical isotropy	± 9.6 %	Rectangular		0.7	0.7			8
System detection limits ± 1.0 % Rectangular √ 3 1 1 ± 0.6 % ± 0.6 % ∞ Readout electronics ± 0.3 % Normal 1 1 1 1 ± 0.3 % ± 0.3 % ∞ Response time ± 0.8 % Rectangular √ 3 1 1 ± 0.5 % ± 0.5 % ∞ Integration time ± 2.6 % Rectangular √ 3 1 1 ± 1.5 % ± 1.5 % ∞ RF ambient noise ± 3.0 % Rectangular √ 3 1 1 ± 1.7 % ± 1.7 % ± 1.7 % ± 1.7 % ± 1.7 % ± 1.7 % ± 1.7 % ±	Boundary effects	± 2.0 %	Rectangular	√ 3	1	1	± 1.2 %	± 1.2 %	8
Readout electronics ± 0.3 % Normal 1 1 1 1 ± 0.3 % ± 0.3 % ∞ Response time ± 0.8 % Rectangular √ 3 1 1 ± 0.5 % ± 0.5 % ∞ Integration time ± 2.6 % Rectangular √ 3 1 1 ± 1.5 % ± 1.5 % ∞ RF ambient noise ± 3.0 % Rectangular √ 3 1 1 ± 1.7 % ± 1.7 % ± 1.7 % ∞ RF ambient reflections ± 3.0 % Rectangular √ 3 1 1 ± 1.7 % ± 1.7 % ± 1.7 % ∞ Probe positioner ± 0.8 % Rectangular √ 3 1 1 ± 0.5 % ± 0.5 % ± 0.5 % ∞ Probe positioning ± 6.7 % Rectangular √ 3 1 1 ± 0.5 % ± 0.5 % ± 0.5 % ∞ Max SAR evaluation ± 4.0 % Rectangular √ 3 1 1 ± 0.5 % ± 0.5 % ± 0.5 % ∞ Test Sample Related Device positioning ± 2.9 % Normal 1 1 1 ± 0.5 % ± 0.5 % ± 0.5 % ∞ Device positioning ± 2.9 % Normal 1 1 1 ± 0.5 % ± 0.5 % ± 0.5 % ∞ Power drift ± 5.0 % Rectangular √ 3 1 1 ± 0.5 % ± 0.5 % ± 0.5 % ∞ Phantom and Set-up Phantom uncertainty ± 4.0 % Rectangular √ 3 1 1 ± 0.5 % ± 0.5 % ± 0.5 % ∞ Phantom uncertainty ± 4.0 % Rectangular √ 3 0.64 0.43 ± 1.8 % ± 1.2 % ∞ Liquid conductivity (target) ± 5.0 % Rectangular √ 3 0.64 0.49 ± 1.7 % ± 1.4 % ∞ <	Probe linearity	± 4.7 %	Rectangular	√ 3	1	1	± 2.7 %	± 2.7 %	8
Response time	System detection limits	± 1.0 %	Rectangular	√ 3	1	1	± 0.6 %	± 0.6 %	8
Integration time	Readout electronics	± 0.3 %	Normal		1	1	± 0.3 %	± 0.3 %	∞
RF ambient noise	Response time	± 0.8 %	Rectangular		1	1	± 0.5 %	± 0.5 %	∞
RF ambient reflections	Integration time	± 2.6 %	Rectangular	√ 3	1	1	± 1.5 %	± 1.5 %	8
Probe positioner	RF ambient noise	± 3.0 %	Rectangular	√3	1	1	± 1.7 %	± 1.7 %	8
Probe positioning	RF ambient reflections	± 3.0 %	Rectangular	√ 3	1	1	± 1.7 %	± 1.7 %	∞
Max. SAR evaluation ± 4.0 % Rectangular √ 3 1 1 ± 2.3 % ± 2.3 % ± 2.3 % ± 2.3 % ± 2.3 % ± 2.3 % ± 2.3 % ± 2.9 % 145 Device holder uncertainty ± 3.6 % Normal 1 1 1 1 ± 3.6 % ± 3.6 % 5 Power drift ± 5.0 % Rectangular √ 3 1 1 ± 2.9 % ± 2.9 % ∞ Phantom and Set-up **	Probe positioner	± 0.8 %	Rectangular	√ 3	1	1	± 0.5 %	± 0.5 %	8
Test Sample Related Device positioning	Probe positioning	± 6.7 %	Rectangular	√ 3	1	1	± 3.9 %	± 3.9 %	8
Device positioning ± 2.9 % Normal 1 1 1 ± 2.9 % ± 2.9 % 145 Device holder uncertainty ± 3.6 % Normal 1 1 1 ± 3.6 % ± 3.6 % 5 Power drift ± 5.0 % Rectangular √ 3 1 1 ± 2.9 % ± 2.9 % ∞ Phantom and Set-up Phantom uncertainty ± 4.0 % Rectangular √ 3 1 1 ± 2.3 % ± 2.3 % ∞ Liquid conductivity (target) ± 5.0 % Rectangular √ 3 0.64 0.43 ± 1.8 % ± 1.2 % ∞ Liquid permittivity (meas.) ± 5.0 % Rectangular √ 3 0.6 0.49 ± 1.7 % ± 1.4 % ∞ Liquid permittivity (meas.) ± 5.0 % Rectangular √ 3 0.6 0.49 ± 1.7 % ± 1.4 % ∞ Combined Uncertainty ± 12.1 % ± 11.9 % 330 Expanded Std. ± 2.3 % + 23.8 %	Max. SAR evaluation	± 4.0 %	Rectangular	√ 3	1	1	± 2.3 %	± 2.3 %	∞
Device holder uncertainty $\pm 3.6 \%$ Normal 1 1 1 1 $\pm 3.6 \%$ $\pm 3.6 \%$ 5 Power drift $\pm 5.0 \%$ Rectangular $\sqrt{3}$ 1 1 $\pm 2.9 \%$ $\pm 2.9 \%$ ∞ Phantom and Set-up Phantom uncertainty $\pm 4.0 \%$ Rectangular $\sqrt{3}$ 1 1 $\pm 2.3 \%$ $\pm 2.3 \%$ ∞ Liquid conductivity (target) $\pm 5.0 \%$ Rectangular $\sqrt{3}$ 0.64 0.43 $\pm 1.8 \%$ $\pm 1.2 \%$ ∞ Liquid conductivity (meas.) $\pm 5.0 \%$ Rectangular $\sqrt{3}$ 0.64 0.43 $\pm 1.8 \%$ $\pm 1.2 \%$ ∞ Liquid permittivity (target) $\pm 5.0 \%$ Rectangular $\sqrt{3}$ 0.66 0.49 $\pm 1.7 \%$ $\pm 1.4 \%$ ∞ Liquid permittivity (meas.) $\pm 5.0 \%$ Rectangular $\sqrt{3}$ 0.6 0.49 $\pm 1.7 \%$ $\pm 1.4 \%$ ∞ Liquid permittivity (meas.) $\pm 5.0 \%$ Rectangular $\sqrt{3}$ 0.6 0.49 $\pm 1.7 \%$ $\pm 1.4 \%$ ∞ Combined Uncertainty $\pm 1.1 \%$	Test Sample Related								
Phantom and Set-up Phantom uncertainty ± 4.0 % Rectangular √ 3 1 1 ± 2.9 % ± 2.9 % ∞ Phantom uncertainty ± 4.0 % Rectangular √ 3 1 1 ± 2.3 % ± 2.3 % ∞ Liquid conductivity (target) ± 5.0 % Rectangular √ 3 0.64 0.43 ± 1.8 % ± 1.2 % ∞ Liquid conductivity (meas.) ± 5.0 % Rectangular √ 3 0.64 0.43 ± 1.8 % ± 1.2 % ∞ Liquid permittivity (target) ± 5.0 % Rectangular √ 3 0.6 0.49 ± 1.7 % ± 1.4 % ∞ Liquid permittivity (meas.) ± 5.0 % Rectangular √ 3 0.6 0.49 ± 1.7 % ± 1.4 % ∞ Combined Uncertainty Expanded Std.		± 2.9 %	Normal	1	1	1	± 2.9 %	± 2.9 %	145
Phantom and Set-up Phantom uncertainty ± 4.0 % Rectangular √ 3 1 1 ± 2.3 % ± 2.3 % ∞ Liquid conductivity (target) ± 5.0 % Rectangular √ 3 0.64 0.43 ± 1.8 % ± 1.2 % ∞ Liquid conductivity (meas.) ± 5.0 % Rectangular √ 3 0.64 0.43 ± 1.8 % ± 1.2 % ∞ Liquid permittivity (target) ± 5.0 % Rectangular √ 3 0.6 0.49 ± 1.7 % ± 1.4 % ∞ Liquid permittivity (meas.) ± 5.0 % Rectangular √ 3 0.6 0.49 ± 1.7 % ± 1.4 % ∞ Combined Uncertainty ± 12.1 % ± 11.9 % 330 Expanded Std. + 24.3 % + 23.8 %	Device holder uncertainty	± 3.6 %			1	1	± 3.6 %	± 3.6 %	5
Phantom uncertainty ± 4.0 % Rectangular √ 3 1 1 ± 2.3 % ± 2.3 % ± 2.3 % ± 2.3 % ± 2.3 % ± 2.3 % ± 2.3 % ± 2.3 % ± 2.3 % ± 2.3 % ± 2.3 % ± 2.3 % ± 1.2 % ∞ Liquid conductivity (meas.) ± 5.0 % Rectangular √ 3 0.64 0.43 ± 1.8 % ± 1.2 % ∞ Liquid permittivity (target) ± 5.0 % Rectangular √ 3 0.6 0.49 ± 1.7 % ± 1.4 % ∞ Liquid permittivity (meas.) ± 5.0 % Rectangular √ 3 0.6 0.49 ± 1.7 % ± 1.4 % ∞ Combined Uncertainty ± 5.0 % <td>Power drift</td> <td>± 5.0 %</td> <td>Rectangular</td> <td>√ 3</td> <td>1</td> <td>1</td> <td>± 2.9 %</td> <td>± 2.9 %</td> <td>∞</td>	Power drift	± 5.0 %	Rectangular	√ 3	1	1	± 2.9 %	± 2.9 %	∞
Liquid conductivity (target) \pm 5.0 % Rectangular $\sqrt{3}$ 0.64 0.43 \pm 1.8 % \pm 1.2 % ∞ Liquid conductivity (meas.) \pm 5.0 % Rectangular $\sqrt{3}$ 0.64 0.43 \pm 1.8 % \pm 1.2 % ∞ Liquid permittivity (target) \pm 5.0 % Rectangular $\sqrt{3}$ 0.6 0.49 \pm 1.7 % \pm 1.4 % ∞ Liquid permittivity (meas.) \pm 5.0 % Rectangular $\sqrt{3}$ 0.6 0.49 \pm 1.7 % \pm 1.4 % ∞ Combined Uncertainty \pm 12.1 % \pm 11.9 % 330 Expanded Std.	Phantom and Set-up								
Liquid conductivity (meas.) \pm 5.0 % Rectangular $\sqrt{3}$ 0.64 0.43 \pm 1.8 % \pm 1.2 % ∞ Liquid permittivity (target) \pm 5.0 % Rectangular $\sqrt{3}$ 0.6 0.49 \pm 1.7 % \pm 1.4 % ∞ Liquid permittivity (meas.) \pm 5.0 % Rectangular $\sqrt{3}$ 0.6 0.49 \pm 1.7 % \pm 1.4 % ∞ Combined Uncertainty \pm 12.1 % \pm 11.9 % 330 Expanded Std.	Phantom uncertainty		Rectangular		•	1			∞
Liquid permittivity (target) ± 5.0 % Rectangular $\sqrt{3}$ 0.6 0.49 ± 1.7 % ± 1.4 % ∞ Liquid permittivity (meas.) ± 5.0 % Rectangular $\sqrt{3}$ 0.6 0.49 ± 1.7 % ± 1.4 % ∞ Combined Uncertainty ± 12.1 % ± 11.9 % 330 Expanded Std.	Liquid conductivity (target)		Rectangular		0.64	0.43	± 1.8 %		8
Liquid permittivity (meas.) \pm 5.0 % Rectangular $\sqrt{3}$ 0.6 0.49 \pm 1.7 % \pm 1.4 % ∞ Combined Uncertainty \pm 12.1 % \pm 11.9 % 330 Expanded Std.	Liquid conductivity (meas.)		Rectangular		0.64	0.43			∞
Combined Uncertainty ± 12.1 % ± 11.9 % 330 Expanded Std. + 24.3 % + 23.8 %			Rectangular		0.6	0.49			∞
Expanded Std. + 24 3 % + 23 8 %	Liquid permittivity (meas.)	± 5.0 %	Rectangular	√ 3	0.6	0.49		± 1.4 %	∞
• • • • • • • • • • • • • • • • • • • •	Combined Uncertainty						± 12.1 %	± 11.9 %	330
Uncertainty ± 24.3 % ± 23.6 %	Expanded Std.						± 2/1 2 0/	± 22 9 0/	
	Uncertainty						± 24.3 %	± 23.0 %	

Table 7: Measurement uncertainties

Worst-Case uncertainty budget for DASY5 valid for 3G communication signals and frequency range 3 - 6 GHz. Probe calibration error reflects uncertainty of the EX3D probe. For specific tests and configurations, the uncertainty could be considerable smaller.



		Relative DASY5 Uncertainty Budget for SAR Tests										
According to IEEE 1528/2013 and IEC62209-1/2011 (3-6GHz range)												
Frank Description	Un	certa	inty	Probability	Divisor	Ci	Ci	St	andard I	Unce	ertainty	v _i ² or
Error Description		Value	Э	Distribution		(1g)	(10g)	± 9	± %, (1g)		%, (10g)	V _{eff}
Measurement System												
Probe calibration	±	6.6	%	Normal	1	1	1	±	6.6 %	±	6.6 %	∞
Axial isotropy	±	4.7	%	Rectangular	√ 3	0.7	0.7	±	1.9 %	±	1.9 %	∞
Hemispherical isotropy	±	9.6	%	Rectangular	√ 3	0.7	0.7	±	3.9 %	±	3.9 %	8
Boundary effects	±	2.0	%	Rectangular	√ 3	1	1	±	1.2 %	±	1.2 %	∞
Probe linearity	±	4.7	%	Rectangular	√3	1	1	±	2.7 %	±	2.7 %	∞
System detection limits	±	1.0	%	Rectangular	√ 3	1	1	H	0.6 %	±	0.6 %	8
Modulation Response	±	2.4	%	Rectangular	√ 3	1	1	±	1.4 %	±	1.4 %	8
Readout electronics	±	0.3	%	Normal	1	1	1	±	0.3 %	±	0.3 %	8
Response time	±	8.0	%	Rectangular	√3	1	1	±	0.5 %	±	0.5 %	∞
Integration time	±	2.6	%	Rectangular	√ 3	1	1	±	1.5 %	±	1.5 %	8
RF ambient noise	±	3.0	%	Rectangular	√ 3	1	1	±	1.7 %	±	1.7 %	8
RF ambient reflections	±	3.0	%	Rectangular	√3	1	1	±	1.7 %	±	1.7 %	∞
Probe positioner	±	0.8	%	Rectangular	√3	1	1	±	0.5 %	±	0.5 %	
Probe positioning	±	6.7	%	Rectangular	√3	1	1	±	3.9 %	±	3.9 %	∞
Max. SAR evaluation	±	4.0	%	Rectangular	√3	1	1	±	2.3 %	±	2.3 %	∞
Test Sample Related												
Device positioning	±	2.9	%	Normal	1	1	1	±	2.9 %	±	2.9 %	
Device holder uncertainty	±	3.6	%	Normal	1	1	1	±	3.6 %	±	3.6 %	5
Power drift	±	5.0	%	Rectangular	√3	1	1	±	2.9 %	±	2.9 %	∞
Phantom and Set-up												
Phantom uncertainty	±	6.6	%	Rectangular	√3	1	1	±	3.8 %	±	3.8 %	
SAR correction	±	1.9	%	Rectangular	√3	1	0.84	±	1.1 %	±	0.9 %	
Liquid conductivity (meas.)	±	5.0	%	Rectangular	√3	0.78	0.71	±	2.3 %	±	2.0 %	∞
Liquid permittivity (meas.)	±	5.0	%	Rectangular	√3	0.26	0.26	±	0.8 %	±	0.8 %	8
Temp. Unc Conductivity	±	3.4	%	Rectangular	√3	0.78	0.71	±	1.5 %	±	1.4 %	
Temp. Unc Permittivity	±	0.4	%	Rectangular	√3	0.23	0.26	±	0.1 %	±	0.1 %	∞
Combined Uncertainty								±	12.4 %	±	12.4 %	330
Expanded Std.									24.9 %	_	24.8 %	
Uncertainty									24.3 /0		24.0 %	

Table 8: Measurement uncertainties

Worst-Case uncertainty budget for DASY5 assessed according to IEEE 1528/2013

and IEC 62209-1/2011 standards. The budget is valid for the frequency range 3GHz -6GHz and represents a worst-case analysis. For specific tests and configurations, the uncertainty could be considerable smaller.



6.1.9 Measurement uncertainty evaluation for System Check

Uncertainty of a System Performance Check with DASY5 System												
			for	the 0.3 - 3	GHz r	ange						
Source of	Und	certaii	ntv	Probability	Divisor	Ci	Ci	St	andard I	Unc	ertainty	v _i ² or
uncertainty		√alue	•	Distribution		(1g)	(10g)	± %, (1g)		± %, (10g)		v _{eff}
Measurement System												
Probe calibration	±	6.0	%	Normal	1	1	1	±	6.0 %	±	6.0 %	8
Axial isotropy	±	4.7	%	Rectangular	√ 3	0.7	0.7	±	1.9 %	±	1.9 %	∞
Hemispherical isotropy	±	0.0	%	Rectangular	√ 3	0.7	0.7	±	0.0 %	±	0.0 %	∞
Boundary effects	±	1.0	%	Rectangular	√3	1	1	±	0.6 %	±	0.6 %	∞
Probe linearity	±	4.7	%	Rectangular	√3	1	1	±	2.7 %	±	2.7 %	∞
System detection limits	±	1.0	%	Rectangular	√ 3	1	1	±	0.6 %	±	0.6 %	8
Readout electronics	±	0.3	%	Normal	1	1	1	±	0.3 %	±	0.3 %	8
Response time	±	0.0	%	Rectangular	√3	1	1	±	0.0 %	±	0.0 %	8
Integration time	±	0.0	%	Rectangular	√ 3	1	1	±	0.0 %	±	0.0 %	8
RF ambient conditions	±	3.0	%	Rectangular	√ 3	1	1	±	1.7 %	±	1.7 %	8
Probe positioner	±	0.4	%	Rectangular	√3	1	1	±	0.2 %	±	0.2 %	8
Probe positioning	±	2.9	%	Rectangular	√3	1	1	±	1.7 %	±	1.7 %	8
Max. SAR evaluation	±	1.0	%	Rectangular	√ 3	1	1	±	0.6 %	±	0.6 %	8
Test Sample Related												
Dev. of experimental dipole	±	0.0	%	Rectangular	√3	1	1	±	0.0 %	±	0.0 %	8
Source to liquid distance	±	2.0	%	Rectangular	√3	1	1	±	1.2 %	±	1.2 %	8
Power drift	±	3.4	%	Rectangular	√ 3	1	1	±	2.0 %	±	2.0 %	8
Phantom and Set-up												
Phantom uncertainty	±	4.0	%	Rectangular	√3	1	1	±	2.3 %	±	2.3 %	8
SAR correction	±	1.9	%	Rectangular	√3	1	0.84	±	1.1 %	±	0.9 %	∞
Liquid conductivity (meas.)	±	5.0	%	Normal	1	0.78	0.71	±	3.9 %	±	3.6 %	8
Liquid permittivity (meas.)	±	5.0	%	Normal	1	0.26	0.26	±	1.3 %	±	1.3 %	8
Temp. unc Conductivity	±	1.7	%	Rectangular	√3	0.78	0.71	±	0.8 %	±	0.7 %	∞
Temp. unc Permittivity	±	0.3	%	Rectangular	√3	0.23	0.26	±	0.0 %	±	0.0 %	∞
Combined Uncertainty								±	9.1 %	±	8.9 %	330
Expanded Std.									40.2.0/		47.0.0/	
Uncertainty								±	18.2 %	±	17.9 %	

Table 9: Measurement uncertainties of the System Check with DASY5 (0.3-3GHz)



Uncertainty (Uncertainty of a System Performance Check with DASY5 System											
Officertainty	oi a Oy		or the 3 - 6 (WILLI		0130	ySt	CIII		
Source of	Uncerta		Probability	Divisor	Ci	Ci	St	andard I	Jnce	ertainty	v _i ² or	
uncertainty	Value	•	Distribution		(1g)	(10g)	±'	%, (1g)	± %	6, (10g)	V _{eff}	
Measurement System					(0)	\ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \		, (0,		, (0,	en	
Probe calibration	± 6.6	%	Normal	1	1	1	±	6.6 %	±	6.6 %	∞	
Axial isotropy	± 4.7	%	Rectangular	√3	0.7	0.7	±	1.9 %		1.9 %	∞	
Hemispherical isotropy	± 0.0	%	Rectangular	√3	0.7	0.7	±	0.0 %		0.0 %	∞	
Boundary effects	± 1.0	%	Rectangular	√3	1	1	±	0.6 %		0.6 %	∞	
Probe linearity	± 4.7	%	Rectangular	√3	1	1	±	2.7 %		2.7 %	∞	
System detection limits	± 1.0	%	Rectangular	√3	1	1	±	0.6 %		0.6 %	∞	
Readout electronics	± 0.3	%	Normal	1	1	1	±	0.3 %		0.3 %	∞	
Response time	± 0.0	%	Rectangular	√3	1	1	±	0.0 %	±	0.0 %	∞	
Integration time	± 0.0	%	Rectangular	√3	1	1	±	0.0 %		0.0 %	∞	
RF ambient conditions	± 3.0	%	Rectangular	√3	1	1	±	1.7 %	±	1.7 %	∞	
Probe positioner	± 0.8	%	Rectangular	√3	1	1	±	0.5 %	±	0.5 %	∞	
Probe positioning	± 6.7	%	Rectangular	√3	1	1	±	3.9 %	±	3.9 %	∞	
Max. SAR evaluation	± 1.0	%	Rectangular	√3	1	1	±	0.6 %		0.6 %	∞	
Test Sample Related			J									
Dev. of experimental dipole	± 0.0	%	Rectangular	√3	1	1	±	0.0 %	±	0.0 %	∞	
Source to liquid distance	± 2.0	%	Rectangular	√3	1	1	±	1.2 %	±	1.2 %	∞	
Power drift	± 3.4	%	Rectangular	√3	1	1	±	2.0 %	±	2.0 %	∞	
Phantom and Set-up												
Phantom uncertainty	± 4.0	%	Rectangular	√3	1	1	±	2.3 %	±	2.3 %	8	
SAR correction	± 1.9	%	Rectangular	√3	1	0.84	±	1.1 %	±	0.9 %	8	
Liquid conductivity (meas.)	± 5.0	%	Normal	1	0.78	0.71	±	3.9 %	±	3.6 %	8	
Liquid permittivity (meas.)	± 5.0	%	Normal	1	0.26	0.26	±	1.3 %	±	1.3 %	8	
Temp. unc Conductivity	± 1.7	%	Rectangular	√3	0.78	0.71	±	0.8 %	±	0.7 %	∞	
Temp. unc Permittivity	± 0.3	%	Rectangular	√3	0.23	0.26	±	0.0 %	±	0.0 %	8	
Combined Uncertainty							±	10.1 %	± ´	10.0 %	330	
Expanded Std.								20.2 %		19.9 %		
Uncertainty Table 10: Measurement uncertainty								20.2 %	I	13.3 70		

Table 10: Measurement uncertainties of the System Check with DASY5 (3-6GHz)

Note: Worst case probe calibration uncertainty has been applied for all probes used during the measurements.



6.1.10 System check

The system check is performed for verifying the accuracy of the complete measurement system and performance of the software. The system check is performed with tissue equivalent material according to IEEE 1528. The following table shows system check results for all frequency bands and tissue liquids used during the tests (plot(s) see annex A).

		Syste	m performer	nce check (1000 mV	<i>I</i>)		
System validation Kit	Frequency	Target SAR _{1g} /mW/g (+/- 10%)	Target SAR _{10g} /mW/g (+/- 10%)	Measured SAR _{1g} / mW/g	SAR _{1g} dev.	Measured SAR _{10g} / mW/g	SAR _{10g} dev.	Measured date
D2450V2 S/N: 710	2450 MHz body	51.20	23.90	48.80	-4.5%	22.50	-7.0%	2017-03-16
D5GHzV2 S/N: 1055	5200 MHz body	74.20	20.80	72.70	-5.1%	20.50	-4.7%	2017-03-16
D5GHzV2 S/N: 1055	5500 MHz body	77.90	21.70	83.20	-0.7%	23.30	0.0%	2017-03-16
D5GHzV2 S/N: 1055	5800 MHz body	73.30	20.20	73.40	-8.6%	20.70	-6.8%	2017-03-16

Table 11: Results system check

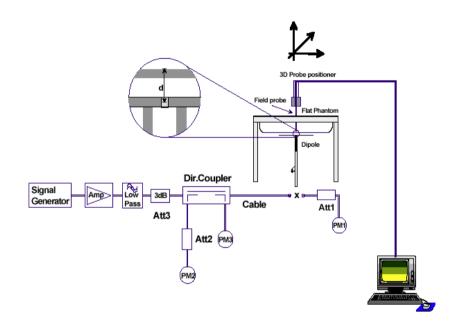


6.1.11 System check procedure

The system check is performed by using a validation dipole which is positioned parallel to the planar part of the SAM phantom at the reference point. The distance of the dipole to the SAM phantom is determined by a plexiglass spacer. The dipole is connected to the signal source consisting of signal generator and amplifier via a directional coupler, N-connector cable and adaption to SMA. It is fed with a power of 1000 mW for frequencies below 2 GHz or 100 mW for frequencies above 2 GHz. To adjust this power a power meter is used. The power sensor is connected to the cable before the system check to measure the power at this point and do adjustments at the signal generator. At the outputs of the directional coupler both return loss as well as forward power are controlled during the validation to make sure that emitted power at the dipole is kept constant. This can also be checked by the power drift measurement after the test (result on plot).

System check results have to be equal or near the values determined during dipole calibration (target SAR in table above) with the relevant liquids and test system.







6.1.12 System validation

The system validation is performed in a similar way as a system check. It needs to be performed once a SAR measurement system has been established and allows an evaluation of the system accuracy with all components used together with the specified system. It has to be repeated at least once a year or when new system components are used (DAE, probe, phantom, dipole, liquid type).

In addition to the procedure used during system check a system validation also includes checks of probe isotropy, probe modulation factor and RF signal.

The following table lists the system validations relevant for this test report:

Frequency (MHz)	DASY SW	Dipole Type /SN	Probe Type / SN	Calibrated signal type(s)	DAE unit Type / SN	body validation
2450	V52.8.7	D2450V2 / 710	EX3DV4 / 3944	CW	DAE3 / 413	2016-09-20
5200	V52.8.7	D5GHzV2 / 1055	EX3DV4 / 3944	CW	DAE3/ 477	2016-10-25
5500	V52.8.7	D5GHzV2 / 1055	EX3DV4 / 3944	CW	DAE3/ 477	2016-10-26
5800	V52.8.7	D5GHzV2 / 1055	EX3DV4 / 3944	CW	DAE3/ 477	2016-10-27



7 Detailed Test Results

7.1 Conducted power measurements

For the measurements the Rohde & Schwarz NRP Power Meter was used.

7.1.1 Conducted power measurements FHSS MSK 2450 MHz

FHSS MSK [MHz]	Data Rate (Kbps)	Channel no./ frequency [MHz]	Conducted avg. Power (dBm)	Conducted avg. Power (mW)
	50	0 / 2402.5	8.6	7.2
	50	34 / 2436.5	17.8	60.3
	50	69 / 2471.5	8.1	6.5
	100	0 / 2402.5	8.5	7.1
	100	34 / 2436.5	17.4	55.0
2402.5 -2471.5	100	69 / 2471.5	8.0	6.3
(70 Channels)	250	0 / 2402.5	8.6	7.2
	250	34 / 2436.5	17.6	57.5
	250	69 / 2471.5	8.0	6.3
	500	0 / 2402.5	8.6	7.2
	500	34 / 2436.5	17.7	58.9
	500	69 / 2471.5	8.0	6.3

7.1.2 Conducted power measurements FHSS MSK 5 GHz

Frequency	TX Port 3	TX Port 3	Antenna Gain	EIRP
(MHz)	(dBm)	(mW)	(dBi)	(dBm)
5190	11.35	13.6458	11.18	22.53
5230	12.04	15.9956	11.18	23.22
(MHz)	(dBm)	(mW)	(dBi)	(dBm)
5270	12.14	16.3682	11.18	23.32
5310	12.85	19.2752	11.18	24.03
Frequency	TX Port 3	TX Port 3	Antenna Gain	EIRP
(MHz)	(dBm)	(mW)	(dBi)	(dBm)
5510	10.35	10.8393	11.18	21.53
5550	10.40	10.9648	11.18	21.58
5590	10.40	10.9648	11.18	21.58
5630	10.40	10.9648	11.18	21.58
5670	10.70	11.7490	11.18	21.88
Frequency	TX Port 3	TX Port 3	Antenna Gain	EIRP
(MHz)	(dBm)	(mW)	(dBi)	(dBm)
5755	10.66	11.6413	11.18	21.84
5795	11.58	14.3880	11.18	22.76



7.2 SAR test results

7.2.1 General description of test procedures

- Test positions as described in the tables above are in accordance with the specified test standard.
- Tests in body position were performed in that configuration, which generates the highest time based averaged output power (see conducted power results).
- According to IEEE 1528 the SAR test shall be performed at middle channel. Testing of top and bottom channel is optional.
- According to KDB 447498 D01 testing of other required channels within the operating mode of a frequency band is not required when the reported 1-g or 10-g SAR for the mid-band or highest output power channel is:
 - ≤ 0.8 W/kg or 2.0 W/kg, for 1-g or 10-g respectively, when the transmission band is ≤ 100 MHz
 - ≤ 0.6 W/kg or 1.5 W/kg, for 1-g or 10-g respectively, when the transmission band is between 100 MHz and 200 MHz
 - ≤ 0.4 W/kg or 1.0 W/kg, for 1-g or 10-g respectively, when the transmission band is ≥ 200 MHz
- IEEE 1528-2013 requires the middle channel to be tested first. This generally applies to wireless devices that are designed to operate in technologies with tight tolerances for maximum output power variations across channels in the band. When the maximum output power variation across the required test channels is > ½ dB, instead of the middle channel, the highest output power channel must be used.



7.2.2 Results overview

	measured / extrapolated SAR numbers - Body worn - FSSH MSK 2450 MHz															
Freq. (MHz)	The Double (OBM)		SAR				SAR _{10g} (W/kg)		SAR _{10g} (W/kg)) SAR _{10g} (W/k		power drift	liquid (°C)	Ant.	Ant.
(IVIIIZ)		decl.**	meas.	meas.	extrap.	meas.	extrap.	(dB)	(C)	Orientation						
2436.5	bottom	19.8	17.8	0.021	0.034	0.012	0.018	0.09	23.2	28°	1					
2436.5	bottom	19.8	17.8	0.041	0.065	0.023	0.036	-0.07	23.2	touch	1					
2436.5	bottom	19.8	17.8	0.002	0.003	0.000	0.001	0.02	23.2	0°	1					
2436.5	bottom	19.8	17.8	0.052	0.082	0.030	0.048	-0.05	23.2	touch	2					
2402.5	bottom	10.6	8.6	0.000	0.000	0.000	0.000	N/A	23.2	touch	2					
2471.5	bottom	10.1	8.1	0.000	0.000	0.000	0.000	N/A	23.2	touch	2					

Table 12: Test results (see max. SAR plot on page 39/40 in Annex B - DAISY 5 measurement results.)

	measured / extrapolated SAR numbers - Body worn - FSSH MSK 5 GHz										
Freq. (MHz) Position	cond. P _{max} (dBm)		SAR _{1g} (W/kg)		SAR _{10g} (W/kg)		power	liquid	Ant.		
	declared**	meas.	meas.	extrap.	meas.	extrap.	drift (dB)	(°C)	Orientation		
5230.0	bottom	14.0	12.0	0.022	0.035	0.008	0.013	0.05	23.3	touch	
5310.0	bottom	14.9	12.9	0.023	0.036	0.007	0.011	-0.19	23.3	touch	
5670.0	bottom	14.0	12.0	0.000	0.000	0.000	0.000	N/A	23.3	touch	
5795.0	bottom	14.9	12.9	0.000	0.000	0.000	0.000	N/A	23.3	touch	

Table 13: Test results (see max. SAR plot on page 41 in Annex B - DAISY 5 measurement results.)

7.2.3 Multiple Transmitter Information

The following information which is relevant for the decision if a simultaneous transmit evaluation is necessary according to FCC KDB 447498D01 General RF Exposure Guidance v05.

Conservative Addition of all worst cases for SAR_(1g):

FSSH MSK (2450 ANT1 + 2450 ANT2 + 5000 ANT) = (0.065 + 0.082 + 0.036) W/kg = **0.183 W/kg**

Conclusion:

ΣSAR << 1.6 W/kg, no further investigation necessary



8 Test equipment and ancillaries used for tests

To simplify the identification of the test equipment and/or ancillaries which were used, the reporting of the relevant test cases only refer to the test item number as specified in the table below.

Equipment	Туре	Manufacturer	Serial No.	Last Calibration	Frequency (months)
Dosimetric E-Field Probe	EX3DV4	Schmid & Partner Engineering AG	3944	August 23, 2016	12
2450 MHz System Validation Dipole	D2450V2	Schmid & Partner Engineering AG	710	August 15, 2016	24
5 GHz System Validation Dipole	D5GHzV 2	Schmid & Partner Engineering AG	1055	August 14, 2015	24
Data acquisition electronics	DAE3V1	Schmid & Partner Engineering AG	477	May 11, 2016	12
Software	DASY52 52.8.7	Schmid & Partner Engineering AG		N/A	
Phantom ELI 4.0	QDOVA0 01BA	Schmid & Partner Engineering AG	1046	N/A	
Network Analyser 300 kHz to 6 GHz	8753ES	Hewlett Packard)*	US39174436	January 28, 2016	24
Dielectric Probe Kit	85070C	Hewlett Packard	US99360146	N/A	12
Signal Generator	8671B	Hewlett Packard	2823A00656	January 31, 2017	24
Amplifier	25S1G4 (25 Watt)	Amplifier Reasearch	20452	N/A	
Power Meter	NRP	Rohde & Schwarz	101367	January 31, 2017	24
Power Meter Sensor	NRP Z22	Rohde & Schwarz	100227	January 31, 2017	12
Power Meter Sensor	NRP Z22	Rohde & Schwarz	100234	January 31, 2017	12
Directional Coupler	778D	Hewlett Packard	19171	January 31, 2017	12

^{)*:} Network analyzer probe calibration against air, distilled water and a shorting block performed before measuring liquid parameters.

9 Observations

No observations exceeding those reported with the single test cases have been made.



Annex A: System performance check

Date/Time: 16.03.2017 11:27:06

SystemPerformanceCheck-D2450 MSL 2017-03-16

DUT: Dipole 2450 MHz; Type: D2450V2; Serial: 710

Communication System: UID 0, CW (0); Communication System Band: D2450 (2450.0 MHz); Frequency: 2450

MHz; Communication System PAR: 0 dB; PMF: 1

Medium parameters used: f = 2450 MHz; $\sigma = 2.002$ S/m; $\epsilon_r = 51.647$; $\rho = 1000$ kg/m³

Phantom section: Flat Section Measurement Standard: DASY5

DASY5 Configuration:

- Probe: EX3DV4 SN3944; ConvF(7.8, 7.8, 7.8); Calibrated: 23.08.2016;
- Sensor-Surface: 1.4mm (Mechanical Surface Detection), z = 1.0, 31.0
- Electronics: DAE3 Sn477; Calibrated: 11.05.2016
- Phantom: ELI 4.0; Type: QDOVA001BA; Serial: 1046
- DASY52 52.8.7(1137); SEMCAD X 14.6.10(7164)

MSL2450/d=10mm, Pin=100mW, dist=1.4mm/Area Scan (81x81x1): Interpolated

grid: dx=1.000 mm, dy=1.000 mm

Maximum value of SAR (interpolated) = 8.30 W/kg

MSL2450/d=10mm, Pin=100mW, dist=1.4mm/Zoom Scan (7x7x7)/Cube 0:

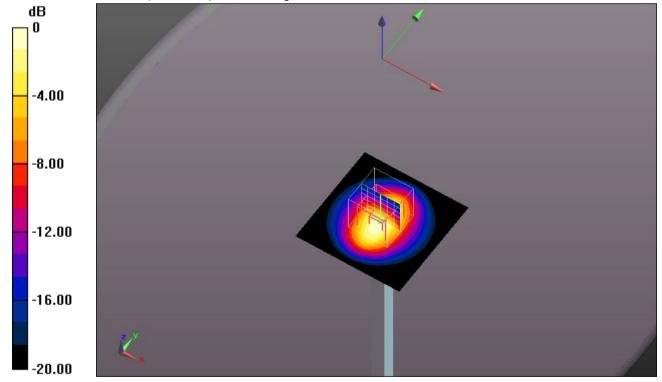
Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 66.625 V/m; Power Drift = -0.09 dB

Peak SAR (extrapolated) = 10.2 W/kg

SAR(1 g) = 4.88 W/kg; SAR(10 g) = 2.25 W/kg

Maximum value of SAR (measured) = 8.25 W/kg



0 dB = 8.25 W/kg = 9.16 dBW/kg

Additional information:

ambient temperature: 23.8°C; liquid temperature: 23.2°C



Date/Time: 16.03.2017 19:19:23

SystemPerformanceCheck-D5GHz MSL 2017-03-16

DUT: Dipole 5GHz; Type: D5GHzV2; Serial: 1055

Communication System: UID 0, CW (0); Communication System Band: D5GHz (5000.0 - 6000.0 MHz);

Frequency: 5200 MHz; Communication System PAR: 0 dB; PMF: 1

Medium parameters used: f = 5200 MHz; $\sigma = 5.411$ S/m; $\varepsilon_r = 48.029$; $\rho = 1000$ kg/m³

Phantom section: Flat Section Measurement Standard: DASY5

DASY5 Configuration:

- Probe: EX3DV4 SN3944; ConvF(4.85, 4.85, 4.85); Calibrated: 23.08.2016;
- Sensor-Surface: 1.4mm (Mechanical Surface Detection), z = 1.0, 23.0
- Electronics: DAE3 Sn477; Calibrated: 11.05.2016
- Phantom: ELI 4.0; Type: QDOVA001BA; Serial: 1046
- DASY52 52.8.7(1137); SEMCAD X 14.6.10(7164)

MSL 5GHz/d=10mm, Pin=100mW 5.2GHz/Area Scan (61x61x1): Interpolated grid:

dx=1.000 mm, dy=1.000 mm

Maximum value of SAR (interpolated) = 18.8 W/kg

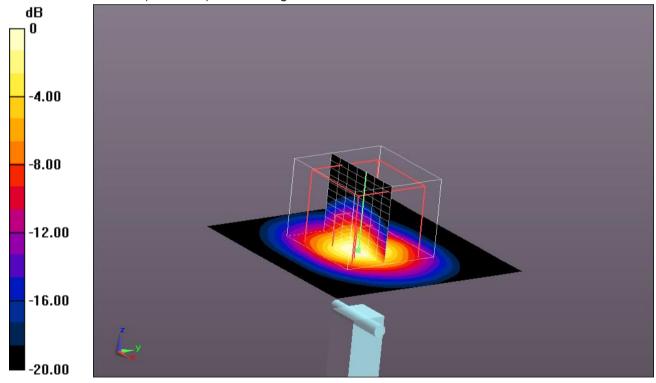
MSL 5GHz/d=10mm, Pin=100mW 5.2GHz/Zoom Scan (8x8x12)/Cube 0:

Measurement grid: dx=4mm, dy=4mm, dz=2mm

Reference Value = 65.420 V/m; Power Drift = -0.15 dB

Peak SAR (extrapolated) = 29.0 W/kg

SAR(1 g) = 7.27 W/kg; SAR(10 g) = 2.05 W/kg Maximum value of SAR (measured) = 17.7 W/kg



0 dB = 17.7 W/kg = 12.48 dBW/kg

Additional information:

ambient temperature: 23.8°C; liquid temperature: 23.3°C



Date/Time: 16.03.2017 19:44:41

SystemPerformanceCheck-D5GHz MSL 2017-03-16

DUT: Dipole 5GHz; Type: D5GHzV2; Serial: 1055

Communication System: UID 0, CW (0); Communication System Band: D5GHz (5000.0 - 6000.0 MHz);

Frequency: 5500 MHz; Communication System PAR: 0 dB; PMF: 1

Medium parameters used: f = 5500 MHz; $\sigma = 5.807$ S/m; $\varepsilon_r = 47.209$; $\rho = 1000$ kg/m³

Phantom section: Flat Section Measurement Standard: DASY5

DASY5 Configuration:

- Probe: EX3DV4 SN3944; ConvF(4.26, 4.26, 4.26); Calibrated: 23.08.2016;
- Sensor-Surface: 1.4mm (Mechanical Surface Detection (Locations From Previous Scan Used)), Sensor-Surface: 1.4mm (Mechanical Surface Detection), z = 1.0, 23.0
- Electronics: DAE3 Sn477; Calibrated: 11.05.2016
- Phantom: ELI 4.0; Type: QDOVA001BA; Serial: 1046
- DASY52 52.8.7(1137); SEMCAD X 14.6.10(7164)

MSL 5GHz/d=10mm, Pin=100mW 5.5GHz/Area Scan (61x61x1): Interpolated grid:

dx=1.000 mm, dy=1.000 mm

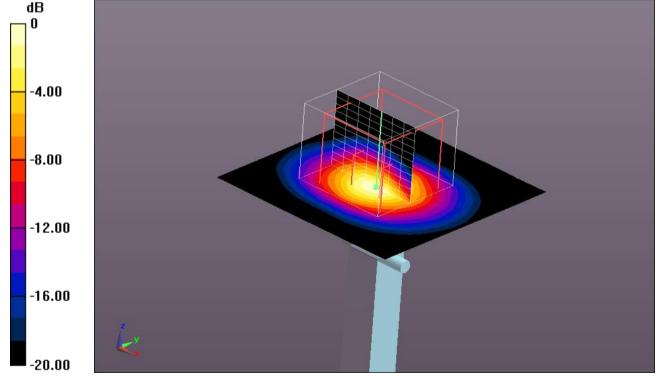
Maximum value of SAR (interpolated) = 19.5 W/kg

MSL 5GHz/d=10mm, Pin=100mW 5.5GHz/Zoom Scan (8x8x12)/Cube 0:

Measurement grid: dx=4mm, dy=4mm, dz=2mmReference Value = 65.247 V/m; Power Drift = 0.13 dB

Peak SAR (extrapolated) = 35.8 W/kg

SAR(1 g) = 8.32 W/kg; SAR(10 g) = 2.33 W/kg Maximum value of SAR (measured) = 21.6 W/kg



0 dB = 21.6 W/kg = 13.34 dBW/kg

Additional information:

ambient temperature: 23.8°C; liquid temperature: 23.3°C



Date/Time: 16.03.2017 20:28:50

SystemPerformanceCheck-D5GHz MSL 2017-03-16

DUT: Dipole 5GHz; Type: D5GHzV2; Serial: 1055

Communication System: UID 0, CW (0); Communication System Band: D5GHz (5000.0 - 6000.0 MHz);

Frequency: 5800 MHz; Communication System PAR: 0 dB; PMF: 1

Medium parameters used: f = 5800 MHz; $\sigma = 6.119$ S/m; $\varepsilon_r = 46.863$; $\rho = 1000$ kg/m³

Phantom section: Flat Section Measurement Standard: DASY5

DASY5 Configuration:

- Probe: EX3DV4 SN3944; ConvF(4.13, 4.13, 4.13); Calibrated: 23.08.2016;
- Sensor-Surface: 1.4mm (Mechanical Surface Detection (Locations From Previous Scan Used)), Sensor-Surface: 1.4mm (Mechanical Surface Detection), z = 1.0, 23.0
- Electronics: DAE3 Sn477; Calibrated: 11.05.2016
- Phantom: ELI 4.0; Type: QDOVA001BA; Serial: 1046
- DASY52 52.8.7(1137); SEMCAD X 14.6.10(7164)

MSL 5GHz/d=10mm, Pin=100mW 5.8GHz/Area Scan (61x61x1): Interpolated grid:

dx=1.000 mm, dy=1.000 mm

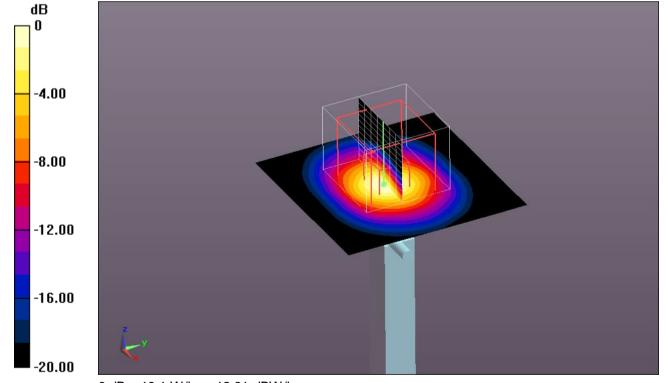
Maximum value of SAR (interpolated) = 18.9 W/kg

MSL 5GHz/d=10mm, Pin=100mW 5.8GHz/Zoom Scan (8x8x12)/Cube 0:

Measurement grid: dx=4mm, dy=4mm, dz=2mmReference Value = 63.518 V/m; Power Drift = 0.08 dB

Peak SAR (extrapolated) = 32.2 W/kg

SAR(1 g) = 7.34 W/kg; SAR(10 g) = 2.07 W/kg Maximum value of SAR (measured) = 19.1 W/kg



0 dB = 19.1 W/kg = 12.81 dBW/kg

Additional information:

ambient temperature: 23.8°C; liquid temperature: 23.3°C



Annex B: DASY5 measurement results

SAR plots for **the highest measured SAR** in each exposure configuration, wireless mode and frequency band combination according to FCC KDB 865664 D02

Annex B.1: FSSH MSK 2450 MHz

Date/Time: 16.03.2017 13:13:29

FCC_EN62209-2 2.4GHz

DUT: Intel; Type: Cockpit; Serial: 603

Communication System: UID 0, FHSS (MSK) 2.4(0); Communication System Band: 2.4 GHz; Frequency:

2436.5 MHz; Communication System PAR: 0 dB; PMF: 1

Medium parameters used (interpolated): f = 2436.5 MHz; $\sigma = 1.981$ S/m; $\epsilon_r = 51.632$; $\rho = 1000$ kg/m³

Phantom section: Flat Section Measurement Standard: DASY5

DASY5 Configuration:

- Probe: EX3DV4 - SN3944; ConvF(7.8, 7.8, 7.8); Calibrated: 23.08.2016;

- Sensor-Surface: 1.4mm (Mechanical Surface Detection (Locations From Previous Scan Used)), Sensor-Surface: 1.4mm (Mechanical Surface Detection), z = 1.0, 31.0

- Electronics: DAE3 Sn477; Calibrated: 11.05.2016

- Phantom: ELI 4.0; Type: QDOVA001BA; Serial: 1046

- DASY52 52.8.7(1137); SEMCAD X 14.6.10(7164)

MSL2450/Bottom Middle Antenna 1 touch/Area Scan (201x261x1): Interpolated

grid: dx=1.500 mm, dy=1.500 mm

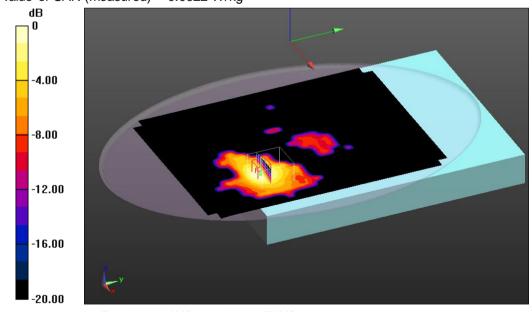
Maximum value of SAR (interpolated) = 0.0629 W/kg

MSL2450/Bottom Middle Antenna 1 touch/Zoom Scan (8x8x7)/Cube 0:

Measurement grid: dx=7.5mm, dy=7.5mm, dz=5mm Reference Value = 5.789 V/m; Power Drift = -0.07 dB

Peak SAR (extrapolated) = 0.0760 W/kg

SAR(1 g) = 0.041 W/kg; SAR(10 g) = 0.023 W/kg Maximum value of SAR (measured) = 0.0622 W/kg



0 dB = 0.0622 W/kg = -12.06 dBW/kg

Additional information:

position or distance of DUT to SAM: 0 mm

ambient temperature: 23.8°C; liquid temperature: 23.2°C



Date/Time: 16.03.2017 14:24:40

FCC_EN62209-2 2.4GHz

DUT: Intel; Type: Cockpit; Serial: 603

Communication System: UID 0, FHSS (MSK) 2.4(0); Communication System Band: 2.4 GHz; Frequency:

2436.5 MHz; Communication System PAR: 0 dB; PMF: 1

Medium parameters used (interpolated): f = 2436.5 MHz; $\sigma = 1.981 \text{ S/m}$; $\epsilon_r = 51.632$; $\rho = 1000 \text{ kg/m}^3$

Phantom section: Flat Section Measurement Standard: DASY5

DASY5 Configuration:

- Probe: EX3DV4 SN3944; ConvF(7.8, 7.8, 7.8); Calibrated: 23.08.2016;
- Sensor-Surface: 1.4mm (Mechanical Surface Detection (Locations From Previous Scan Used)), Sensor-Surface: 1.4mm (Mechanical Surface Detection), z = 1.0, 26.0
- Electronics: DAE3 Sn477; Calibrated: 11.05.2016
- Phantom: ELI 4.0; Type: QDOVA001BA; Serial: 1046
- DASY52 52.8.7(1137); SEMCAD X 14.6.10(7164)

MSL2450/Bottom Middle Antenna 2 touch/Area Scan (201x261x1): Interpolated

grid: dx=1.500 mm, dy=1.500 mm

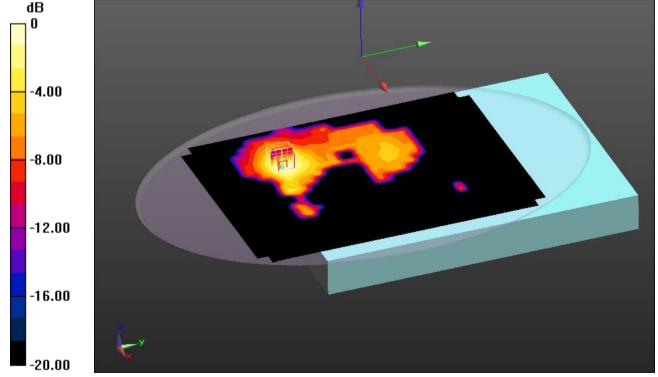
Maximum value of SAR (interpolated) = 0.0778 W/kg

MSL2450/Bottom Middle Antenna 2 touch/Zoom Scan (5x5x7)/Cube 0:

Measurement grid: dx=7.5mm, dy=7.5mm, dz=5mmReference Value = 6.150 V/m; Power Drift = -0.05 dB

Peak SAR (extrapolated) = 0.0920 W/kg

SAR(1 g) = 0.052 W/kg; SAR(10 g) = 0.030 W/kg Maximum value of SAR (measured) = 0.0768 W/kg



0 dB = 0.0768 W/kg = -11.15 dBW/kg

Additional information:

position or distance of DUT to SAM: 0 mm

ambient temperature: 23.8°C; liquid temperature: 23.2°C



Annex B.2: FSSH MSK 5 GHz

Date/Time: 16.03.2017 16:12:14

FCC EN62209-2 5GHz

DUT: Intel; Type: Cockpit; Serial: 603

Communication System: UID 0, 5GHz (0); Communication System Band: 5 GHz Band; Frequency: 5230 MHz;

Communication System PAR: 0 dB; PMF: 1

Medium parameters used: f = 5230 MHz; $\sigma = 5.426$ S/m; $\varepsilon_r = 47.821$; $\rho = 1000$ kg/m³

Phantom section: Flat Section Measurement Standard: DASY5

DASY5 Configuration:

- Probe: EX3DV4 - SN3944; ConvF(4.85, 4.85, 4.85); Calibrated: 23.08.2016;

- Sensor-Surface: 1.4mm (Mechanical Surface Detection), Sensor-Surface: 2mm (Mechanical Surface

Detection), z = 1.0, 23.0

- Electronics: DAE3 Sn477; Calibrated: 11.05.2016

- Phantom: ELI 4.0; Type: QDOVA001BA; Serial: 1046

- DASY52 52.8.7(1137); SEMCAD X 14.6.10(7164)

MSL5000/Bottom Ch 5230 Antenna touch/Area Scan (161x201x1): Interpolated grid:

dx=1.500 mm, dy=1.500 mm

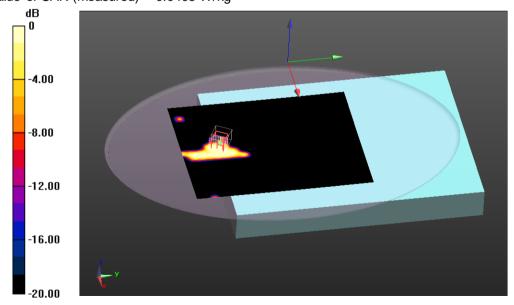
Maximum value of SAR (interpolated) = 0.0908 W/kg

MSL5000/Bottom Ch 5230 Antenna touch/Zoom Scan (8x10x12)/Cube 0:

Measurement grid: dx=4mm, dy=4mm, dz=2mm Reference Value = 2.631 V/m; Power Drift = 0.05 dB

Peak SAR (extrapolated) = 0.198 W/kg

SAR(1 g) = 0.022 W/kg; SAR(10 g) = 0.0081 W/kg Maximum value of SAR (measured) = 0.0405 W/kg



0 dB = 0.0405 W/kg = -13.93 dBW/kg

Additional information:

position or distance of DUT to SAM: 0 mm

ambient temperature: 23.9°C; liquid temperature: 23.3°C



Date/Time: 16.03.2017 17:12:19

FCC_EN62209-2 5GHz

DUT: Intel; Type: Cockpit; Serial: 603

Communication System: UID 0, 5GHz (0); Communication System Band: 5 GHz Band; Frequency: 5310 MHz;

Communication System PAR: 0 dB; PMF: 1

Medium parameters used: f = 5310 MHz; $\sigma = 5.583$ S/m; $\varepsilon_r = 47.769$; $\rho = 1000$ kg/m³

Phantom section: Flat Section Measurement Standard: DASY5

DASY5 Configuration:

- Probe: EX3DV4 SN3944; ConvF(4.48, 4.48, 4.48); Calibrated: 23.08.2016;
- Sensor-Surface: 1.4mm (Mechanical Surface Detection (Locations From Previous Scan Used)), Sensor-Surface: 2mm (Mechanical Surface Detection), z = 1.0, 23.0
- Electronics: DAE3 Sn477; Calibrated: 11.05.2016
- Phantom: ELI 4.0; Type: QDOVA001BA; Serial: 1046
- DASY52 52.8.7(1137); SEMCAD X 14.6.10(7164)

MSL5000/Bottom 5310 Antenna touch/Area Scan (161x201x1): Interpolated grid:

dx=1.500 mm, dy=1.500 mm

Maximum value of SAR (interpolated) = 0.0420 W/kg

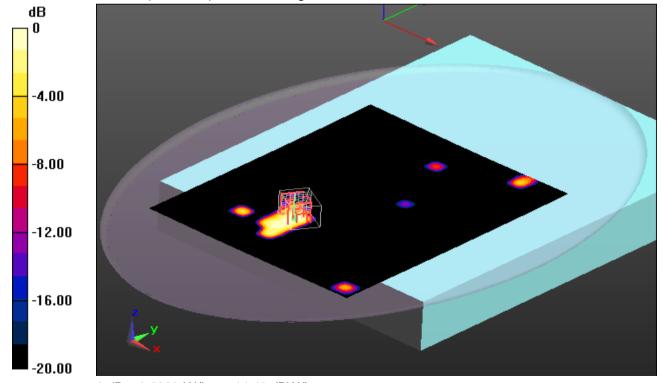
MSL5000/Bottom 5310 Antenna touch/Zoom Scan (8x10x12)/Cube 0:

Measurement grid: dx=4mm, dy=4mm, dz=2mm

Reference Value = 2.760 V/m; Power Drift = -0.19 dB

Peak SAR (extrapolated) = 0.281 W/kg

SAR(1 g) = 0.023 W/kg; SAR(10 g) = 0.00677 W/kg Maximum value of SAR (measured) = 0.0363 W/kg



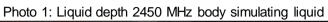
0 dB = 0.0363 W/kg = -14.40 dBW/kg

Additional information:

position or distance of DUT to SAM: 0 mm

ambient temperature: 23.9°C; liquid temperature: 23.3°C

Annex B.3: Liquid depth



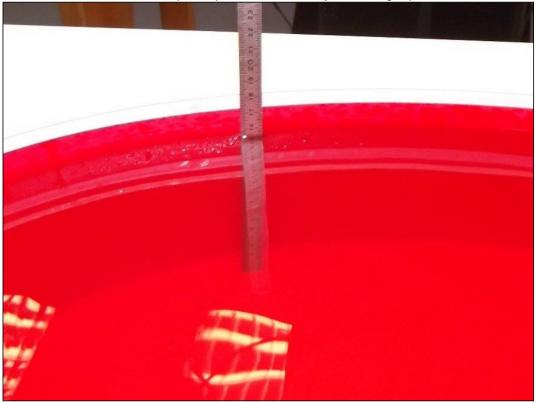


Photo 2: Liquid depth 5 GHz body simulating liquid





Annex C: Photo documentation

Photo documentation is described in the additional document:

Appendix to test report no. 1-2536/16-02-02 Photo documentation

Annex D: Calibration parameters

Calibration parameters are described in the additional document:

Appendix to test report no. 1-2536/16-02-02 Calibration data, Phantom certificate and detail information of the DASY5 System



Annex E: RF Technical Brief Cover Sheet acc. to RSS-102 Annex A

1. COMPANY NUMBER: 1000B	
2. PRODUCT MARKETING NAME (PM	/IN): RCM24G + VLMRX58G
3. HARDWARE VERSION IDENTIFICA	ATION NO. (HVIN): D + AMN-PCB_183 REV 2.0
4. FIRMWARE VERSION IDENTIFICATION	TION NO. (FVIN): RCM24G_12017USCN + 4.2.2
5. HOST MARKETING NAME (HMN): I	Intel Cockpit Ground Control Station
6. IC CERTIFICATION NUMBER: 1000	DB-RCM24G + 1000B-VLMRX58G
7. APPLICANT: Intel Canada Ltd.	
8. SAR/RF EXPOSURE TEST LABOR/	ATORY: CTC advanced GmbH
9. TYPE OF EVALUATION:	
(a) SAR Evaluation: Device not Used	in the Vicinity of the Human Head.
(b) SAR Evaluation: Body-Worn Devi ● Multiple transmitters: Yes ⊠ No □	ce
 Evaluated against exposure limits: G Duty cycle used in evaluation: 100 % Standard used for evaluation: listed i 	
• SAR value: 0.082 W/kg.	Measured $oxed{\boxtimes}$ Computed $oxed{\square}$ Calculated $oxed{\square}$
(c) SAR Evaluation: Limb-Worn Devic • Multiple transmitters: Yes ⊠ No □	e
 Evaluated against exposure limits: G Duty cycle used in evaluation: 100 % Standard used for evaluation: listed i 	
• SAR value: 0.048 W/kg .	Measured $oxtimes$ Computed $oxtimes$ Calculated $oxtimes$



Annex E.1: Declaration of RF Exposure Compliance Annex B

ATTESTATION: I attest that the information provided in Annex E: is correct; that a Technical Brief was prepared and the information it contains is correct; that the device evaluation was performed or supervised by me; that applicable measurement methods and evaluation methodologies have been followed and that the device meets the SAR and/or RF exposure limits of RSS-102.

Signature: p.o.

NAME: Alexander Hnatovskiy

TITLE: Dipl.-Ing. (FH)

COMPANY: CTC advanced GmbH

PRODUCT MARKETING NAME (PMN): RCM24G + VLMRX58G

HARDWARE VERSION IDENTIFICATION NO. (HVIN): D + AMN-PCB_183 REV 2.0

FIRMWARE VERSION IDENTIFICATION NO. (FVIN): RCM24G_12017USCN + 4.2.2

HOST MARKETING NAME (HMN): Intel Cockpit Ground Control Station

IC CERTIFICATION NUMBER: 1000B-RCM24G + 1000B-VLMRX58G

Test Standard	Version	Description
IEEE 1528-2013	2014-06	Recommended Practice for Determining the Peak Spatial-Average Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques
RSS-102 Issue 5	2015-04	Radio Frequency Exposure Compliance of Radio communication Apparatus (All Frequency Bands)
Canada's Safety Code No. 6	2015-03	Limits of Human Exposure to Radiofrequency Electromagnetic Fields in the Frequency Range from 3 kHz to 300 GHz
IEEE Std. C95-3	2002	IEEE Recommended Practice for the Measurement of Potentially Hazardous Electromagnetic Fields – RF and Microwave
IEEE Std. C95-1	2005	IEEE Standard for Safety Levels with Respect to Human Exposure to Radio Frequency Electromagnetic Fields, 3 kHz to 300 GHz.
IEC 62209-2	2010	Human exposure to radio frequency fields from hand-held and body mounted wireless communication devices. Human models, instrumentation, and procedures. Procedure to determine the specific absorption rate (SAR) for wireless communication devices used in close proximity to the human body (frequency range of 30 MHz to 6 GHz)
FCC KDBs		
KDB 865664D01v01r03	2014-02-07	FCC OET SAR measurement requirements 100 MHz to 6 GHz
KDB 447498D01v05r02	2014-02-07	Mobile and Portable Devices RF Exposure Procedures and Equipment Authorization Policies
KDB 248227D01v02r01	2015-05-28	SAR Measurement Procedures for 802.11 a/b/g Transmitters



Annex F: Document History

Version	Applied Changes	Date of Release
	Initial Release	2017-03-17

Annex G: Further Information

Glossary

DTS - Distributed Transmission System

DUT - Device under Test EUT - Equipment under Test

FCC - Federal Communication Commission

FCC ID - Company Identifier at FCC

HW - Hardware IC - Industry Ca

IC - Industry Canada Inv. No. - Inventory number N/A - not applicable

PCE - Personal Consumption Expenditure
OET - Office of Engineering and Technology

SAR - Specific Absorption Rate

S/N - Serial Number SW - Software

UNII - Unlicensed National Information Infrastructure